

# Series 988

# User's Manual

Includes 986, 987, 988 and 989









### 1/8 DIN Microprocessor-Based Temperature/Process Controller

### **User Levels:**

- New User..... go to Introduction • Experienced User...... go to page 4.1
- Installers:
- Set-up...... go to page 1.1
- Wiring & Installation..... go to page 2.1

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# Series 988

# User's Manual

Includes 986, 987, 988 and 989

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# Introduction to the Watlow Series 988 Controllers









Figure Int.1 -The Series 988 Controllers.

Watlow's Series 988 controllers set a new standard in the controller industry by packing an impressive array of features into an 1/8-DIN package. No other controller offers the flexibility, compact size and durability of the Series 988. It can control a wide variety of temperature and process applications, with a broad range of input and output options that allow control of virtually any process variable.

The Series 988 is the only 1/8 DIN controller that can provide single-unit cascade control of a process. Its other features include heater current monitoring, remote set point input, ratio control and valve control through slidewire feedback. The Series 988 also delivers expanded auto-tuning capabilities, increased alarm functionality and several unique control algorithms.

When we refer to the "Series 988" controller, we refer also to the horizontal and low-voltage versions of the Series 988: the 986, 987, 988 and 989. We recommend that you read all of this manual's introduction to familiarize yourself with the conventions and content of this manual and the steps to setting up a Series 988 controller. Make sure you understand the "Caution" and "Warning" symbols we use in the book.

### **Using this Manual**

This manual provides the information you will need to install and operate a Series 988 controller.

If you need information about Series 988 configurations and model numbers, refer to the Appendix of this manual or, for more detailed information, to *Optimizing Your Process System with the Series 988 Controller: An Application Guide for the Watlow Series 988 Family.* 

If your Series 988 controller will be used for data communications, you will also need our communications manual, *Data Communications with the Watlow Series 988 Family of Controllers* (green cover).

Series 988 controllers are calibrated in the factory, but if you need to do periodic calibration you will need our calibration manual, *Calibrating Watlow Process Controllers*, (blue cover).

This manual explains the five steps of setting up a Series 988 controller:

- 1. Set and document all of the DIP switches, if applicable: Chapter 1.
- 2. Mount the controller: Chapter 2.
- 3. Wire and document the controller wiring: Chapter 2.
- 4. Configure and document the controller software: Chapters 3-6.
- 5. Run, test and adjust your application. Update documentation.

<u>Chapters 7</u> and <u>8</u> and the <u>Appendix</u> provide detailed advice, definitions and specifications along with application examples to help you optimize the safety and performance of your application. Use the <u>Table of Contents</u> and <u>Index</u> to find specific information.

# The Menu Overview in the Appendix shows all the

shows all the menus and prompts.

NOTE:

board.

NOTE:

The 12-digit number

is printed on the top of the stickers on each side of the

controller's case and on the right-

hand or top circuit

### **Document Every Step**

The Series 988 provides powerful and complex features. Carefully document each step of the setup and any subsequent changes. This will make it much easier to change, adjust and troubleshoot your application.

Make the configuration documentation available to engineers and technicians, on all shifts, who may need to work with the Series 988. We provide space in this manual to record configurations. You may prefer to photocopy the blank forms and keep them in a separate binder. However you maintain your documentation, be sure to replace all old copies of the documentation with updated versions whenever the controller configuration is changed.

### **Notes, Cautions and Warnings**

We use note, caution and warning symbols throughout this book to draw your attention to important operational and safety information.

A bold text "**NOTE**" marks a short message in the margin to alert you to an important detail.

A bold text "CAUTION" safety alert appears with information that is important for protecting your equipment and performance. Be especially careful to read and follow all cautions that apply to your application.

A bold text "WARNING" safety alert appears with information that is important for protecting you, others and equipment from damage. Pay very close attention to all warnings that apply to your application.

The  $\underline{\wedge}$  symbol (an exclamation point in a triangle) precedes a general CAUTION or WARNING statement.

The  $\triangle$  symbol (a lightning bolt in a triangle) precedes an electric shock hazard CAUTION or WARNING safety statement.

### **Technical Assistance**

If you encounter a problem with your Watlow controller, review all of your configuration information for each step of the setup to verify that your selections are consistent with your applications.

If the problem persists after checking all the steps, you can get technical assistance by calling Watlow Controls at (507) 454-5300, between 7 a.m. and 5 p.m. CST, and asking for an applications engineer. When you call have the following information on hand: the controller's model number (the 12-digit number is printed on the top of the stickers on each side of the controller's case and on the right-hand or top circuit board); your user's manual; all configuration information; and the Diagnostics Menu readings.

### We Value Your Feedback

Your comments and suggestions on this manual are welcome. Please send them to, Technical Writer, Watlow Controls, 1241 Bundy Blvd., P.O. Box 5580, Winona, MN 55987-5580 or call (507) 454-5300 or fax (507) 452-4507.(1233)

# **Chapter 1** Hardware Setup

### **DIP Switch Locations and Functions**

The Watlow Series 988 has at least one and as many as six dual in-line package (DIP) switches inside the controller, depending on the model number. They allow users to configure the controller for a variety of input sensors, to provide power for external signal conditioners or to lockout front panel access to some functions.

### To set any DIP switch:

- Remove the controller from the case by pressing firmly on the two release tabs on one side or the top of the bezel until they unsnap. Then firmly press the two release tabs on the opposite side or the bottom of the control until they unsnap. You will need to gently rock the bezel back and forth to release it from the chassis.
- Use the illustrations on the following pages to locate and set each DIP switch.

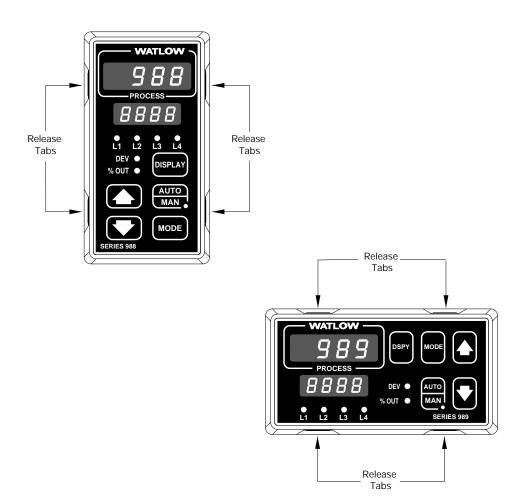
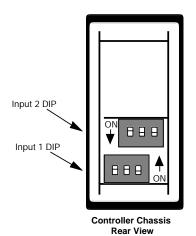


Figure 1.1 - Press the release tabs to remove the controller chassis.

# **DIP Switches**

1. Set the input DIP switches to match the sensors you are using in your application. Only controllers with model number 98\_\_-2\_\_- or 98\_\_-2\_\_- have an input DIP switch.



NOTE: The Input 2 DIP switch is mounted upside down.

Input 1 Input 2 (98 \_ -2 \_ - \_ \_ )(98 \_ -2 \_ - \_ \_ )

NOTE: Only controllers with the indicated model numbers have these DIP switches.

RTD (100  $\Omega$ )



these DIP nes.

thermocouple: R, S or B



thermocouple: J, K, T, N, E, C, D, Pt2 or 0-50mV (high impedance)



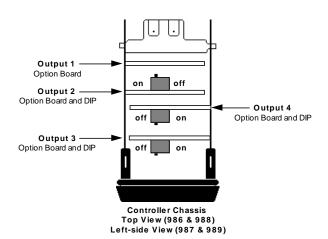
Figure 1.2 - Input DIP switches.

0-20 or 4-20mA; 0-5, 1-5 or 0-10V





# **DIP Switches**



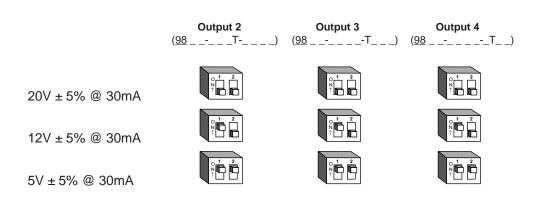
NOTE:

For other voltages or current settings contact the factory.

NOTE:

Only controllers with the indicated model numbers have these DIP switches.

Figure 1.3 -External signal conditioner power supply DIPs.



3. When the DIP switches are set, gently insert the controller chassis into the case and push it firmly into place until all four tabs snap into place.

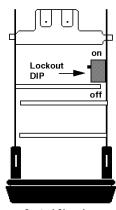
## **DIP Switches**



error.

**CAUTION:** The lockout DIP switch makes the **Setup and Factory** menus unavailable. Configure all the **Setup and Factory** menus before locking them out. Failure to do so could result in damage to equipment in the event of a setup

4. The lockout DIP switch hides the Setup Menus (Input, Output, Global and Communications) and the Factory Menus (Panel Lockout, Diagnostics and Calibration). All units have a lockout DIP switch.



**Control Chassis** Top View (986 & 988) Left-side View (987 & 989)

no hardware lockout (Switch 1 has no effect.)

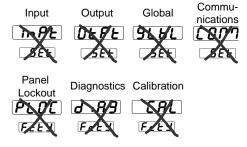






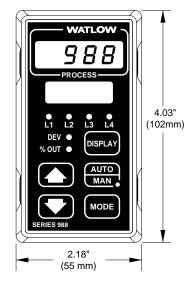


Figure 1.4 -Lockout DIP switch. lockout Setup and Factory menus (Switch 1 has no effect.)



# Chapter 2 Installation and Wiring

NOTE: Space panel cutouts at least 1.66 inches (42.2mm) apart.

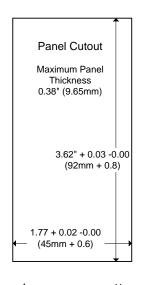


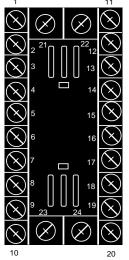


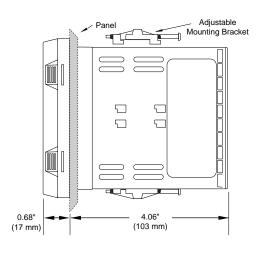
NOTE: Adjustable mounting brackets can be side-mounted.

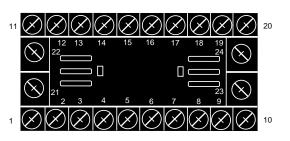
NOTE: Holes can be cut in the panel using a Greenlee 1/8 DIN Hydraulic Kit #60068 (punch #60069, die #60070).

Figure 2.1 -Series 988 and Series 989 dimensions and terminal number layout.







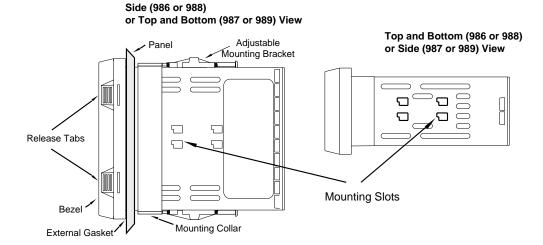


### **Installing the Series 988**

Installing and mounting requires access to the back of the panel.

- 1. Make a panel cutout using the panel cutout dimensions from the previous page.
- To remove the controller chassis from its case, press in firmly on the two tabs on one side or the top of the bezel until they unsnap, then unsnap the two tabs on the opposite side or the bottom. Pull the chassis out of the case by gently rocking it.
- NOTE: Removing the controller chassis from its case makes mounting easier.
- 3. Slide the case into the panel cutout. Check to see that the gasket is not twisted, and is seated within the case bezel flush with the panel. Slide

Figure 2.2 - Side and top view.



the mounting collar over the back of the control.

- 4. Loosen the mounting bracket screws enough to allow for the mounting collar and panel thickness. Place each mounting bracket into the mounting slots (head of the screw facing the back of the controller). Push each bracket backward then down to secure it to the control case. To guarantee a proper NEMA 4X seal, Series 986 and 988 units (vertical) must have the mounting brackets located on either side of the unit. When installing Series 987 and 989 units (horizontal) the brackets must be on the top and bottom of the unit.
- 5. Make sure the case is seated properly. Tighten the installation screws firmly against the mounting collar to secure the unit. To ensure a NEMA 4X seal, there should be no space between the bezel and panel. Overtightening the screws will distort the case and make it difficult to remove or replace the controller.
- 6. Make sure the inside gasket is seated properly and not twisted. Insert the controller chassis into its case and press the bezel until all four tabs snap.
- 7. To release the mounting brackets, loosen the mounting bracket screws and push the brackets forward, then pull it up and out.



CAUTION:
Follow the installation procedure
exactly to guarantee a proper NEMA 4X seal. Make sure the gasket between the panel and the rim of the case is not twisted and is seated properly. Failure to do so could result in damage to equipment.

### Wiring



WARNING:
To avoid potential electric shock, use National Electric Code (NEC) safety practices when wiring and connecting this unit to a power source and to electrical sensors or peripheral

devices. Failure to

do so could result

in injury or death.

### NOTE:

Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

Figure 2.4 - Power wiring.

### Wiring the Series 988

Wiring options depend on the model number and DIP switch settings. Check the terminal designation stickers on either side of the controller and compare your model number to those shown here and with the model number breakdown on the inside back cover of this manual.

### Input-to-output Isolation

The Series 988 uses optical isolation between the analog inputs and the controller outputs/digital input. This isolation provides a  $500V\sim$  (ac) barrier to prevent ground loops when using grounded sensors and/or peripheral equipment.

Here is a breakdown of the isolation barriers:

- Analog inputs 1 and 2 are grouped together.
- Outputs 1 through 4 and the standard event input are grouped together. This does not apply to Output 4 when configured as communications.
- The digital communications output (4) is separate from the above groups.

### **Power Wiring**

**100 to 240V (ac/dc) nominal**, (85 to 264 actual)

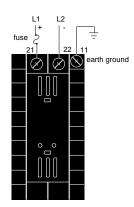
 Vertical Package
 98 8 - - \_ - \_ - \_ \_

 Horizontal Package
 98 9 - - \_ - - \_ - \_ \_

24 to 28 V≂ (ac/dc) nominal, (20 to 30 actual)

 Vertical Package
 98 6 -- \_\_\_\_\_

 Horizontal Package
 98 7 -- \_\_\_\_\_



### **Sensor Installation Guidelines**



CAUTION:

The Series 988 will not function with two grounded thermocouple inputs. Avoid using a grounded thermocouple for both input 1 and input 2. Failure to follow this guideline could result in damage to equipment.

### NOTE:

Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2. Maintain isolation between input 1 and input 2 to prevent a ground loop. A ground loop may cause incorrect readings, dashes across the upper display or the display of error codes.

**Thermocouple input:** Extension wire for thermocouples must be of the same alloy as the thermocouple itself to limit errors.

Using grounded thermocouples for both input 1 and input 2 may create ground loop problems. To correct this problem, replace at least one of the grounded thermocouples with an ungrounded thermocouple. If the application requires grounded thermocouples, use an isolated transmitter, such as a Watlow Gordon 5702 isolated transmitter.

**RTD** (100  $\Omega$ ) input: Each  $1\Omega$  of lead wire resistance can cause a  $+2^{\circ}$ C error when using a two-wire RTD. A three-wire RTD sensor overcomes this problem. All three wires must have the same electrical resistance (i.e., same gauge, same length, multi-stranded or solid, same metal).

**Process input:** Isolation must be maintained between input 1 and input 2. If both input 1 and input 2 are used as process inputs, a separate power supply and transmitter must be used for each input. Output option T (external signal conditioner power supply) can be used to supply power for only one input.

# Wiring Example



### **WARNING:**

To avoid potential electric shock, use National Electric Code (NEC) safety practices when wiring and connecting this unit to a power source and to electrical sensors or peripheral devices. Failure to do so could result in injury or death.



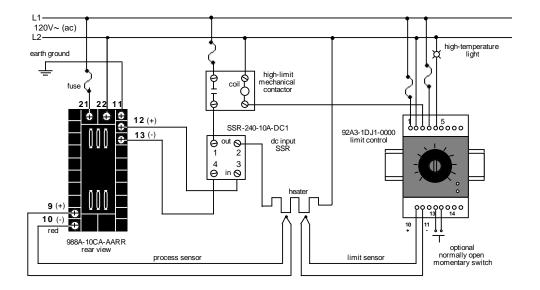
**WARNING:** Install high or low temperature limit control protection in systems where an over temperature fault condition could present a fire hazard or other hazard. Failure to install temperature limit control protection where a potential hazard exists could result in damage to equipment, property and injury to personnel.

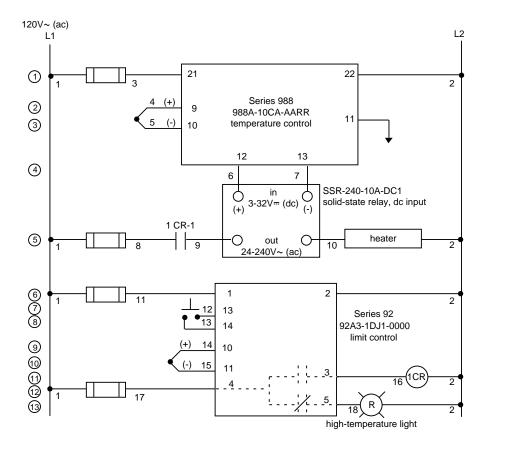


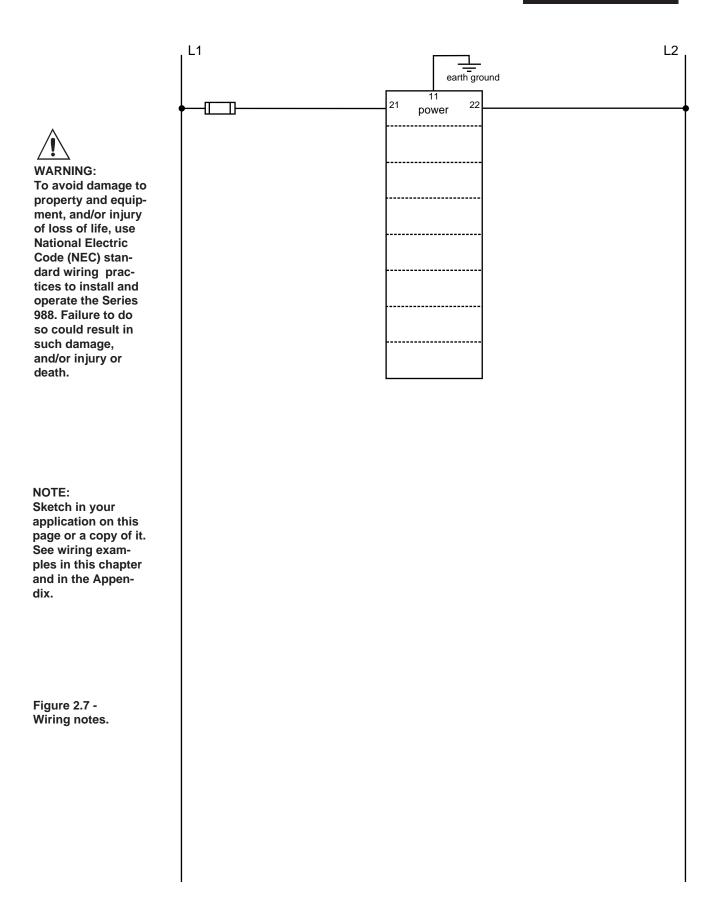
### **WARNING:**

To avoid damage to property and equipment, and/or injury of loss of life, use National Electric Code (NEC) standard wiring practices to install and operate the Series 988. Failure to do so could result in such damage, and/or injury or death.

Figure 2.6 -System wiring example.







# Input 1 Wiring

### Figure 2.8a — Thermocouple or 0-50mV (high impedance)

NOTE: Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (<u>Chapter 2</u> and <u>Appendix</u>);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

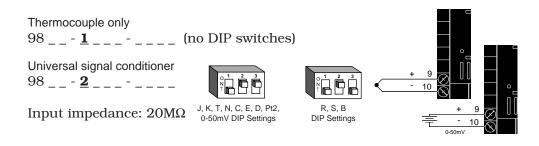


Figure 2.8b — RTD (2- or 3-wire) (100  $\Omega$ )

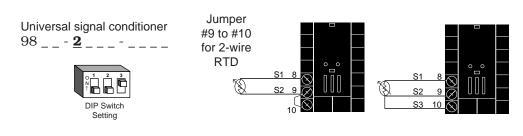
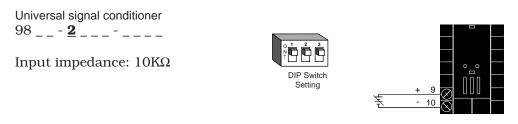


Figure 2.8c — 0-5V=, 1-5V= or 0-10V= (dc) Process



### Figure 2.8d — **0-20mA or 4-20mA Process**

Universal signal conditioner  $98\_-2\_--\_$  Input impedance:  $7\Omega$ 

### NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (<u>Chapter 2</u> and <u>Appendix</u>);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

### Figure 2.9a — Thermocouple or 0-50mV (high impedance)

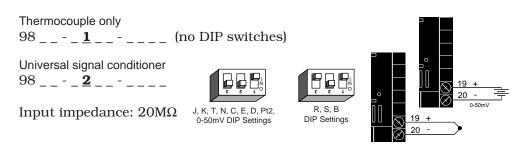


Figure 2.9b — RTD (2- or 3-wire) (100  $\Omega$ )

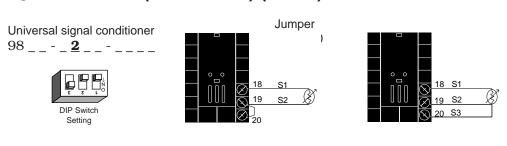
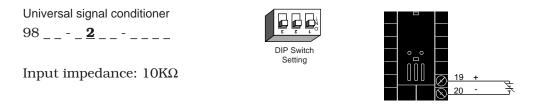


Figure 2.9c — 0-5V =, 1-5V = or 0-10V = (dc) Process



### Figure 2.9d - 0-20mA or 4-20mA Process

Universal signal conditioner  $98\_--22\_--\_$   $Input impedance: 7\Omega$  DIP Switch Setting 20 +

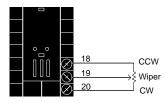
# Input 2 Wiring

### NOTE:

See <u>Chapter 8</u> for information on slidewire feedback.

### Figure 2.10a — Slidewire Feedback or Potentiometer Input

98 \_ \_ - \_ **3** \_ \_ - \_ \_ \_



### NOTE:

A process output cannot be installed on output 1 when using a current transformer input.

### NOTE:

Successful installation requires five steps:

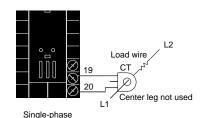
- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

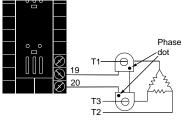
### Figure 2.10b — Current Transformer Input

98 \_ \_ - \_ **4** \_ \_ - \_ \_ \_

The current transformer must be purchased separately. See Appendix for Watlow current transformer part numbers.

Systems that use more than 50 Amps need an interstage transformer. For example, if you use a 300A current transformer, part #16-0073, and an interstage transformer, part #16-0176, the 300A current transformer provides a 5A signal to the interstage transformer. In turn, the transformer sends a 20mA maximum signal to the controller.



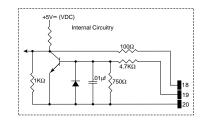


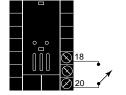
3-phase using 2 current transformers

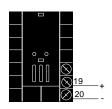
### Figure 2.10c — Digital Event Input 2

98 \_ \_ - \_ **5** \_ \_ - \_ \_ \_

**open** 0-3V≡ (dc) Event Input 2 off **closed** 14-36V≡ (dc) Event Input 2 on







# **Event Input 1 Wiring**

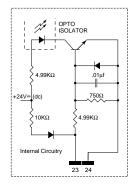
### Figure 2.11a — Digital Event Input 1

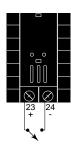
NOTE: Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (<u>Chapter 2</u> and <u>Appendix</u>);
- Sensor installation (<u>Chapter 2</u>); and
  Wiring (<u>Chapter 2</u>).

Available on all units.

**open** 14-36V**=** (dc) Event Input 1 off **closed** 0-3V**=** (dc) Event Input 1 on





# **Output 1 Wiring**

### NOTE:

Successful installation requires five

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

### NOTE:

Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor **Quencharc brand** name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

### Figure 2.12a — AC Outputs

### Solid-state Relay with Contact Suppression

98 \_ \_ - \_ \_ **B** \_ - \_ \_ \_

0.5 amps, minimum off-state impedance:  $20 \text{K}\Omega$ 

### Electromechanical Relay with Contact Suppression

(Suppression between NO and COM contacts only)

98 \_ \_ - \_ **D** \_ - \_ \_ \_

Form C, 5 amps, minimum off-state impedance:  $20K\Omega$ 

### Electromechanical Relay without Contact Suppression

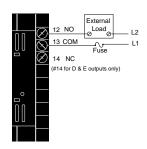
98 \_ \_ - \_ **<u>E</u>** \_ - \_ \_ \_

Form C, 5 amps off-state impedance:  $31M\Omega$ 

### Solid-state Relay without Contact Suppression

98 \_ \_ - \_ \_ **K** \_ - \_ \_ \_

0.5 amps, off-state impedance:  $31M\Omega$ 



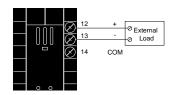
### Figure 2.12b — Switched DC, Open Collector

98 \_ \_ - \_ **C** \_ - \_ \_ \_

Maximum voltage: 42V (dc)

Maximum current: 1A

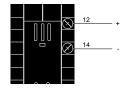




### Figure 2.12c — 0-20mA and 4-20mA Process

98 \_ \_ - \_ **F** \_ - \_ \_ \_

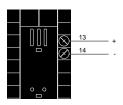
Maximum load impedance:  $800\Omega$ 



### Figure 2.12d — 0-5V=, 1-5V= and 0-10V= (dc) Process

98 \_ \_ - \_ **F** \_ - \_ \_ \_

Minimum load impedance:  $1K\Omega$ 



### Figure 2.13a — AC Outputs

### NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (<u>Chapter 2</u> and <u>Appendix</u>);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

### NOTE:

Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

### NOTE:

Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

### Solid-state Relay with Contact Suppression

98 \_ \_ - \_ **B** - \_ \_ \_

0.5 amps, minimum off-state impedance:  $20 \text{K}\Omega$ 

### Electromechanical Relay with Contact Suppression

(Suppression between NO and COM contacts only)

98 \_ - - \_ \_ **D** - \_ \_ \_

Form C, 5 amps, minimum off-state impedance:  $20K\Omega$ 

### Electromechanical Relay without Contact Suppression

98 \_ \_ - \_ \_ **<u>E</u>** - \_ \_ \_

Form C, 5 amps off-state impedance:  $31M\Omega$ 

### Solid-state Relay without Contact Suppression

98 \_ \_ - \_ \_ **K** - \_ \_ \_

0.5 amps, off-state impedance:  $31M\Omega$ 

# 15 NO Load Load Load Load Fuse L1 Fuse

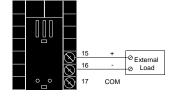
### Figure 2.13b — Switched DC, Open Collector

98 \_ \_ - \_ \_ <u>C</u> - \_ \_ \_

Maximum voltage: 42V= (dc)

Maximum current: 1A

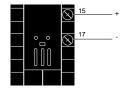




### Figure 2.13c — 0-20mA and 4-20mA Process

98 \_ \_ - \_ **F** - \_ \_ \_

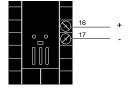
Maximum load impedance:  $800\Omega$ 



### Figure 2.13d — 0-5V=, 1-5V= and 0-10V= (dc) Process

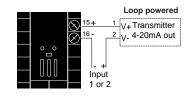
98 \_ \_ - \_ \_ **F** - \_ \_ \_

Minimum load impedance:  $1 \text{K}\Omega$ 



### Figure 2.13e — External Signal Conditioner Power Supply

98 \_ \_ - \_ \_ **T** - \_ \_ \_



# **Output 3 Wiring**

### NOTE:

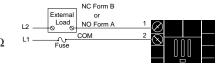
Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

### Figure 2.14a — AC Outputs

### Solid-state Relay with Contact Suppression

98 \_ \_ - \_ \_ - **B** \_ \_ \_ 0.5 amps, minimum off-state impedance:  $20 \text{K}\Omega$ 



### Electromechanical Relay without Contact Suppression

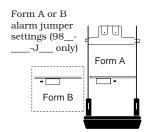
98 \_ \_ - \_ \_ \_ **J** \_ \_ \_ \_

Form A or B, 5 amps, off-state impedance:  $31M\Omega$ 

### Solid-state Relay without Contact Suppression

98 \_ \_ - \_ **K** \_ \_ \_ \_

0.5 amps, off-state impedance:  $31M\Omega$ 



### NOTE:

Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor Quencharc brand name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

### NOTE:

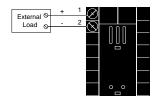
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1 or input 2.

### Figure 2.14b — Switched DC

98 \_ \_ - \_ \_ - **C** \_ \_ \_

Minimum load resistance:  $500\Omega$ 





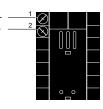
### Figure 2.14c — Process Retransmit

**0-20mA, 4-20mA,** Load impedance:  $600\Omega$  max.

98 \_ \_ - \_ \_ \_ - **<u>M</u>** \_ \_ \_

**0-5V=, 1-5V=, 0-10V= (VDC)**, Load impedance:  $500\Omega$  min.

98 \_ \_ - \_ \_ \_ - <u>N</u> \_ \_ \_



### Figure 2.14d — External Signal Conditioner Power Supply

98 \_ \_ - **T** \_ \_ \_

NOTE: See Chapter 1 for power supply DIP switch information. Transmitter V+ 4-20mA out V-Input

# Output 4 Wiring

### NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match
   (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

### NOTE:

Switching inductive loads (relay coils, solenoids, etc.) with the mechanical relay or solid state relay output options requires using an R.C. suppressor. Watlow carries the R.C. suppressor **Quencharc brand** name, which is a trademark of ITW Paktron. Watlow Part No. 0804-0147-0000.

### NOTE:

Input-to-output isolation is defeated when the external transmitter power supply is used to power a signal conditioner connected to input 1 or input 2.

### Figure 2.15a — AC Outputs

### Solid-state Relay with Contact Suppression

98 \_ \_ - \_ **B** \_ \_

0.5 amps, minimum off-state impedance:  $20\text{K}\Omega$ 

### Electromechanical Relay with Contact Suppression

(Suppression between NO and COM contacts only)

98 \_ \_ - \_ **D** \_ \_ \_

Form C, 5 amps, minimum off-state impedance:  $20 \text{K}\Omega$ 

### Electromechanical Relay without Contact Suppression

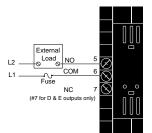
98 \_ \_ - \_ \_ **\_ <u>E</u>** \_ \_ \_

Form C, 5 amps, off-state impedance:  $31M\Omega$ 

### Solid-state Relay without Contact Suppression

98 \_ \_ - \_ \_ \_ **K** \_ \_ \_

0.5 amps, off-state impedance:  $31\mbox{M}\Omega$ 



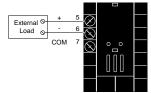
### Figure 2.15b — Switched DC, Open Collector

98 \_ \_ - \_ \_ \_ - \_ **C** \_ \_

Maximum voltage: 42V (dc)

Maximum current: 1A

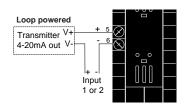




### Figure 2.15c — External Signal Conditioner Power Supply

98 \_ \_ - \_ \_ \_ - \_ **T** \_ \_

NOTE: See Chapter 1 for power supply DIP switch information.



For data communications wiring refer to *Data Communications* with the Watlow Series 988 Family of Controllers.

# Chapter 3 Front Panel and Display Loop

### **Keys and Displays**

### **Upper Display**

Indicates the actual process value, prompt parameter value or error code.

### **DEV LED**

When lit, the lower display shows the most recent deviation unit from the set point.

### % OUT LED

When lit, the lower display shows the current percent output.

### **Up-arrow Key**

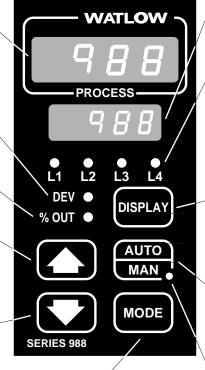
Increases the value or changes the parameter in the upper display (except for set point changes in the Display Loop, which occur in the lower display). Hold the key down to increase the value rapidly. New data takes effect in five seconds or when the Mode key or Display key is pressed.

### **Down-arrow Key**

Decreases the value or changes the parameter in the upper display (except for set point changes in the Display Loop, which occur in the lower display). Hold the key down to decrease the value rapidly. New data takes effect in five seconds or when the Mode key or Display key is pressed.

### Up + Down Keys

Press simultaneously for three seconds to go to the Setup Menu. Continue to press both keys for another three seconds to go to the Factory Menu. Access to the Setup and Factory menus can be disabled with lockout DIP switch.



### Mode Key

Enters new data and steps to the next prompt in the current menu.

### Mode + Up-arrow Keys

Hold the Mode key then press the Up-arrow key to move backwards through the current menu. Scrolling stops when you reach the top of the menu.

### **Lower Display**

Indicates the set point, deviation, percent power, temperature unit, menu prompt name or alarm code.

### L1, L2, L3, L4

These LED's indicate when output 1, 2, 3 or 4 are active. Outputs can be configured as:

Ot1 Control

Ot2 Control or Alarm

Ot3 Alarm or Retransmit

Ot4 Alarm or Communications (flashes on transmit and

receive)

### **Display Key**

Pressing this key enters the Display Loop. Press the Display key at any time to return to this loop. The next page has more information on the Display Loop.

### Auto/Man Key

In Manual mode the lower display shows percent output. Pressed once, it clears any latched alarm. If pressed again within five seconds it will toggle between Auto and Manual mode.

### Auto/Man LED

Lit when the control is in Manual operation. Press the Auto/Man key twice to enter Automatic operation. When blinking, press the Auto/Man key to toggle between Auto and Manual. After five seconds without pressing the Auto/Man key, the LED stops blinking and returns to its previous state.

Figure 3.1 - Series 988 Keys and Displays

# **Display Loop**

### **Display Loop**

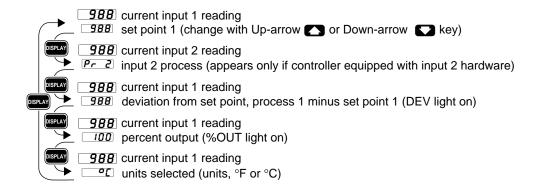
The Display Loop is the "home" state of the Series 988 controller. Pressing the Display key returns the controller to the Display Loop from any prompt in any menu. The controller automatically returns to the Display Loop from any menu when a minute passes without any keys being pressed.

NOTE:
For information on input 1 In I and input 2 In 2 ranges, refer to Chapter 4.

NOTE:

If \_\_\_\_\_\_ is selected for \_\_\_\_\_\_\_, in the Input Menu, the \_\_\_\_\_\_\_\_\_ prompt will not appear.

Figure 3.2 -The Display Loop



# **Chapter 4** The Setup Menus

### NOTE:

When navigating through menus, outputs will be disabled.

### NOTE:

Press the Display key bear to return to the Display Loop from any point in any menu.

### **Navigating the Setup Menus**

To reach the Setup Menus, begin in the Display Loop and press both the Uparrow and Down-arrow keys for three seconds. The Setup Menu prompt **5£** will appear in the lower display, and the Input Menu prompt **InP** will appear in the upper display. The four Setup Menus are: Input **InP**; Output **O**\* Down-arrow key to select a menu and the Mode key to step through a menu. The Communications Menu appears only on units equipped with the data communications option.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 988 returns to the Setup Menu prompt **5**££. Use the Up-arrow and Down-arrow keys to select the next menu, or use the Mode key to advance through the same menu again. To move backwards through the menu hold the Mode key down and press the Up-arrow key . Use the Up-arrow or Down-arrow key to change the prompt setting.

Refer to the Appendix for model number options. For information about communications and the communications prompts, refer to the supplemental manual *Data Communications with the Watlow Series 988 Family of Controllers*.

DEPE

5E Ł

Output

Menu

p. 4.18

InPt

5EE Input

Menu

p. 4.2



● Begin in the Display Loop, and press the Up-arrow
 and Down-arrow
 keys simultaneously to reach the Setup Menus.

9L b L

5E Ł

Global

Menu

p. 4.34

Communications

Menu

p. 4.44

Figure 4.1 -Navigating the Setup Menus.

### NOTE: The lockout DIP switch hides the Setup Menus. See Chapter 1.



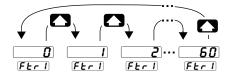
**2** Press the Up-arrow key **(** to select one of the Setup Menus.

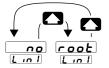
# Setup-Input

### **Reaching the Input Menu**



3 Select the Input Menu, then press the Mode key wore to step through the prompts.





**②** Press the Up-arrow key **△** or the Down-arrow key **○** to select one of the prompt values.

\*Prompts may not appear, depending on controller configuration.

InPE 5EE Setup Prompt Enter your settings, from the controller's upper display. In Input 1 **∂EC** / \*Decimal 1 👱 🗔 Range Low 1 📜 🖙 Range High 1 Input 1 (p. 4.3) CRLI Calibration Offset 1 rtd ! \*RTD Calibration Curve 1 FEF I Software Filter 1 Lin 1 \*Linearization 1 ᆂ ፲*፲፭* \*Input 2 \*Remote Set Point Decimal 2 MODE \*Range Low 2 😕 🕝 \*Range High 2 Input 2 (p. 4.9) Lrat \*Learn Low LcoH \*Learn High **CRL2** \*Calibration Offset 2 \*RTD Calibration Curve 2 FEr2 \*Software Filter 2 Linearization 2 #שהŁ \*Hunt Slidewire (p. 4.16)

5H45 \*Slidewire Hysteresis

Figure 4.2 -The Input Menu.

### **Input Prompts**

NOTE:

Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1

| JEC | and Decimal 2 | JEC | parameters in the Input Menu.

When you are in the Setup menus, the Series 988 displays the menu selection ([InPE], [IEPE], [IEPE] or [IEPE]) in the upper display, and [IEE] in the lower display.

The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the prompt in the lower display and its value in the upper display. Use the Up-arrow or Down-arrow key to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key woos.



**CAUTION:** 

to the factory

default values. Document all set-

Changing the value of \_\_\_\_\_\_ changes

most other prompts

tings before changing sensor type.

Verify the correct

sensor type before

this guideline could

result in damage to

equipment or prop-

erty. Document all

settings before changing sensor

type.

making a change.

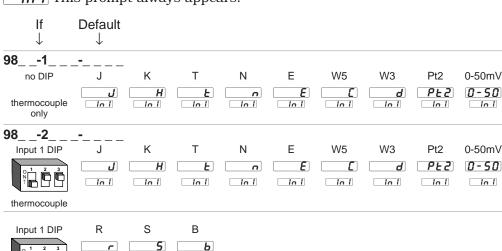
Failure to follow

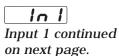
### Input 1

**Select sensor type for input 1.** This selection must match the sensor type connected to terminals 8, 9 and 10. See <u>Appendix</u> for more information about sensors.

- Changing the value of <u>in !</u> changes all other prompts to the factory default values, except the Communications and Lockout menus, the <u>f. F</u> prompt in the Global Menu and the <u>dF!</u> prompt in the Calibration Menu. If you change the value, the default warning <u>dF! E</u> will flash in the upper display.
- Changes do not take effect automatically after five seconds; you must press the Mode key wore to enter the sensor type change and advance to the next prompt.

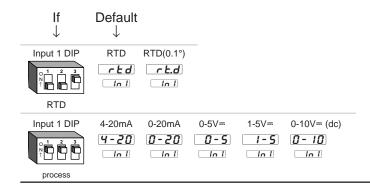
In I This prompt always appears.





### Setup-Input

Input 1 continued from previous page.





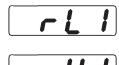
### **Decimal 1**

**Select the decimal point location for process type input 1 data.** This prompt, in conjunction with the Range Low and Range High prompts, allows you to format and limit units of measure for process 1.

- All prompts with units of measure related to input 1 will display in the selected decimal format.
- This affects propbands, alarm set points, process set points, calibration offsets, deadbands and ranges.

**JEL!** This prompt appears only if you have set input 1 **In!** to a process input or to a thermocouple input set to 0-50mV.





### Range Low 1 and Range High 1

**Select the low and high limits for input 1.** These prompts limit the adjustment range for the set points. The default values are the same as the limits of the sensor you selected by setting the input 1 DIP switch and selecting a value for Input 1  $I_0 I_0$ .

• Process inputs are scaled by these values. Range high is the value displayed when the maximum process signal is present at the input. Range low is the value displayed when the minimum process signal is present at the input.

| NOTE:                 |
|-----------------------|
| These values do not   |
| affect the low or the |
| high set point limit  |
| for process alarms.   |

| Example: | Set <b>In 1</b> to <b>4-20</b> mA |
|----------|-----------------------------------|
|          | Set [ c ] I to [ Inn].            |

Set <u>r[]</u> to <u>IUU</u>. Set <u>rH]</u> to <u>500</u>.

A 4mA input will display **100**. A 12mA input will display **300**. A 20mA input will display **500**.

- The low and high values of each sensor type are listed on the specifications page of the Appendix.
- Choose between Fahrenheit and Celsius at the **[[]** prompt in the Global Menu.

**rl** These prompts always appear.

| 32     32   |          | Default Defau | ult Default Defau<br>↓ ↓<br>☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐ | ult           |
|---|----------|---------------|---|---------------|
| H   |          |               |   | 981 or<br>982 |
| 6       32[2312]       0[300]         6       -328[470]       -200[799]         (W5)       0[2316]         (W3)       0[2316]         PE2       32[4200]       0[2316]         high impedance |          | - 3282500     | -200[37]  |               |
| E       -328[470]       -200[799]         (W5)       32[4200]       0[2316]         (W3)       32[4200]       0[2316]         PE2       32[2543]       0[1395]         high impedance         | E        | -328 750      | -200399   |               |
| (W5) (W3) (W3) (PE2) 32(2543)  high impedance   | <u> </u> | 32[2372]      | 0[300]  |               |
| (W3)  ### ### ############################  | Ε        | -328[1470]    | -200 199  |               |
| PE2 32[2543] 0[395] high impedance  |          | 324200        | 0[23 16]  |               |
| high impedance  |          | 324200        | 023 16  |               |
|   | PE2      | 32[2543]      | 0[1395]   |               |
|   |          | -999 999      | -513 513  |               |

# NOTE: When high impedance [3-50] is selected for input 1 the range high for both [3] and [4] can be extended to [3]. The range low when [4] is selected can be extended to [3].

| rHI               |
|-------------------|
| Range Low 1 and   |
| Range High 1      |
| continued on next |
| page.             |

# Setup-Input



Range Low 1 and Range High 1 continued from previous page.

### NOTE:

These values do not affect the low or the high set point limit for process alarms.

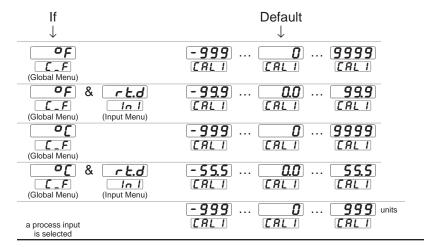
|             | CF1 CH1       | cti chi                   |     |
|-------------|---------------|---------------------------|-----|
| only        | 32[3200]      | 0[1760]                   | 982 |
|             |               |                           |     |
| <b>5</b>    | <b>323200</b> | <u> </u>                  | _   |
| <b>b</b>    | <b>323300</b> | <u> </u>                  |     |
| red         | -328[1472]    | <u>-200</u> <u>800</u>    | _   |
| r Ł.d       | -999[9999]    | <u>- 133</u> <u>[531]</u> | _   |
| 4-20        | - <b>999</b>  | .[ <b>9999</b> ] units    |     |
| 0-20        | - <b>999</b>  | .[ <b>9999</b> ] units    |     |
| 0-5         | - <b>999</b>  | .[ <b>9999</b> ] units    |     |
| <u> 1-5</u> | - <b>999</b>  | .[ <b>9999</b> ] units    |     |
| 0-10        | - <b>999</b>  | . <u>9999</u> units       |     |

# [AL I

### **Calibration Offset 1**

**Offset the input 1 signal by a positive or negative value.** This allows you to compensate for lead resistance, sensor errors or other factors.

**[FIL I**] This prompt always appears.





### RTD (100 $\Omega$ ) Calibration Curve 1

Select the calibration curve for the RTD 1 input. The RTD input uses either the European (DIN,  $0.003850\Omega/\Omega/^{\circ}$ C) or the Japanese (JIS,  $0.003916\Omega/\Omega/^{\circ}$ C) linearization standard.

 $\[ \underline{r} \, \underline{t} \, \underline{d} \, I \]$  This prompt appears only if you have set  $\[ \underline{l} \, \underline{n} \, I \]$  to  $\[ \underline{r} \, \underline{t} \, \underline{d} \]$  or  $\[ \underline{r} \, \underline{t} \, \underline{d} \]$ .

# Ftr 1

### **Software Filter 1**

**Select the filter time constant, in seconds, for input 1.** This smooths a rapidly changing input signal for display or control purposes.

- Select a positive value to filter only the display.
- Select a negative value to filter the input signal.
- Set the value to \_\_\_\_\_\_ to disable the filter.

**F***E***r** *I* This prompt always appears.

# Setup-Input

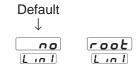


### **Linearization 1**

### Select square root linearization for input 1.

**Lin!** This prompt appears only if you have set **In!** to a process input or to a thermocouple set to (3-50) mV.

NOTE: See <u>Chapter 8</u> for more information on input linearization.





### **CAUTION:**

Changing the value of In2 changes most other prompts to the factory making a change. Failure to follow this quideline could result in damage to equipment or property. Document all settings before changing sensor type.

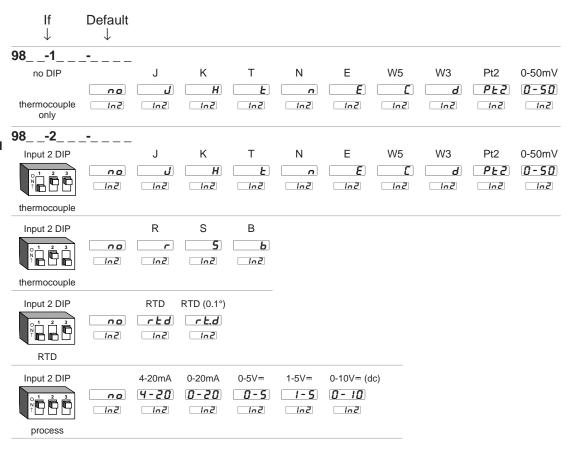
### default values. Document all settings before changing sensor type. Verify the correct sensor type before

Input 2

**Select sensor type for input 2.** This selection must match the sensor type connected to terminals 18, 19 and 20. See Appendix for more information about sensors.

- Changing the value of \_\_\_\_\_\_ changes all other prompts to the factory default values, except the Communications and Lockout menus, the [[F] prompt in the Global Menu and the GFL prompt in the Calibration Menu. If you change the value, the default warning dflb will flash in the upper display.
- Changes do not take effect automatically after five seconds; you must press the Mode key wore to enter the sensor type change and advance to the next prompt.

This prompt and other Input 2 prompts appear only on controllers equipped with input 2 hardware (not 98\_\_-\_0\_\_-\_\_\_).



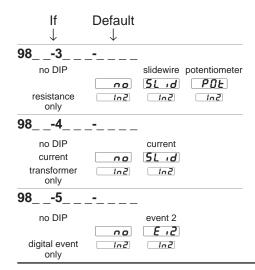
NOTE:

If no is selected for In2 none of the other input 2 prompts will appear.

102 Input 2 continued on next page.

### Setup-Input

In 2 In 2 Input 2 continued from previous page.

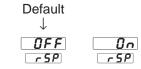




#### **Remote Set Point**

#### Enable a remote set point signal.

**r5P** This prompt appears only if the controller is equipped with input 2 hardware and if **In2** is not set to **no** and if **In2** (in the Global Menu) is set to **no**.





#### **Decimal 2**

**Select the decimal point location for process type input 2 data.** This prompt, in conjunction with the Range Low and Range High prompts, allows you to format and limit units of measure for process 2.

- All prompts with units of measure related to input 2 will display in the selected decimal format.
- This affects propbands, alarm set points, process set points, calibration offsets, deadbands and ranges.

**JEC2** This prompt appears only if you have set input 2 **In2** to a process input, **[Urr**] or a thermocouple input set to **[3-50]** mV.





#### Range Low 2 and Range High 2



**Select the low and high limits for input 2.** These prompts limit the adjustment range for the set points. The default values are the same as the limits of the sensor you selected by setting the input 2 DIP switch and selecting a value for Input 2 **In2**.

• Process inputs are scaled by these values. Range high is the value displayed when the maximum process signal is present at the input. Range low is the value displayed when the minimum process signal is present at the input.

Set **rL2** to **100**. Set **rH2** to **500**.

A 4mA input will display **100**. A 12mA input will display **300**. A 20mA input will display **500**.

Range Low 2 and Range High 2 continued on next page.

- The low and high values of each sensor type are listed on the specifications page of the Appendix.
- Choose between Fahrenheit and Celsius at the **[[]** prompt in the Global Menu.

These prompts appear only if the controller is equipped with input 2 hardware and with Input 2  $\boxed{In2}$  not set to  $\boxed{In2}$  or  $\boxed{E \cdot 2}$ .

# Setup-Input

| <u> </u>  |  | $\begin{array}{ccc} \text{Default} & & \text{Default} \\ \downarrow & & \downarrow \end{array}$ | Default Default ↓ ↓ | t             |
|---|--|---|---------------------|---------------|
| Range Low 2 and                                     |  | CTS CHS   |                     |               |
| Range High 2 continued from previ-                  | <u>J</u>                                 | 32 ISOO   | 0816                | 981 or<br>982 |
| ous page.   | (K) <b>H</b>                             | - 328)[2500]  | -200[37]            |               |
|   | E  | -328 750  | -200399             | -             |
|   | n  | 32[2372]  | <b>0</b> [1300]     | -             |
|   | Ε  | -328)[1470]   | -200 199            | -             |
|   | (W5)                                     | 324200  | 023 16              | -             |
| NOTE:<br>These values do not                        | (W3)                                     | 324200  | 023 16              | -             |
| affect the low or the high set point limit          | PE2                                      | 322543  | <b>0</b> 1395       | -             |
| for process alarms.                                 | high impedance                           | -999 999  | -513 513            | -             |
|   |  | 323200  | 01760               | 982 only      |
|   | 5  | 323200  | 0[1760]             | -             |
| NOTE:   | Ь  | 323300  | <b>D</b> [18 16]    | -             |
| When high impedance <u>(7 - 5 (7)</u> is            | rtd                                      | -328[472]   | -200800             | -             |
| selected for input 1 the range high for both OF and | r Ł.d                                    | -9999999  | - 13.3[5317]        | _             |
| oF can be extended to 9999.                         | 4-20                                     | - <b>999</b> [  | <b>9999</b> units   |               |
| The range low when is selected                      | 0-20                                     | - <b>999</b> 9  | <b>9999</b> units   |               |
| can be extended to [-999].                          | 0-5                                      | <b>- 999</b> [  | <b>9999</b> units   |               |
|   | 1-5                                      | <b>- 999</b> [  | <b>9999</b> units   |               |
|   | 0-10                                     | <b>- 999</b> [  | <b>9999</b> units   |               |
|   | 0-50                                     | <b>- 999</b> [  | <b>9999</b> units   |               |
|   | 0400                                     | <b>- 999</b> [  | <b>9999</b> units   |               |
|   | slidewire<br><b>5<i>L</i> .</b> <i>d</i> | [ [ [ [ [ [ [ [ [ [ [ [ [ [ [ [ [ [ [   | 1200 ohms           |               |
|   | current <b>Eurr</b>                      | <b>B</b>  | <b>50</b> amps      |               |
|   | potentiometer <b>PDE</b>                 | <b>[</b> ][   | 1200 ohms           |               |



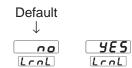
#### **Learn Low**

Write the low-end resistance of the slidewire potentiometer to the range low 2 parameter.

 $[\underline{LrnL}]$  This prompt appears only on controllers equipped with input 2 hardware and with Input 2  $[\underline{InC}]$  set to  $[\underline{SLnC}]$  or  $[\underline{PDL}]$ .

#### NOTE:

See <u>Chapter 8</u> for more information on slidewire feedback.





#### **Learn High**

Write the high-end resistance of the slidewire potentiometer to the range low 2 parameter.

 $[\underline{LrnH}]$  This prompt appears only on controllers equipped with input 2 hardware and with Input 2  $[\underline{In2}]$  set to  $[\underline{5Lnd}]$  or  $[\underline{PDE}]$ .

#### NOTE:

See <u>Chapter 8</u> for more information on slidewire feedback.

| Default<br>↓ |            |
|--------------|------------|
| no           | <b>YE5</b> |
| LrnH         | LrnH       |



#### **Calibration Offset 2**

**Offset the input 2 signal by a positive or negative value.** This allows you to compensate for lead resistance, sensor errors or other factors.

**[RL2]** This prompt appears only if the controller is equipped with input 2 hardware and if  $\boxed{In2}$  is not set to  $\boxed{no}$  or  $\boxed{E\cdot 2}$ .

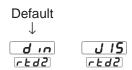
| If<br>↓                                 | Minimum               | Default<br>↓ | Max. setting/range   |
|---|-----------------------|--------------|----------------------|
| C_F<br>(Global Menu)                    | - <b>999</b><br>[RL2] | CAL 2        | <b>999</b><br>Cal 2  |
| C_F & rt.a<br>(Global Menu) (Input Menu | CAL2                  | CAL 2        | <b>99.9</b><br>Cal 2 |
| C_F<br>(Global Menu)                    | -555<br>[RL2]         | CAL 2        | <u>555</u><br>CRL2   |
| C_F (Global Menu) (Input Menu           | C R L 2               | CAL 2        | <b>55.5</b><br>CAL 2 |
| a process input<br>is selected          | - <b>999</b><br>[RL2] | CAL 2        | <b>999</b> units     |



#### **RTD Calibration Curve 2**

Select the calibration curve for the RTD 2 input. The RTD input uses either the European (DIN,  $0.003850\Omega/\Omega/^{\circ}$ C) or Japanese (JIS,  $0.003916\Omega/\Omega/^{\circ}$ C) linearization standard.

 $rec{r \not L \not d \not Z}$  This prompt appears only on controllers equipped with input 2 hardware and with  $rec{r \not L \not d}$  set to  $rec{r \not L \not d}$ .



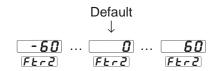


#### **Software Filter 2**

**Select the filter time constant, in seconds, for input 2.** This smooths a rapidly changing input signal for display or control purposes.

- Select a positive value to filter only the display.
- Select a negative value to filter the input signal.
- Set the value to \_\_\_\_\_\_ to disable the filter.

**FEC2** This prompt appears only on controllers equipped with input 2 hardware and with  $\boxed{In2}$  not set to  $\boxed{no}$  or  $\boxed{EI2}$ .





#### **Linearization 2**

#### Select square root linearization for input 2.

#### NOTE: See <u>Chapter 8</u> for more information on input linearization.

| Default<br>↓ |      |
|--------------|------|
| L 102        | root |

### Setup-Input



NOTE: See <u>Chapter 8</u> for more information

on slidewire feed-

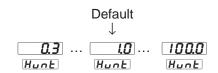
back.

#### Hunt

Set the deadband, as a percentage of output, to keep the valve from hunting.

• The slidewire hysteresis **[5HY5**] setting provides additional control over a valve.

**Hunk** This prompt appears only if the controller is equipped with slidewire hardware  $(98\_\_\_3\_\_\_\_\_)$  and with  $\boxed{ 102}$  set to  $\boxed{51.10}$ .





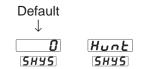
#### **Slidewire Hysteresis**

Set the inner hysteresis, the point at which the valve output turns off.

• The figure below illustrates the interaction between slidewire hysteresis [5HY5] and hunt [Hunk].

[5HY5] This prompt appears only if the controller is equipped with slidewire hardware (98\_\_-3\_\_-\_\_) and with Input 2 [InZ] set to [5LID]

NOTE: See <u>Chapter 8</u> for more information on slidewire feedback.



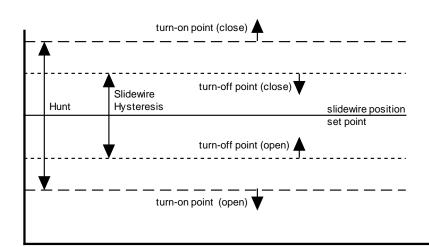
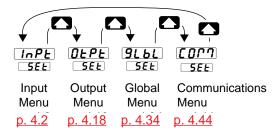


Figure 4.17 -Hunt and slidewire inner hysteresis.

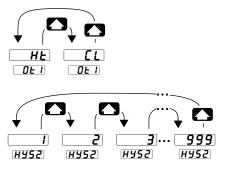
#### **Reaching the Output Menu**

● Begin in the Display Loop, and press the Up-arrow → and Downarrow → keys simultaneously for three seconds to reach the Setup Menus.



**②** Press the Up-arrow key **△** to select one of the Setup Menus.

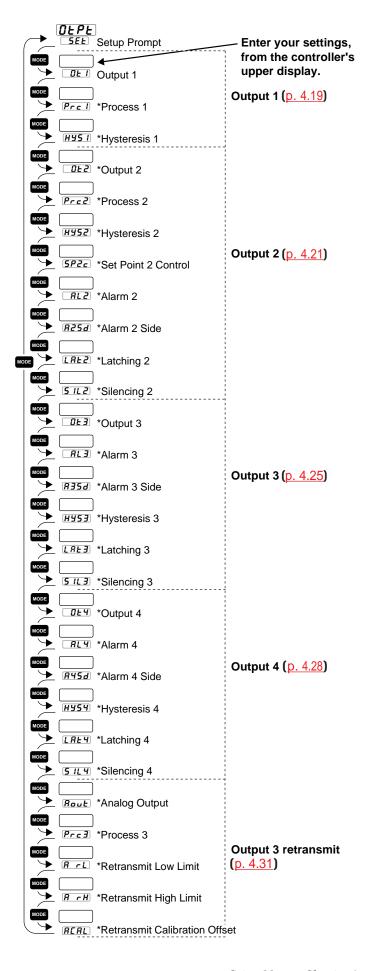
• Press the Mode key MODE to step through the prompts.



**②** Press the Up-arrow key **△** or the Down-arrow key **○** to select one of the prompt values.

\*Prompts may not appear, depending on controller configuration.

Figure 4.18 - Navigating the Output Menu.



#### **Output Prompts**

#### NOTE:

Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1

| JE[] and Decimal 2
| JE[] parameters in the Input Menu.

When you are in the Setup menus, the Series 988 displays the menu selection ([InPE], [InPE], [InPE]) or [InPE]) in the upper display, and [InPE] in the lower display.

The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key woos.

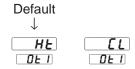


#### Output 1

Set the way that output 1 will respond to a difference between the set point and an input variable.

- **HE** select reverse action, so that output 1 responds when the input signal is less than the setpoint.
- **[**[] select direct action, so that output 1 responds when the input signal is more than the setpoint.

**OE** I This prompt always appears.



### Prcl

#### **Process 1**

#### Select the process range for output 1.

 $P_{rc}$  This prompt appears only on controllers equipped with output 1 process hardware (98\_ -- \_F\_-\_ \_).

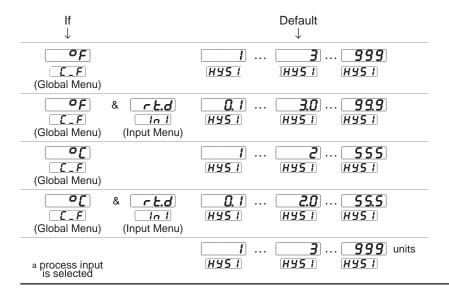
| Default      |        |                  |       |             |
|--------------|--------|------------------|-------|-------------|
| $\downarrow$ |        |                  |       |             |
| 4-20mA       | 0-20mA | 0-5V <del></del> | 1-5V≕ | 0-10V= (dc) |
| 4-20         | 0-20   | <i>B</i> - 5     | 1-5   | 0-10        |
| Prc!         | Prc!   | Prc!             | Prcl  | Prc!        |

# **HY5** 1

### **Hysteresis 1**

**Select the switching hysteresis for output 1.** This determines the change in temperature or process units needed to turn the output from full on to full off.

**HY5**! This prompt does not appear on controllers equipped with output 1 process hardware (98\_ -- \_F\_-\_\_\_). This prompt only appears with the controller set up as an on/off controller (Pb IR) = I).





#### **Output 2**

Set the way that output 2 will respond to a difference between the set point and an input variable.

- RL2 de-energizes output 2 in an alarm condition.
- **RL2** energizes output 2 in an alarm condition.
- **HE** select reverse action, so that output 2 responds when the input signal is less than the set point.
- **[**] select direct action, so that output 2 responds when the input signal is more than the set point.

This prompt appears only on controllers equipped with output 2 hardware (not  $98\_-\_\_A-\_\_\_$ ). RL2 and RL2n do not appear if output 2 is a process output  $(98\_-\_\_F-\_\_)$ . HE and  $\boxed{LL}$  do not appear if  $\boxed{RL90}$  (in the Global Menu) is set to  $\boxed{GUPL}$ .



## Prc2

#### **Process 2**

Select the process range for output 2.

Prc2 This prompt appears only on controllers equipped with output 2 process hardware (98\_-\_\_F-\_\_) and with De2 not set to no.



## **HY52**

#### **Hysteresis 2**

**Select the switching hysteresis for output 2.** This determines the change in temperature or process units needed to turn the output from off to on.

- If **AL2** is set to **FREE** settings for **HY52** will be in degrees per minute or units per minute.
- If the input referenced by **AL2** is set to **relative** the range is affected as listed below.

**HY52** This prompt appears only on controllers equipped with output 2 hardware and with the controller set up as an on/off controller (Pb2R) = O), and with O12 not set to O2. This prompt does not appear on controllers equipped with output 2 process hardware, (O12 = O13, or if O14 O15 in the Global menu = O17 O17.

| lf                          |                  |             | Default      |                  |
|-----------------------------|------------------|-------------|--------------|------------------|
|                             |                  |             | $\downarrow$ |                  |
| oF                          |                  |             |              | <b>999</b>       |
| [ [F                        |                  | HY52        | H425         | HY52             |
| (Global Menu)               |                  |             |              |                  |
| OF                          | & <b>r Ł.d</b>   | <b>[</b> ]  | 3.0          | <b>99.9</b>      |
| [ [F                        | Input 1 or 2     | H452        | H425         | HY52             |
| (Global Menu)               | (see note above) |             |              |                  |
| 0[                          |                  | <i>I</i>    | . 2          | 555              |
| [ [F                        |                  | H425        | H425         | H425             |
| (Global Menu)               |                  |             |              |                  |
| 0[                          | & <b>r Ł.d</b>   | <b>B.</b> 1 | <b>2.0</b>   | 55.5             |
| [ [F                        | Input 1 or 2     | H425        | H425         | H425             |
| (Global Menu)               | (see note above) |             |              |                  |
|                             |                  | <i>1</i>    | . <b>3</b>   | <b>999</b> units |
| a process input is selected |                  | H425        | H425         | нчѕг             |

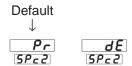
# 5*P2c*

#### **Set Point 2 Control**

Select a second set point.

- Pr enables a set point independent from the Set Point 1 **5P!** value.
- <u>dE</u> enables a set point at a deviation from the Set Point 1 <u>5P</u>! value.

[Prc] This prompt appears only if output 2 hardware is present and is equal to the output 1 setting.





NOTE:

on alarms.

See Chapter 7 for

more information

#### Alarm 2

**Select the alarm type for alarm 2.** Select the trigger points for the alarm with the [R2L0] and [R2H1] settings in the System Menu [545].

- **Pr!** uses the process signal from input 1. Changing the set point does not change the alarm response.
- **dE** I uses a deviation from the input 1 signal. Changing the set point changes the alarm response.
- **Pr2** uses the process signal from input 2. This choice does not appear if the controller is not equipped with input 2 hardware or if **In2** is set to **no** or **E12**.
- **dee** uses a deviation from the input 2 signal. This prompt does not appear if the controller is not equipped with input 2 hardware or if **ine** is set to **no** or **e**.
- **FREE** uses the rate of change at input 1 in degrees per minute.

**RL2** This prompt appears only on controllers equipped with output 2 hardware and with **DE2** set to **RL2** or **RL2**o.





#### Alarm 2 Side

Select what triggers alarm 2.

- **both** triggers an alarm when the signal  $\leq$  **R2L0** or  $\geq$  **R2H1**.
- $H \cdot 9H$  triggers an alarm when the signal  $\geq R2HI$ .
- **Lob** triggers an alarm when the signal  $\leq$  **R2L0**.

 $\boxed{\textbf{R256}}$  This prompt appears only on controllers equipped with output 2 hardware and with  $\boxed{\textbf{GEC}}$  set to  $\boxed{\textbf{RLC}}$  or  $\boxed{\textbf{RLC}}$ .

```
Default

↓

both H • 9H Loud

R250 R250 R250
```

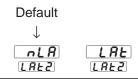


#### Latching 2

**Select whether alarm 2 will be latching or non-latching.** A latching alarm **LRE** must be turned off manually. A non-latching alarm **ner** turns off when an alarm condition no longer exists.

[LRE] This prompt appears only on controllers equipped with output 2 hardware and with [RE] set to [RE] or [RE].

NOTE: See <u>Chapter 7</u> for more information on alarms.



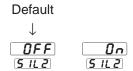


#### Silencing 2

Select silencing to inhibit alarm 2 on startup and to allow the operator to reset the alarm output, not the visual display.

• Silencing disables the alarm until the signal is between  $\boxed{\textit{R2L0}}$  and  $\boxed{\textit{R2H1}}$ .

**RL2** This prompt appears only on controllers equipped with output 2 hardware and with **DL2** set to **RL2** or **RL2** or **RL2**.





#### **Output 3**

#### Select the alarm condition for output 3.

- **AL3** de-energizes output 3 in an alarm condition.
- **AL3** energizes output 3 in an alarm condition.

NOTE: See <u>Chapter 7</u> for more information on alarms.

| This prompt appears only on controllers equipped with output | 3 |
|--|---|
| ardware for a relay (98B, 98J or                             |   |
| 8K) or switched dc (98C).                                    |   |
|  |   |
| Default  |   |
| $\downarrow$   |   |
| RL3 RL3n no  |   |
|  |   |



#### Alarm 3

#### Select the alarm type for alarm 3.

- **Pr!** uses the process signal from input 1.
- **dE** I uses a deviation from the input 1 signal.
- **Pr2** uses the process signal from input 2. This prompt does not appear if the controller is not equipped with input 2 hardware or if **In2** is set to **no** or **E12**.
- dE2 uses a deviation from the input 2 signal. This prompt does not appear if the controller is not equipped with input 2 hardware or if In2 is set to no or E.2.
- **FREE** uses the rate of change at input 1 in degrees per minute.

| <b>RL3</b> This prompt appears only on controllers equipped with output 3 |
|---|
| hardware for a relay (98B, 98J or   |
| 98K) or switched dc (98C), and with <b></b>                               |
| set to <b>RL3</b> or <b>RL3n</b> .  |

# Default ↓ Pr! dE! Pr2 dE2 rREE no RL3 RL3 RL3 RL3 RL3 RL3



See <u>Chapter 7</u> for more information

NOTE:

on alarms.

#### Alarm 3 Side

Select what triggers alarm 3.

- **both** triggers an alarm when the signal  $\leq$  **R3L0** or  $\geq$  **R3H1**.
- [H , gH] triggers an alarm when the signal  $\geq [R gH]$ .
- [LOUJ] triggers an alarm when the signal  $\leq [R3LO]$ .

 $\begin{picture}(20,0) \put(0,0){\line(1,0){15}} \put(0,0$ 



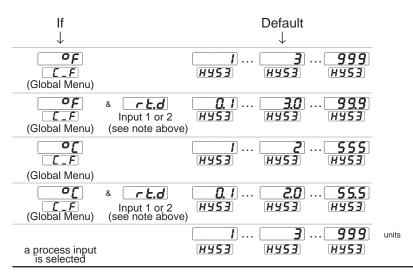
### **Hysteresis 3**

**Select the switching hysteresis for alarm 3.** This determines the change in temperature or process units needed to turn the output from off to on.

- If **AL3** is set to **FREE** settings for **HY53** will be in degrees per minute or units per minute.
- If the input referenced by  $\boxed{\textbf{RL} \ 3}$  is set to  $\boxed{\textbf{r} \ \textbf{E} . \textbf{d}}$  the range is affected as listed below.

[HY53] This prompt appears only on controllers equipped with output 3 hardware for a relay (98\_\_-\_\_\_-B\_\_\_, 98\_\_-\_\_\_-J\_\_\_ or

98\_ -- \_ \_ -K\_ \_ \_) or switched dc (98\_ -- \_ \_ -C\_ \_ \_).

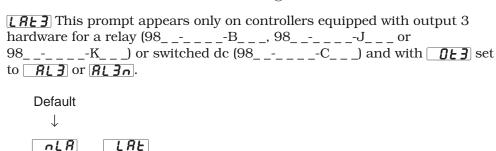




#### Latching 3

**Select whether alarm 3 will be latching or non-latching.** A latching alarm *LRE* must be turned off manually. A non-latching alarm *nLR* turns off when an alarm condition no longer exists.

NOTE: See <u>Chapter 7</u> for more information on alarms.





### Silencing 3

LRE3

LRE3

Select silencing to inhibit alarm 3 on startup and to allow the operator to reset the alarm output, not the visual display.

• Silencing disables the alarm until the signal is between **R3L0** and **R3H1**.

NOTE: See <u>Chapter 7</u> for more information on alarms. **[5** *IL* **3**] This prompt appears only on controllers equipped with output 3 hardware for a relay  $(98\_-\_\_--B\_\_, 98\_-\_\_--J\_\_$  or  $98\_-\_--K\_\_$  or switched dc  $(98\_--\_--C\_\_)$  and with  $\boxed{\texttt{OE}}$  set to  $\boxed{\texttt{RL3}}$  or  $\boxed{\texttt{RL3}}$ n.

| Default      |        |
|--------------|--------|
| $\downarrow$ |        |
| OFF          | On.    |
| 5 IL 3       | 5 1L 3 |



#### Output 4

#### Select the alarm condition for output 4.

- **FLY** de-energizes output 4 in an alarm condition.
- RLYn energizes output 4 in an alarm condition.

NOTE: See <u>Chapter 7</u> for more information on alarms.

| Default      |      |
|--------------|------|
| $\downarrow$ |      |
| <b>RLY</b>   | ALYn |
| DE4          | OE4  |



#### Alarm 4

#### Select the alarm type for alarm 4.

- **Pr** I uses a process signal from input 1.
- **dE** I uses a deviation from the input 1 signal.
- **Pr2** uses the process signal from input 2. This prompt does not appear if the controller is not equipped with input 2 hardware or if **In2** is set to **no** or **E 12**.
- dE2 uses a deviation from the input 2 signal. This prompt does not appear if the controller is not equipped with input 2 hardware or if In2 is set to In2.
- **FREE** uses the rate of change at input 1 in degrees per minute.

**RLY** This prompt appears only on controllers equipped with output 4 hardware for a relay (98\_ -- \_ -B\_ , 98\_ -- \_ -D\_ , 98\_ -- \_ -E\_ or 98\_ -- \_ -K\_ ) or switched dc (98\_ -- \_ -C\_ ).

| Default  |      |            |     |         |     |
|----------|------|------------|-----|---------|-----|
| ↓<br>Pri | dE I | <i>P-2</i> | 985 | r A E E | no  |
| BIY      | 814  | 814        | 814 | BIY     | 814 |



#### Alarm 4 Side

#### Select what triggers alarm 4.

- **both** triggers an alarm when the signal  $\leq [RYL]$  or  $\geq [RYH]$ .
- $H \cdot gH$  triggers an alarm when the signal  $\geq RHI$ .
- [LOLJ] triggers an alarm when the signal  $\leq [RYLO]$ .

NOTE: See <u>Chapter 7</u> for more information on alarms.

| <b>R45</b> This prompt appears only on controllers equipped with output 4 |
|---|
| hardware for a relay (98 B, 98 D,   |
| 98 E_ or 98 K_ ) or switched dc (98 C_ )                                  |
| and with OFY set to ALY or ALY.   |

| Default      |       |      |
|--------------|-------|------|
| $\downarrow$ |       |      |
| POFH.        | H ISH | LOUJ |
| R45d         | R45d  | 845d |

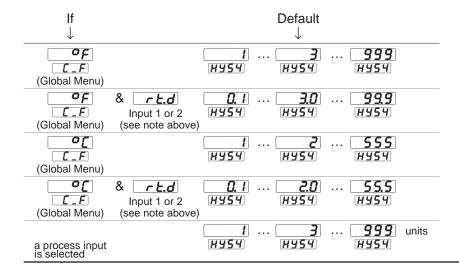
## HY54

#### **Hysteresis 4**

**Select the switching hysteresis for alarm 4.** This determines the change in temperature or process units needed to turn the output from off to on.

- If  $\boxed{\textit{RLY}}$  is set to  $\boxed{\textit{rRLE}}$  settings for  $\boxed{\textit{HY5Y}}$  will be in degrees per minute or units per minute.
- If the input referenced by  $\boxed{\textit{RLY}}$  is set to  $\boxed{\textit{rE.d}}$  the range is affected as listed below.

 $\boxed{\textit{HY5Y}}$  This prompt appears only on controllers equipped with output 4 hardware for a relay (98\_ -- \_ -- B\_ \_, 98\_ -- \_ -- D\_ \_ , 98\_ -- \_ -- E\_ or 98\_ -- \_ -- K\_ \_) or switched dc (98\_ -- \_ -- C\_ \_).

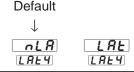


### LALY

### Latching 4

**Select whether alarm 4 will be latching or non-latching.** A latching alarm **LAE** must be turned off manually. A non-latching alarm **LAE** turns off when an alarm condition no longer exists.

NOTE: See <u>Chapter 7</u> for more information on alarms.  $\[ \underline{\textit{REY}} \]$  This prompt appears only on controllers equipped with output 4 hardware for a relay (98\_ -- \_ -- B\_ \_, 98\_ -- \_ -- J\_ \_ or 98\_ -- \_ -- K\_ \_) or switched dc (98\_ -- \_ -- C\_ \_). and with  $\[ \underline{\textit{DEY}} \]$  set to  $\[ \underline{\textit{RLY}} \]$  or  $\[ \underline{\textit{RLY}} \]$  or  $\[ \underline{\textit{RLY}} \]$ .





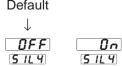
#### Silencing 4

Select silencing to inhibit alarm 4 on startup and to allow the operator to reset the alarm output, not the visual display.

NOTE: See Chapter 7 for more information on alarms.

• Silencing disables the alarm until the signal is between [AYL []] and RYH I.

| <b>5 !L 4</b> This prompt appears only on controllers equipped with output 4 |
|--|
| hardware for a relay (98 B, 98 D,  |
| 98 E_ or 98 K_ ) or switched dc (98 C_ )                                     |
| and with OFY set to ALY or ALY.  |
| Default  |





See Chapter 8 for

more information

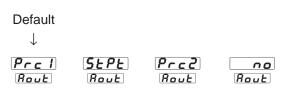
on retransmit.

### **Analog Output**

Select which value to retransmit as the output 3 signal.

- **Prc** 1 retransmits the process 1 value.
- **5***EPE* retransmits the set point.
- **Pre2** retransmits the process 2 value. This prompt appears only if the controller is equipped with input 2 hardware and if \[ \langle \langle \langle \] is not set to or **E** 12.
- turns off retransmit function.

**Rout** This prompt appears only on controllers equipped with retransmit hardware (98\_ -\_ \_ -**M**\_ \_ or 98\_ -- \_ \_ -**N**\_ \_ ).



NOTE:

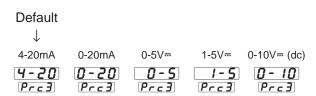
Setup Menus, Chapter 4



#### **Process 3**

#### Select the range for the retransmit signal at output 3.

Prc3 This prompt appears only on controllers equipped with retransmit hardware (98\_\_-\_\_-M\_\_\_ or 98\_\_-\_\_-N\_\_ ) and with Rout not set to Rout





#### **Retransmit Low Limit**

#### Select the low limit for the retransmit signal at output 3.

- The **default** value is equal to <u>rll</u> or <u>rll</u> (in the Input Menu) depending on whether <u>Rout</u> is set to <u>Prcl</u> or <u>Prcl</u>.
- The decimal precision of  $[R_{cl}]$  is determined by [det[l]] (Input Menu) if  $[R_{cul}]$  is set to  $[R_{cul}]$  or [SLPL]; it is determined by [det[l]] if  $[R_{cul}]$  is set to  $[R_{cul}]$ .

### NOTE:

See <u>Chapter 8</u> for more information on retransmit.



#### Retransmit High Limit

Select the high limit for the retransmit signal at output 3.

- The **default** value is equal to \( \( \cappa H \) \) or \( \cappa H \) (in the Input Menu) depending on whether **Rout** is set to **Prc!** or **Prc?**.
- The decimal precision of **ALAL** is determined by **GEL** (Input Menu) if (Rout) is set to (Prc) or (5tPt); it is determined by (dEC2) if (Rout) is set to Prc2.

hardware (98\_ -- \_\_ -M\_ \_\_ or 98\_ -- \_\_ -N\_ \_\_) and with **Rout** not set to no.



#### **Retransmit Calibration Offset**

Select an offset value for the retransmit signal at output 3.

• The decimal precision of **ALAL** is determined by **JELI** (Input Menu) if [Rout] is set to [Prc] or [StPt]; it is determined by [december E] if [Rout] is set to **Prc2**.

**REBL** This prompt appears only on controllers equipped with retransmit hardware (98\_ -\_ \_ -M\_ \_ or 98\_ -\_ \_ -N\_ \_) and with **Rout** not set to oo.

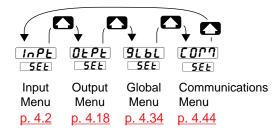
| If<br>↓                     | Default<br>↓                    |
|-----------------------------|---------------------------------|
| (Global Menu)               | -999 0 999<br>ACAL ACAL ACAL    |
| (Global Menu)               | -555 0 555<br>ACAL ACAL ACAL    |
| a process input is selected | -999 0 999 units RERL RERL RERL |

NOTE: See Chapter 8 for more information on retransmit.

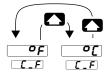
### Setup-Global

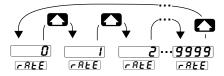
#### **Reaching the Global Menu**

• Begin in the Display Loop, and press the Up-arrow → and Downarrow → keys simultaneously for three seconds to reach the Setup Menus.



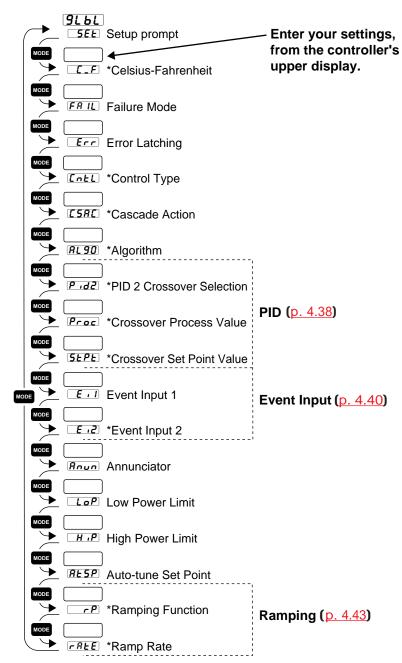
- **②** Press the Up-arrow key **△** to select one of the Setup Menus.
- 3 Press the Mode key MODE to step through the prompts.





**②** Press the Up-arrow key **△** or the Down-arrow key **√** to select one of the prompt values.

Figure 4.34 - Navigating the Global Menu.



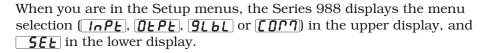
\*Prompts may not appear, depending on controller configuration.

#### **Global Prompts**

NOTE:

Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1

| JELI | and Decimal 2 | JELI | parameters in the Input Menu.



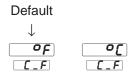
The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key of the Mode key



#### **Celsius-Fahrenheit**

Select which temperature scale the controller will use.

**[L\_F]** This prompt appears only on controllers with either Input 1 or Input 2 set to something other than a process input.





#### **Failure Mode**

Select the output level that the controller will maintain if an input fails.

 $\bullet$  Bumpless transfer  $\fbox{\textbf{bPL5}}$  maintains the same output settings after an input failure.

**FRIL** This prompt always appears.

| lf                         | Default      |                          |
|----------------------------|--------------|--------------------------|
| $\downarrow$               | $\downarrow$ |                          |
| a heat/cool<br>application | FR IL        | - 100 100 %<br>FRIL FRIL |
| a heat-only application    | FR IL        | FRIL FRIL                |
| a cool-only application    | FR IL        | - 100 0 %<br>FRIL FRIL   |

### Setup-Global

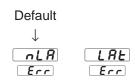


#### **Error Latching**

Select whether errors will be latching or non-latching.

- Non-latching alarms \[ \begin{aligned} \begi
- Latching alarms **LAE** must be turned off manually.

**Err** This prompt always appears.

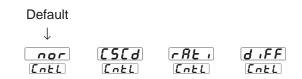




#### **Control Type**

Select a control method: normal  $\bigcap OC$ ; cascade [5]O; ratio  $\bigcap BC$ ; or differential OC;

**[\_n\_L\_]** This prompt appears only on controllers equipped with enhanced software (98\_B-\_\_\_-\_\_) and input 2 hardware for a basic thermocouple signal conditioner (98\_\_-1\_\_-\_\_) or a universal signal conditioner (98\_\_-2\_\_-\_\_) and with  $\boxed{r5P}$  set to  $\boxed{0FF}$ .



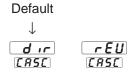


#### **Cascade Action**

Select the control action between the inner and outer loop of a cascade system.

- Direct action directly makes the percent output from the outer loop directly proportional to the set point of the inner loop (input 2). A 100% signal in the outer loop will set the inner loop to range high 2 red (Input Menu). A 0% signal in the outer loop will set the inner loop to range low 2 red ? (Input Menu).
- Reverse action **FEU** makes the percent output from the outer loop inversely proportional to the set point of the inner loop (input 2). A 100% signal in the outer loop will set the inner loop to range low 2 **FL2** (Input Menu). A 0% signal in the outer loop will set the inner loop to range high 2 **FH2** (Input Menu).

**[58]** This prompt appears only on controllers equipped with enhanced software (98\_B-\_\_\_-) and with **[nell**] set to **[5]**.



### Setup-Global

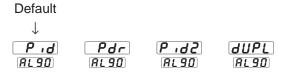


#### **Algorithm**

#### Select the control algorithm.

- P d selects one set of PID prompts.
- *Pdr* selects proportional/derivative control with manual reset in percent power.
- **P**,**d**? selects two complete sets of PID prompts. This selection does not appear if **[**,**b**] is set to **[**,**5**].
- **GUPL** selects duplex (heating and cooling) control. This prompt does not appear unless output 1 is a process output.

**RL90** This prompt appears only on controllers equipped with enhanced software (98\_B-\_\_\_-\_\_).



#### **PID 2 Crossover Selection**



Select which parameter determines the crossover from PID A to PID B: process  $P_{COC}$ ; set point 5EPE; or none COC.

[P, d2] This prompt appears only on controllers with [ALSO] set to [P, d2].



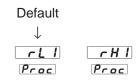


#### **Crossover Process Value**

Select the process value at which the control algorithm will crossover between PID A and PID B. PID A is active below this value and PID B is active above this value.

• This value cannot be set lower than range low 1 \_\_\_\_\_\_ or higher than range high 1 \_\_\_\_\_\_\_.

 $P_{roc}$  This prompt appears only on controllers with  $P_{roc}$  set to  $P_{roc}$ .





#### **Crossover Set Point Value**

Select the set point value at which the control algorithm will crossover between PID A and PID B. PID A is active below this value and PID B is active above this value.

• This value cannot be set lower than range low 1 **rel** or higher than range high 1 **rel**.

**5***EPE* This prompt appears only on controllers with  $P \cdot d2$  set to 5 EPE.



### Setup-Global



#### **Event Input 1**

Select the effect of closing the event input 1 switch.

- disables event input 1.
- LOE locks out the front panel keys.
- **AL** resets an alarm.
- R-P7 switches the controller to manual mode at the power level set at FRIL (Global Menu) and disables the Auto/Man key.
- **OFF** turns all control outputs off (de-energize relays).
- **P** , d switches from PID A to PID B.
- **Rctn** selects the opposite control action for output 1 and 2.
- **F5P** switches to a remote set point.
- *Id5P* switches to an idle or second set point.
- **E** . ! This prompt always appears.



| no LOC  | ALr         | <b>8-17</b> | OFF | Pid | Rctn | r 5P  | IdSP  |
|---------|-------------|-------------|-----|-----|------|-------|-------|
| EII EII | $E \cdot I$ | E , !       | Eil | Eil | Eil  | E , ! | E , ! |



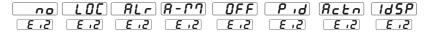
#### **Event Input 2**

**Select the effect of closing the event input 2 switch.** The selections are the same as for event input 1.

This prompt appears only on controllers equipped with hardware for a second event input (98\_ --5\_ -- \_ \_ ) and with \_\_\_\_\_\_\_ set to \_\_\_\_\_\_\_\_.





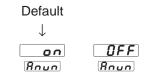




#### **Annunciator**

Select whether alarm messages will flash in the lower display.

**Anun** This prompt always appears.

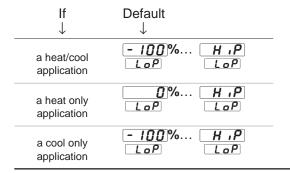




#### **Low Power Limit**

**Select the low limit for the percent output.** For cooling (direct acting) enter a negative number.

**LoP** This prompt always appears.



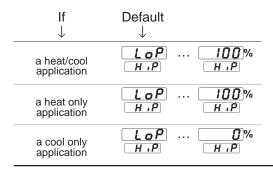
### Setup-Global



#### **High Power Limit**

**Select the high limit for the percent output.** For cooling (direct acting) enter a negative number.

**H** .**P** This prompt always appears.





#### **Auto-tune Set Point**

Select the percentage at which the controller will auto tune the current control set point.

**RESP** This prompt always appears.





#### **Ramping Function**

**Select when the controller will ramp.** Ramping limits the speed at which an element can heat up. Ramping is often used to protect parts that would crack or warp if they heat up too quickly.

- **OFF** sets the system to heat as quickly as possible.
- **5***E* sets the system to ramp only at startup.
- **[5***EPE*] sets the system to ramp at startup and whenever the set point changes.

 $\[ \] P$  This prompt appears only on controllers with  $\[ \] P$  (Input Menu) set to  $\[ \] P$  and with  $\[ \] P$  and with  $\[ \] P$  and with  $\[ \] P$  (Global Menu) not set to  $\[ \] P$  or  $\[ \] P$  or  $\[ \] P$ .





#### Ramp Rate

Select the ramping rate in degrees per minute.

```
Default
↓

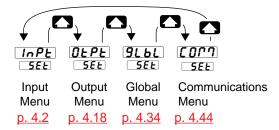
90 ... 100 ... 9999 °/min.

¬REE ¬REE ¬REE
```

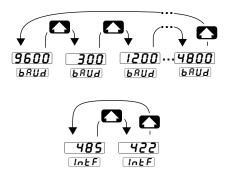
## Setup-Comm

#### **Reaching the Communications Menu**

● Begin in the Display Loop, and press the Up-arrow → and Downarrow → keys simultaneously for three seconds to reach the Setup Menus.

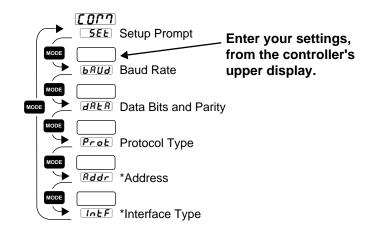


- **②** Press the Up-arrow key **△** to select one of the Setup Menus.
- **3** Press the Mode key MoDE to step through the prompts.



● Press the Up-arrow key or the Down-arrow key to select one of the prompt values.

Figure 4.44 - Navigating the Communications Menu.



\*Prompts may not appear, depending on controller configuration.

#### NOTE:

See Data Communications with the Series 988 Family of Controllers for detailed information on communications.

#### **Communications Prompts**

When you are in the Setup menus, the Series 988 displays the menu selection ([InPE], [IEPE], [IEPE]) or [IEPE]) in the upper display, and [IEPE] in the lower display.

The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key wood.



#### **Baud Rate**

#### Select the communications speed.

**BRUd** This prompt appears only on controllers equipped with communications hardware (98 $\_$ - $\_$ - $_$ - $_$ R $\_$ , 98 $\_$ - $\_$ - $_$ - $_$ U $\_$  or 98 $\_$ - $_$ - $\_$ - $_$ S $\_$ ).





#### **Data Bits and Parity**

Select the communications format (start bit = 1, stop bit = 1).

• Setting [Prob] to [Prob] automatically sets [dRbR] to [Bn].

 $\overline{\textit{GRER}}$  This prompt appears only on controllers equipped with communications hardware (98\_ -- \_ \_ -R\_ \_, 98\_ -- \_ \_ -U\_ or 98\_ -- \_ \_ -S\_ \_).



## Setup-Comm



## **Protocol Type**

Select the communications protocol.

- **FULL** selects ANSI X3.28 2.2 A.3.
- selects Xon/Xoff.
- **[7700**] selects Modbus

 $\begin{picture}(20,0) \put(0,0){\line(1,0){15}} \put(0,0$ 





### **Address**

**Select an address for the controller.** The computer will use this address when communicating with this controller.

**Rddr** This prompt appears only on controllers equipped with communications hardware for EIA/TIA-485 and EIA/TIA-422.

| If<br>↓    | Default<br>↓   |
|------------|----------------|
| <b>485</b> | Rddr Addr      |
| IntF       | Bddr Bddr      |
| [nef       | 8ddr 8ddr 8ddr |

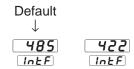


### **Interface Type**

Select the interface type for Output 4, Option S.

- **485** selects EIA/TIA-485.
- **422** selects EIA/TIA-422.

*In F* This prompt appears only on controllers equipped with communications hardware for EIA/TIA-485 and EIA/TIA-422 (98\_ -- \_ - \_ - \_ S\_ \_).

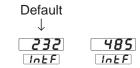




### **Interface Type**

Select the interface type for Output 4, Option U.

- **485** selects EIA/TIA-485.
- **232** selects EIA/TIA-232.



# **Chapter 5** The Operation Menus

### **Navigating the Operation Menus**

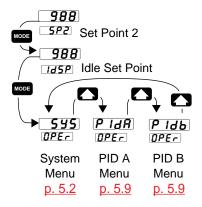
To reach the Operation Menus, begin in the Display Loop and press the Mode key open Depending on the controller configuration, either the Set Point 2 prompt 5P2, the Idle Set Point prompt 1d5P or the Operation Menu prompt 0PEr will appear in the lower display. The three Operation Menus are: System 5y5; PID A P.dR; and PID B P.db. Use the Mode key of to step past the Set Point 2 prompt 5P2 or the Idle Set Point prompt 1d5P, if they appear (see prompt information). Upon reaching the Operation Menu prompt 0PEr use the Up-arrow or Downarrow key to select a menu and the Mode key of to step through a menu.

NOTE:
Press the Display
key to return to
the Display Loop
from any point in
any menu.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 988 returns to the Operation Menu prompt <code>@PFr</code>. Use the Up-arrow and Down-arrow keys to select the next menu, or use the Mode key of to advance through the same menu again. To move backwards through the menu hold the Mode key of down and press the Up-arrow key. Use the Up-arrow or Down-arrow key to change the prompt setting.



• Begin in the Display Loop, and press the Mode key to reach the Set Point 2 prompt 5P2, the Idle Set Point prompt 1d5P or the Operation Menu 0PEr.





② Use the Mode key wood to step past the Set Point 2 prompt **5P2** or the Idle Set Point prompt **165P**, if they appear (see prompt information). Upon reaching the Operation Menu prompt **3PEr** use the Up-arrow key to select a menu.

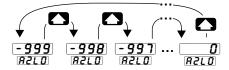
Figure 5.1 -Navigating the Operation Menus.

## **Operation-System**

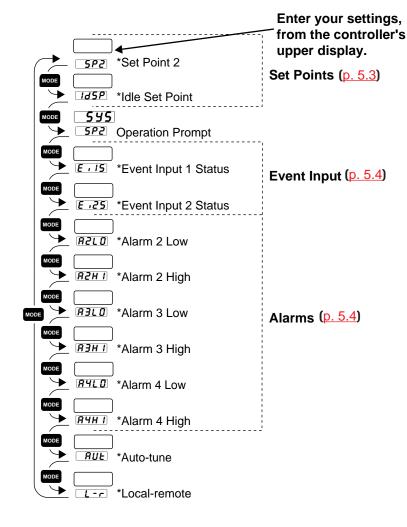
## **Reaching the System Menu**



• Select the System Menu, then press the Mode key Mode to step through the prompts.



◆ Press the Up-arrow key 
 to step
through the prompt values. The
Down-arrow key 
 backs through
the values.



\*Prompts may not appear, depending on controller configuration.

Figure 5.2 - The System Menu.

### **System Prompts**

### NOTE:

Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1

| JE[] and Decimal 2 | JE[] parameters in the Input Menu.

After you step past the Set Point 2 prompt  $\boxed{5P2}$  and the Idle Set Point prompt  $\boxed{1d5P}$  to the Operation menus, the Series 988 displays the menu selection ( $\boxed{595}$ ,  $\boxed{P \cdot dR}$  or  $\boxed{P \cdot db}$ ) in the upper display and  $\boxed{QPEr}$  in the lower display.

The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key.



### **Set Point 2**

**Select a second set point that will activate output 2.** This allows you to boost the heating or cooling action of the output 1 device.

• The **range and default settings** depend on the **[n]**, **[r]** and **[r]** settings (Input Menu).

**SP2** This prompt appears only if  $\boxed{0 + 1}$  and  $\boxed{0 + 2}$  (Output Menu) are both set to  $\boxed{1 + 1}$  or  $\boxed{1 + 1}$ .

| r <u>L</u> I | <br>r H I |
|--------------|-----------|
| <i>5P2</i>   | 592       |



### **Idle Set Point**

**Select the set point to be activated by an event input.** This allows you to select a temperature that will be maintained when the application is idle.

[1d5P] This prompt appears only if [E,I] or [E,G] (Global Menu) is set to [1d5P].

| rL1  | <br>rH! |
|------|---------|
| IdSP | 1858    |

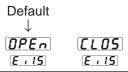
## **Operation-System**

# E , 15

### **Event Input 1 Status**

Indicates whether the event input 1 circuit is open or closed (read only).

[E, 15] This prompt appears only if [E, 1] (Global Menu) is set to something other than [no].

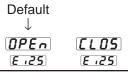


# E ,25

### **Event Input 2 Status**

Indicates whether the event input 2 circuit is open or closed (read only).

**E** .25 This prompt appears only on controllers equipped with a second digital event input  $(98\_--5\_--\_)$  and with **E** .2 (Global Menu) set to something other than **E** .2.

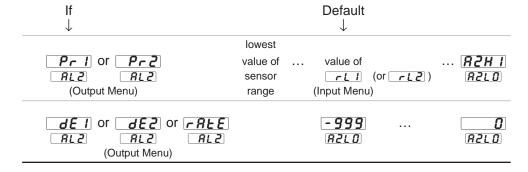


## R2L0

### Alarm 2 Low

Select the low trigger value for the output 2 alarm.

 $\boxed{\textbf{R2L0}}$  This prompt appears only if  $\boxed{\textbf{RL2}}$  (Output Menu) is set to something other than  $\boxed{\textbf{no}}$ .

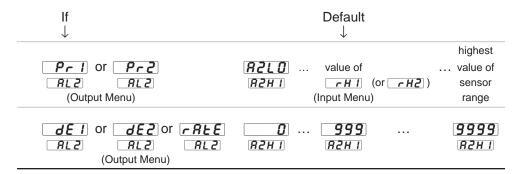




### Alarm 2 High

### Select the high trigger value for the output 2 alarm.

 $\boxed{\textbf{\textit{R2H I}}}$  This prompt appears only if  $\boxed{\textbf{\textit{RL2}}}$  (Output Menu) is set to something other than  $\boxed{\textbf{\textit{ng}}}$ .

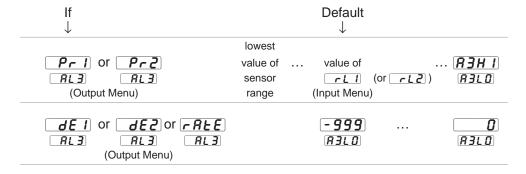




### Alarm 3 Low

### Select the low trigger value for the output 3 alarm.

 $\boxed{\textbf{R3L0}}$  This prompt appears only if  $\boxed{\textbf{RL3}}$  (Output Menu) is set to something other than  $\boxed{\textbf{no}}$ .



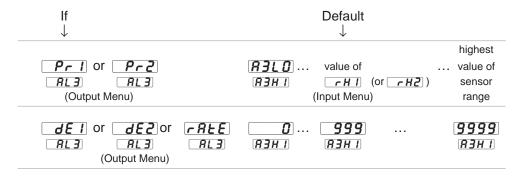
## Operation-System



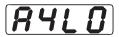
### Alarm 3 High

### Select the high trigger value for the output 3 alarm.

[R3HI] This prompt appears only if [RL3] (Output Menu) is set to something other than [RO].



### Alarm 4 Low



### Select the low trigger value for the output 4 alarm.

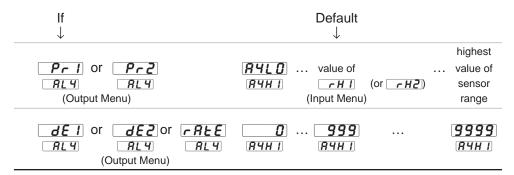
| IT                 | L          | Default       |              |
|--------------------|------------|---------------|--------------|
|                    |            | $\downarrow$  |              |
|                    | lowest     |               |              |
| Pr! or Pr2         | value of v | alue of       | <b>AYH</b> 1 |
| ALY ALY            | sensor     | rL 1 (or rL2) | A4L0         |
| (Output Menu)      | range (Inp | out Menu)     |              |
|                    |            |               |              |
| dE I or dE2 or rAE | <u> </u>   | · 999         |              |
| ALY ALY AL         | 1          | A4L0          | A4L0         |
| (Output Menu)      |            |               |              |



### Alarm 4 High

Select the high trigger value for the output 4 alarm.

 $\boxed{\textbf{RYH I}}$  This prompt appears only if  $\boxed{\textbf{RL Y}}$  (Output Menu) is set to something other than  $\boxed{\textbf{no}}$ .





### **Auto-tune**

### Initiate an auto-tune.

P ,db appears only on controllers with enhanced software (98\_B-\_\_\_-\_ and with RL 90 (Global Menu) set to P ,d2 or c5cd.

**RUE** This prompt always appears.

NOTE: For more information on auto-tune see Chapter 7.

| Default<br>↓ |      |      |
|--------------|------|------|
| OFF          | P.dA | Pidb |
| AUL          | AUL  | RUE  |

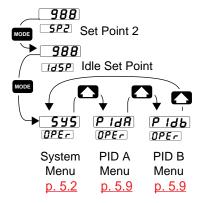
# Operation-System



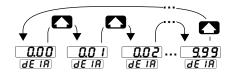
| <b>Select a local or remote set point.</b> With selected the controller displays the remote set point rather than the internal (local) set point, and the set point cannot be changed with the Up-arrow or Down-arrow key. |
|--|
| L-r This prompt appears only if r5P (Input Menu) is set to n.  |
| Default<br>↓   |
|  |

### Reaching the PID Menus

• Begin in the Display Loop, and press the Mode key to reach the Set Point 2 prompt 5P2, the Idle Set Point prompt 165P or the System Menu 545.

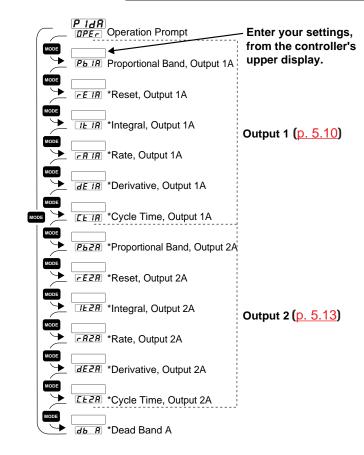


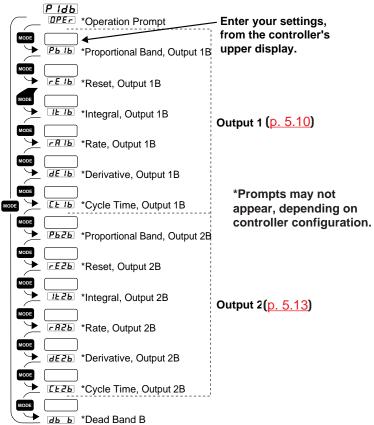
- ② Use Mode key MoDE to step past the Set Point 2 prompt 5P2 and the Idle Set Point prompt 1d5P, if they appear (see prompt information). Upon reaching the Operation Menu prompt 1PEr use the Uparrow key to select a menu.
- **3** Press the Mode key Mode to step through the prompts.



● Press the Up-arrow key ▲ to step through the prompt values. The Down-arrow key ▶ backs through the values.

Figure 5.9 -The PID Menus.





### **PID A or PID B Prompts**

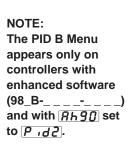
NOTE:

After you step past the Set Point 2 prompt  $\boxed{5P2}$  and the Idle Set Point prompt  $\boxed{1d5P}$  to the Operation menus, the Series 988 displays the menu selection ( $\boxed{595}$ ,  $\boxed{P \cdot dR}$  or  $\boxed{P \cdot db}$ ) in the upper display and  $\boxed{DPEr}$  in the lower display.

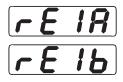
The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key woos.

### **Proportional Band, Output 1A or 1B**

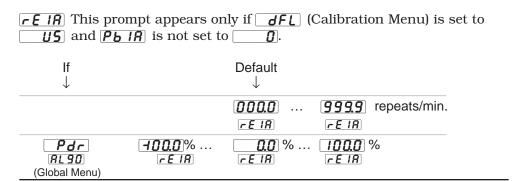
**Pb** IR This prompt always appears.

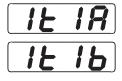


| lf<br>↓   | Default<br>↓                                     |
|---|--|
| U5 & OF  dFL C_F  (Calibration Menu) (Global Menu)    |  |
| & <b>r Ł.d</b><br>Input 1 or 2<br>(Input Menu)        | <u>0.0</u> <u>25</u> <u>999.9</u><br>Рыя Рыя Рыя |
| U5 & C<br>dFL Calibration Menu) (Global Menu)         | <u> </u>   |
| & <b>r Ł.d</b><br>Input 1 or 2<br>(Input Menu)        |  |
| SI & P.d2  GFL RL90  (Calibration Menu) (Global Menu) |  |



### Reset, Output 1A or 1B

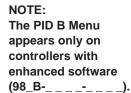




### Integral, Output 1A or 1B

Tune integral to eliminate the offset or droop between the set point and the actual process temperature for PID output 1. When set to integral is disabled.

| IE IR This prompt appears only if         | <b>GFL</b> (Calibration Menu) is set to |
|---|---|
| <b>5</b> I and <b>Pb</b> IR is not set to | <b>0</b> .                              |



| Default<br>↓ |                |              |
|--------------|----------------|--------------|
| <b>0.00</b>  | . <i>99.99</i> | min. / repea |
| IE IR        | IL IA          |              |



### Rate, Output 1A or 1B

| Adjust the rate to eliminate overshoot on startup or after the set point changes. The rate setting will not influence the percent power if the process temperature is more than twice the proportional band from the set |
|--|
| point. When set to rate is disabled.   |
| This prompt appears only if JFL (Calibration Menu) is set to J5 and Pb IR is set higher than D.  |
| Default<br>↓   |
| 0.00 9.99 min.   |

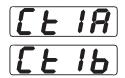


### Derivative, Output 1A or 1B

5 1 and Pb 18 is set higher than  $\boxed{0}$ .

| Adjust the derivative to eliminate overshoot on startup or after the   |
|--|
| <b>set point changes.</b> The derivative setting will not influence the percent  |
| power if the process temperature is more than twice the proportional band from the set point. When set to $\bigcirc$ derivative is disabled. |
| dEIR This prompt appears only if $dFL$ (Calibration Menu) is set to  |

| Default<br>↓ |                   |
|--------------|-------------------|
| 0.00         | . <b>999</b> min. |
| dE 18        | dE 18             |



### Cycle Time, Output 1A or 1B

Select the time, in seconds, of a complete on/off cycle.

[FIR] This prompt appears only if In I (Input Menu) is not set to a process, [Intl (Global Menu) is not set to [ISL d] and [Pb IR] is set higher than [I].

| If<br>↓   |       | Default<br>↓                             |
|---|-------|--|
| mechanical<br>relay<br>outputs                    |       | 5.0 10.0 999.9 min.<br>CE IR CE IR CE IR |
| open collector<br>or solid-state<br>relay outputs | EE IR | (CE IR) (CE IR) (S99.9) min.             |



### **Proportional Band, Output 2A or 2B**

Pb2R This prompt appears only if [nt] (Global Menu) is not set to [5[d] and if [nt] (Output Menu) is set to [nt] or if [nt] or if [nt] (Global Menu) is set to [nt] (Global Menu) is not set to [nt] (Global Menu) (

| If<br>J  | Default<br>↓   |
|--|--|
| US & OF  GFL  (Calibration Menu) (Global Menu) | 8 <u>25</u> <u>9999</u><br>Pb2R Pb2R Pb2R                      |
| & <b>r Ł.d</b> Input 1 or 2 (Input Menu)       | 0.0 25 999.9<br>P628 P628 P628                                 |
| U5 & C<br>dFL (Calibration Menu) (Global Menu) | 0 149999<br>P628 P628 P628                                     |
| & <b>r.t.d</b> Input 1 or 2 (Input Menu)       | 0.0 14 999.9<br>P628 P628 P628                                 |
| S I  GFL  (Calibration Menu)                   | <u>0.0</u> <u>3.0</u> <u>999.9</u> % of span<br>Рьгя Рьгя Рьгя |



### Reset, Output 2A or 2B

Tune reset to eliminate the offset or droop between the set point and the actual process temperature for PID A output 2. When set to reset is disabled.

This prompt appears only ifJFL(Calibration Menu) is set toUSand [Pb2R] is set higher than[0].

| If<br>↓                      |                        | Default<br>↓ |                  |              |
|------------------------------|------------------------|--------------|------------------|--------------|
|                              |                        | 000.0        | 999.9<br>r E 2 R | repeats/min. |
| Pdr<br>RL90<br>(Global Menu) | <b>⊣00.0</b> %<br>₽€28 | <u>0.0</u> % | 100.0 %          | 0            |



### Integral, Output 2A or 2B

Tune integral to eliminate the offset or droop between the set point and the actual process temperature for PID output 2. When set to integral is disabled.

| IE 2R This            | prompt appears only if _dFL (Calibration Menu) is set to |
|-----------------------|--|
| <b>5</b> <i>1</i> and | $Pb2R$ is set higher than $\square$ .                    |
| Default               |  |



## Rate, Output 2

| Adjust the rate to eliminate overshoot on startup or after the set point changes. The rate setting will not influence the percent power if the process temperature is more than twice the proportional band from the set point. When set to |
|---|
| This prompt appears only if JFL (Calibration Menu) is set to JS and Pb2R is set higher than D.  |
| Default<br>↓  |
|   |



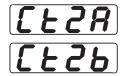
### **Derivative, Output 2A or 2B**

**0.00** ... **9.99** min.

9E58

9E58

| Adjust the derivative to eliminate overshoot on startup or after the set point changes. The derivative setting will not influence the percent power if the process temperature is more than twice the proportional band from the set point. When set to derivative is disabled. |
|---|
| <u>dE2R</u> This prompt appears only if <u>dFL</u> (Calibration Menu) is set to <u>SI</u> and <u>Pb2R</u> is set higher than <u>□</u> .   |
| Default<br>↓  |

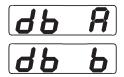


### Cycle Time, Output 2A or 2B

Select the time, in seconds, of a complete on/off cycle.

 $\boxed{\textbf{LEAR}}$  This prompt appears only if  $\boxed{\textbf{LnEL}}$  (Global Menu) is not set to  $\boxed{\textbf{CSLA}}$  and  $\boxed{\textbf{PbAR}}$  is set higher than  $\boxed{\textbf{D}}$ .

| If<br>↓   |                       | Default $\downarrow$             |
|---|-----------------------|----------------------------------|
| mechanical<br>relay<br>outputs                    |                       | 5.0 10.0 999.9<br>CE28 CE28 CE28 |
| open collector<br>or solid-state<br>relay outputs | br <b>5</b> Ł<br>CŁ2A | 0.1 10 9999<br>CE28 CE28         |



### **Dead Band A or B**

**Select the width of the zone between the action of the heating output and the cooling output.** If you select a positive value the heat and cool outputs cannot be energized at the same time. If you select a negative value, both outputs can be energized at the same time.

NOTE: The PID B Menu appears only on controllers with enhanced software (98\_B-\_\_\_-). **J** This prompt appears only if **P E R** is set higher than **D** and one output performs heating action and the other performs cooling action.

| If<br>↓                     | Default<br>↓                 |
|-----------------------------|------------------------------|
| (Global Menu)               | -999 0 999<br>db 8 db 8 db 8 |
| (Global Menu)               | -555 0 555<br>db R db R db R |
| a process input is selected | -999 0 999 units             |

# **Chapter 6** The Factory Menus

### **Navigating the Factory Menus**

#### NOTE:

The Factory Menus will not appear if the hardware lockout DIP is set to on.
See Chapter 1 for more information.

#### NOTE:

The Factory Menus can only be entered when the setup prompt <u>5EL</u> is displayed.

### NOTE:

Press the Display key to return to the Display Loop from any point in any menu.

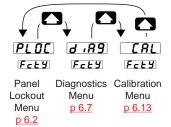


To reach the Factory Menus, begin in the Display Loop and press the Uparrow and Down-arrow keys together and hold for three seconds. The **5**ft prompt will appear in the lower display. Press and hold the Up-arrow and Down-arrow keys together again for three seconds until the **Fcty** prompt appears in the lower display. The Factory Menus will not appear if the hardware lockout DIP is set to on. (See **Chapter 1** for more information on DIP switch settings.) The three Factory Menus are: Panel Lockout **PLOC**; Diagnostics **d.R9**; and Calibration **CRL**. Upon reaching the Factory Menu prompt **Fcty** use the Up-arrow or Down-arrow key to select a menu and the Mode key to step through a menu.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 988 returns to the Factory Menu prompt **Fcty**. Use the Up-arrow and Down-arrow keys to select the next menu, or use the Mode key for advance through the same menu again. To move backwards through the menu hold down the Mode key for and press the Up-arrow key. Use the Up-arrow for Down-arrow key to change the prompt setting.



• Press the Up-arrow ▲ and Down-arrow ▶ keys together and hold until the ►5EE prompt appears in the lower display. Press and hold again until the ►cEY prompt appears in the lower display.





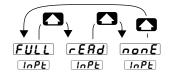
**②** Use the Up-arrow key **(** to select one of the Factory Menus.

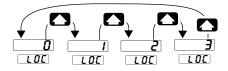
## Factory-Panel Lockout

# Reaching the Panel Lockout Menu

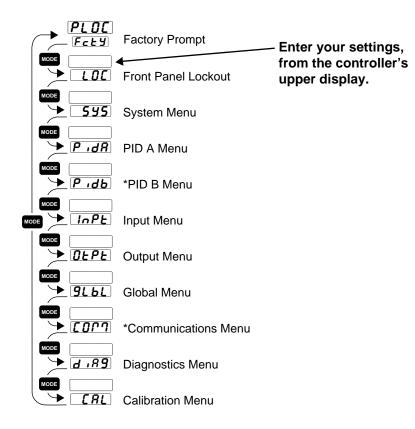


**③** Select the Panel Lockout Menu, then press the Mode key MoDE to step through the prompts.





● Press the Up-arrow key or the Down-arrow key to select one of the prompt values.



\*Prompts may not appear, depending on controller configuration.

Figure 6.2 -The Panel Lockout Menu.

### **Panel Lockout Prompts**

When you are in the Factory menus, the Series 988 displays the menu selection (PLDL, JRS or LRL) in the upper display and FLS in the lower display.

The Up-arrow or Down-arrow key selects another menu. Press the Mode key to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key ...

### **Front Panel Lockout**



CAUTION:
Setting LOC to
Z or 3
disables the

disables the
Auto/Man key AUTO
and will force the
controller into manual mode if an open
sensor occurs.
Verify that the controller is operating
in the desired mode
(auto or manual)
before setting the
lockout level.
Failure to do so
could result in damage to equipment
and or property.

**Sets the Lockout level for the Front Panel.** This allows you to disable keys on the front of the controller.

- 🔃 🛭 enables all keys.
- disables the Mode key MODE.
- disables the Mode key MODE and the Auto/Man key AUTO and the Auto/Man key
- disables the Mode key wore and the Auto/Man key and locks the set point value.
- **LOC** This prompt always appears.



LOC





## Factory-Panel Lockout

The prompts within the Panel Lockout Menu allow you to lockout an entire menu. You can set the level of lockout to none  $\boxed{nonE}$ , read only  $\boxed{rERd}$ , or lockout read and write  $\boxed{FULL}$ .

# 545

### System Menu

**Select the lockout level for the System Menu.** Set the System Menu lockout to no lockout  $\boxed{rest}$ , read only  $\boxed{rest}$  or full lockout  $\boxed{rull}$ .

**LOC** This prompt always appears.

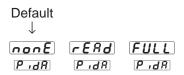




### PID A Menu

**Select the lockout level for the PID A Menu.** Set the PID A Menu lockout to no lockout [FULL].

**P** IdR This prompt always appears.

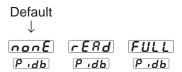




### PID B Menu

**Select the lockout level for the PID B Menu.** Set the PID B Menu lockout to no lockout  $\boxed{rest}$ , read only  $\boxed{rest}$  or full lockout  $\boxed{rest}$ .

P .db This prompt appears only on controllers with enhanced software (98\_B-\_\_\_-) and with [RL 90] (Global Menu) set to [P .d2] or [LnEL] (Global Menu) set to [L5Ld].





### **Input Menu**

Select the lockout level for the Input Menu. Set the Input Menu lockout to no lockout  $\boxed{rend}$ , read only  $\boxed{rend}$  or full lockout  $\boxed{FULL}$ .

**InP**E This prompt always appears.

```
Default

\[
\begin{align*}
\cone & \co
```



### **Output Menu**

Select the lockout level for the Output Menu. Set the Output Menu lockout to no lockout [FULL].

**DEPE** This prompt always appears.





### **Global Menu**

Select the lockout level for the Global Menu. Set the Global Menu lockout to no lockout  $\boxed{rest}$ , read only  $\boxed{rest}$  or full lockout  $\boxed{FULL}$ .

**9L** bL This prompt always appears.

```
Default

↓

nonE rERd FULL

9LbL 9LbL 9LbL
```

## Factory-Panel Lockout



### **Communications Menu**

Select the lockout level for the Communications Menu. Set the Communications Menu lockout to no lockout  $\boxed{rest}$ , read only  $\boxed{rest}$  or full lockout  $\boxed{FULL}$ .

[ [ ] This prompt appears only on controllers equipped with Communications hardware (98\_ -\_ \_\_-R\_ or 98\_ -\_ \_\_-S\_ ).

### Default ↓

none read full

### **Diagnostics Menu**



Select the lockout level for the Diagnostics Menu. Set the Diagnostics Menu lockout to no lockout  $\boxed{rest}$ , read only  $\boxed{rest}$  or full lockout  $\boxed{FULL}$ .

**d** . R **9** This prompt always appears.

### Default

v nonE rEAd FULL d.89 d.89 d.89

### **Calibration Menu**



**Select the lockout level for the Calibration Menu.** Set the Calibration Menu lockout to no lockout **Goal**, read only **FBB** or full lockout **FULL**.

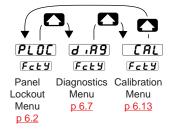
**[FL]** This prompt always appears.

### Default

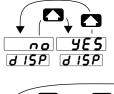
→
nonE read Full
cal cal cal

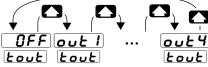
### **Reaching the Diagnostics Menu**

• Press the Up-arrow • and Down-arrow keys together and hold until the **5**EE prompt appears in the lower display. Press and hold again until the **F**cEY prompt appears in the lower display.



- ② Use the Up-arrow key to step from the Panel Lockout Menu PLOC to the Diagnostics Menu J.89.
- **3** Press the Mode key **MODE** to step through the prompts.





● Press the Up-arrow key or the Down-arrow key to select one of the prompt values.

In the Diagnostics Menu only the values of  $\boxed{\textbf{d} \ \textbf{15P}}$ ,  $\boxed{\textbf{Loub}}$  and  $\boxed{\textbf{DPLP}}$  can be changed.

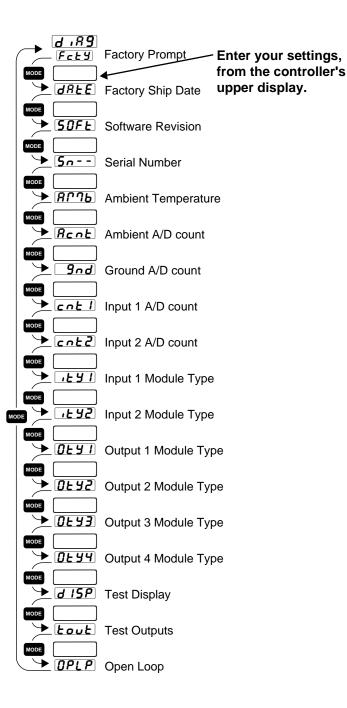


Figure 6.7 - The Diagnostics Menu.



### **Factory Ship Date**

Shows the date that the final factory control test was performed. The first two digits represent the week as numbered from [0.1-] to [5.2-]. The second two digits represent the year [-94], [-95], etc...

**GREE** This prompt always appears.



### **Software Revision**

Shows the controller's software revision code when set to years. This letter should match the software revision code on the cover of the manual that came with your controller; n and W988-XUMN Rev N00.

**50F** This prompt always appears.



### **Serial Number**

**Shows the controller's serial number.** The first two letters in the upper display are to indicate that the controller is in serial number mode. The right half of the upper display shows the first two digits of the serial number. The lower display shows the last four digits of the serial number.

5678

This is what the controller with the serial number 0988<u>345678</u> would display.

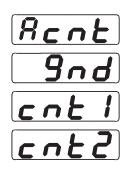
**5**<sub>n</sub> - - This prompt always appears.



## **Ambient Temperature**

**Shows the ambient temperature at the Input 1 terminals.** The temperature is shown in °F in the form  $\boxed{0000}$  regardless of the settings of  $\boxed{0000}$ ,  $\boxed{0000}$ ,  $\boxed{0000}$ ,  $\boxed{0000}$ ,  $\boxed{00000}$ ,  $\boxed{00000}$ ,  $\boxed{00000}$ ,  $\boxed{00000}$ ,  $\boxed{00000}$ ,  $\boxed{000000}$ ,  $\boxed{000000}$ 

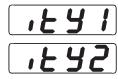
**AP76** This prompt always appears.



### **Factory Use Only**

These prompts are used only at the factory.

**Acnt 9nd cnt 1 cnt 2** These prompts always appear.



### Inputs 1 and 2 Module Types

**Displays which input module is installed in the controller.** Please document this value before contacting the factory for technical assistance.

### Input Types

- nonE No input module
- Thermocouple only module
- [urrent detect
- **5L** Is Slidewire module
- **UDFF** Universal off
- Urtd Universal rtd
- **Utch** Universal high-gain thermocouple
- \*\*Ubcl\* Universal low-gain thermocouple
- **บกา**บ Universal millivolts
- [UPrc] Universal process
- **Event** input 2

These prompts always appear.



### Outputs 1, 2, 3 and 4 Module Types

**Display the controller's output module.** Please document this value before contacting the factory for technical assistance.

### **Output Types**

- nonE no output module (A)
- **55** 0.5A solid-state relay (K)
- **55** 15 0.5A solid-state relay with suppression (B)
- dc switched dc open collector (C)
- rlyc form C relay (E)
- relay with suppression (D)
- relay A/B (J)
- **Proc** process output (F)
- Ur Et voltage/retransmit (N)
- Ir Et current/retransmit (M)
- **5PL y** power supply (T)
- EIA/TIA-232 communications (R)
- **485** EIA/TIA-485 or EIA/TIA-422 communications (S)
- Z32 EIA/TIA-232 or EIA/TIA-485 communications (U)

**OEY! OEY3 OEY4** These prompts always appear.

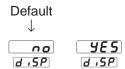


### **Test Displays**

Runs a brief test of the controller's displays and LEDs. To run the test, scroll through the Diagnostics Menu until **[J.5P]** is shown in the lower display. Use the Up-arrow key or Down-arrow key to select **YE5** from the upper display and press the mode key **YE5**.

The controller will run pattern tests, blink all the LEDs on and off, and end with the model number in both displays.

**d.5P** This prompt always appears.





### **Test Outputs**

This prompt tests each output. To run the test, scroll through the Diagnostics Menu until <code>Loub</code> is shown in the lower display. Use the Uparrow key or Down-arrow key to select an output <code>oub!</code>, <code>oub!</code>, <code>oub!</code>, <code>oub!</code>, <code>oub!</code>, or <code>oub!</code>. The LED for that output should light after a second or two indicating that the output has been successfully energized. Do not press the mode key <code>oub!</code> to activate the test; it starts automatically when anything other than <code>OFF</code> is selected.

If any of the LEDs fail to light contact the factory.

This prompt always appears.





### **Open Loop**

Checks the control loop, consisting of the controller output, power control, heater and sensor. With open loop enabled, the controller monitors the output power level and checks for a change in the process input value. If the output power is at maximum for a period of time equal to the reset time and the process input has not changed by at least  $\pm 5^{\circ}$ F, the controller will switch to manual mode at 0% output power and  $\boxed{DPLP}$  will be displayed in the lower display.

To clear this error, enter the Setup Menu and press the display key of the Company to get back into auto mode, press the Auto/Man key MAN.

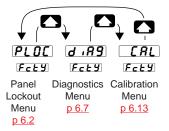
**OPLP** This prompt always appears.



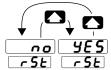
## **Factory-Calibration**

# Reaching the Calibration Menu

- Begin in the Display Loop, and press the Up-arrow → and Downarrow → key simultaneously for six seconds until the Setup Menu → 5EE, then the Factory Menu ← Factory Menu
- ② Use the Up-arrow key ▲ or Downarrow key ▼ to step through the Factory Menu to the Calibration Menu ▼ FRL .



• Press the Mode key wore to step through the prompts.



● Press the Up-arrow key or the Down-arrow key to select one of the prompt values.

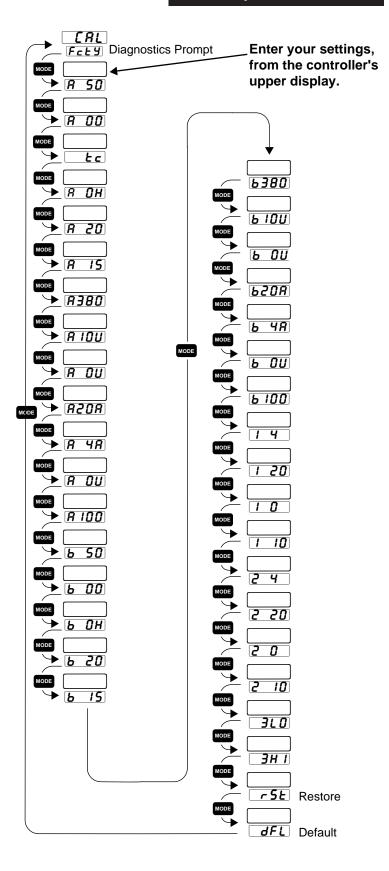
Refer to *Calibrating Watlow Process Controls* for information about the Calibration Menu.



### **CAUTION:**

Before attempting to calibrate, make sure you have the proper equipment called for in each procedure. The Series 988 is calibrated and tested before it leaves the factory. Attempting to calibrate the controller without the proper equipment could result in damage to property and/or equipment.

Figure 6.13 - The Calibration Menu.



## Factory-Calibration



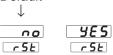
### Restore

**Restores the original factory calibration values when set to YE5**. This is a simple way to recover from a mistake made while calibrating the controller.

**r 5** E This prompt always appears.

Default

↓





## **Default**

Set the operating parameter defaults to domestic or international measures.

- <u>**#5**</u> (domestic) sets the controller to °F; rate in minutes; proportional band in degrees or units; and reset in repeats per minute.
- **5** *I* (international) sets the controller to °C; derivative in minutes; proportional band in percent of span; and integral in minutes per repeat.

**GFL** This prompt always appears.

US SI

# **Chapter 7** Tuning, Manual Operation, Alarms and Error Codes

### **Auto-tuning (Heat and/or Cool)**

The Series 988 can automatically tune the PID parameters to fit the characteristics of your particular thermal system.

Standard software units (98\_  $\underline{\mathbf{A}}$  -\_\_\_\_\_) have 1 set of PID parameters. Units with enhanced software (98\_  $\underline{\mathbf{B}}$  -\_\_\_\_\_\_) and  $\boxed{\textbf{RLSO}}$  set to  $\boxed{\textbf{P.d2}}$  (Global Menu) have two sets of PID parameters, PID A and PID B. Only one PID set can be auto-tuned at a time. For information on tuning a cascade system, see  $\underline{\mathbf{Chapter 8}}$ .

Before beginning the auto-tune sequence, make sure the **RESP** parameter located in the Global Menu is at the proper setting. This allows the user to select the tuning set point as a percentage of the current control set point. See Chapter 4 for more information on this parameter. The figure below uses the default setting, 90%, to define the auto-tuning process.

Once the auto-tune sequence has begun, the output 1 and output 2 proportional band is set to 0 and the control goes into an on/off mode of control at the set point percentage determined by the **RESP** parameter. The displayed set point remains unchanged.

### NOTE:

A useful reference on tuning is *Tuning* of *Industrial Control Systems* by Armando B. Corripio, published by the Instrument Society of America.

### NOTE:

### NOTE:

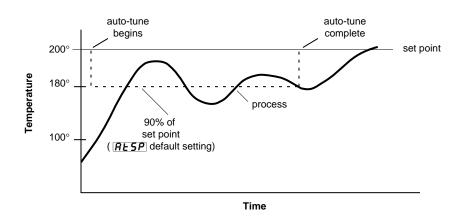
For information about tuning a cascade system, see Chapter 9.

### NOTE:

Before attempting to auto-tune a cascade system, see Cascade Setup in Chapter 9.

Figure 7.1 - Auto-tuning example.

### Auto-tuning at a set point of 200°F



## Tunina

If a mechanical relay or contactor is switching power to the load, a longer cycle time may be desirable to minimize wear on the mechanical components. The typical life of a mechanical relav is 100.000 cycles. Verify that the cycle time selected is appropriate for the output device type. Failure to do so could result in damage to equipment and/or property.

When the control finishes "learning" the system, it resumes standard PID control using the PID values established by the auto-tuning process. Changing the set point during an auto-tune restarts the auto-tune procedure.

During auto-tuning the process must cross the set point four times within an 80-minute time span for the Series 988 to successfully complete the auto-tune. If this does not happen within the 80-minute time limit, the Series 988 chooses PID values based on the 80-minute tuning cycle per-

### To start auto-tuning:

- 1. **Press the Mode key** Mode to advance to the System Menu 545. Press the Mode key to advance through the menu until the **AUE** prompt appears in the lower display.
- 2. Use the Up-arrow  $\bigcirc$  or Down-arrow  $\bigcirc$  key to select  $\bigcirc$  or  $\bigcirc$  or if your controller is equipped with enhanced software (98 $\underline{\mathbf{B}}$ -\_\_\_\_). Only one PID set can be auto-tuned at a time.
- 3. Press the Display key DISPLAY. While the control is in the tuning mode the lower display alternates every second between the normal information and the  $\boldsymbol{\xi}_{\boldsymbol{u}\boldsymbol{n}}\boldsymbol{\xi}$  prompt.
- **4. When tuning is complete,** the displays return to their previous state and **RUE** reverts to **OFF**. The Series 988 installs the PID tuning parameters it has calculated and saves them in non-volatile memory.

**To abort auto-tuning** either reset the **RUE** prompt to off, press the Auto/Man key we twice, or cycle power off and on. In all cases, aborting auto-tune restores all values to their state before auto-tuning began.

## **Manual Tuning**

For optimum control performance, tune the Series 988 to your thermal system. The tuning settings here are for a broad spectrum of applications; your system may have somewhat different requirements. NOTE: This is a slow procedure that may take hours to obtain optimum values.

Tune heating outputs at a set point above the ambient process value. Tune cooling outputs at a set point below the ambient process value.

If your controller is equipped with enhanced software (98\_B-\_\_\_-\_ \_), the P ,db parameters may need to be tuned also. Perform this procedure on both PID sets, they are functionally identical. The parameters within the procedure apply to both output 1 and 2, and PID A and B.

Tuning

| 1. | Apply power to the Series 988 and enter a set point. Begin with  Pb set to I; FE or Ib set to OOO; FR or dE  set to OOO; FB set to SOO; CRL set to OFF.   |
|----|---|
| 2. | <b>Proportional Band Adjustment:</b> Gradually increase Pb until the upper display process value stabilizes at a constant value. The process value will not be right on set point because the initial reset value is 0.00 repeats per minute. (If Pb is set to D then F, IE, F and B are inoperative, and the Series 988 functions as a simple on/off control.) The HY5 prompt determines the switching differential value.             |
| 3. | <b>Reset/Integral Adjustment:</b> Gradually increase $\[ \] F \]$ or $\[ \] I \]$ until the upper display process value begins to oscillate or "hunt." Then slowly decrease $\[ \] F \]$ or $\[ \] I \]$ until the upper display stabilizes again near set point.   |
| 4. | <b>Cycle Time Adjustment:</b> Set $\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $  |
| 5. | <b>Rate/Derivative Adjustment:</b> Increase $\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$   |
|    | Raise the set point by 20° to 30°F, or 11° to 17°C and watch the approach to the new set point. If you increase $\boxed{\textit{rR}}$ or $\boxed{\textit{dE}}$ too much, the approach to set point will be very sluggish. Repeat as necessary until the system rises to the new set point without overshooting or approaching the set point too slowly.   |
| 6. | <b>Calibration Offset Adjustment:</b> You may want your system to control to a process value other than the value coming from the input sensor. If so, measure the difference between that process value (perhaps at another point in the system) and the process value showing in the upper display. Then enter the <b>TRL</b> offset value you want. Calibration offset adds or subtracts degrees from the value of the input signal. |

### **Manual and Automatic Operation**

To change from auto to manual operation, press the Auto/Man key wice.

NOTE: When a sensor opens, the controller switches from automatic to manual operation. The Auto/Man LED (located on the Auto/Man key (MAN) indicates whether the controller is in automatic or manual operation. When the LED is lit, the control is in manual operation. When the LED is off, it is in automatic operation. When the LED flashes, press the key again within five seconds to complete the change in operation.

• If **FRIL** is set to **bPL5** and the process has stabilized at a power level less than 75% (±5%) for a two-minute period prior to the sensor break, then the Series 988 switches to manual operation at the last automatic power level. If these conditions are not met, the output goes to 0% power (output disabled).

When transferring from automatic to manual operation, the control output, or outputs, remain stable — a bumpless, or smooth, transition. The lower display changes from the set point to the % output value.

• If **FRIL** is set from **HOO** to **IOO**, the Series 988 switches to manual operation at that percent power.

# **Changing the Output 3 Alarm Jumper**

If you have model number <u>98 \_ \_ - \_ \_ \_ \_ **J** \_ \_ \_ ,</u> output 3 can be configured as a Form A (NO and common contact) or Form B (NC and common contact) alarm. To change the alarm jumper:

- 1. Remove the control from the case. Release the two tabs on one side of the control, then release the two tabs on the opposite side. You may need to rock the bezel back and forth several times to release the chassis.
- 2. Set the jumper to the position you want. See below for jumper location.

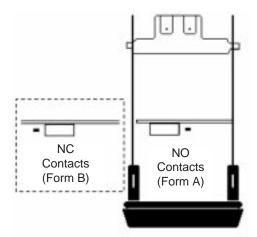


Figure 7.5 -Alarm jumper location.

**Controller Chassis - Top View** 

3. Return the controller chassis to the case. Be sure you have it oriented correctly. Press firmly, but gently, to seat the chassis.

If you select Form A, the contact is open when power is removed from the control. If you select Form B, the contact closes when power is removed.

# **Using Alarms**

Output 2, 3, and 4 of the Series 988 can function as alarms. This is accomplished with the <code>[]EE]</code>, <code>[]EE]</code> or <code>[]EE]</code> prompt (Output Menu). If <code>[]EE]</code>, <code>[]EE]</code> or <code>[]EE]</code> is selected, the output is energized in the non-alarm condition and de-energizes the output in the alarm condition. Selecting <code>[]EE]</code>, <code>[]EE]</code> or <code>[]EE]</code> reverses this action: de-energizing the output in a non-alarm condition and energizing it in an alarm condition.

If the L2, L3 or L4 LED on the front panel is lit, this indicates an alarm condition for output 2, 3 or 4 respectively.

Once you've configured the outputs as alarms, enter the Output Menu again and select the <code>RL2</code>, <code>RL3</code> or <code>RLY</code> prompt. At these prompts you can select the type of alarm: process; deviation; or rate. Each may be independently set low and high. Choose between <code>PrI</code> (process alarm input 1), <code>Pr2</code> (process alarm input 2), <code>dEI</code> (deviation alarm input 1), <code>dE2</code> (deviation alarm input 2) or <code>rRLE</code> (rate alarm referenced to input 1).

Example:  $P_{r}$  can reference the input 1 process value against the  $P_{r}$  and  $P_{r}$  settings, or  $P_{r}$  can reference the input 2 process value against the  $P_{r}$  and  $P_{r}$  settings.

A **process alarm** sets an absolute temperature range or process value range. When the temperature or process leaves the range an alarm occurs. A process alarm is not tied to the set point.

**Example:** If your set point is 100°F and a process alarm high limit is set to 150°F and the low limit is set to 50°F, the high limit trips at 150°F, and the low alarm at 50°F. If you change the set point, the process alarm limits remain the same.

A **deviation alarm** alerts the operator when the process strays too far from the set point. The operator can enter independent high and low alarm settings. The reference for the deviation alarm is the set point. Any change in set point causes a corresponding shift in the deviation alarm. Low alarms are usually set at a negative deviation while high alarms are a positive deviation.

**Example**: If your set point is  $100^{\circ}F$ , a deviation alarm high limit is set to  $+7^{\circ}F$  and the low limit is set to  $-5^{\circ}F$ , then the high alarm trips at  $107^{\circ}F$ , and the low alarm at  $95^{\circ}F$ . If you change the set point to  $130^{\circ}F$ , the alarms follow the set point and trip at  $137^{\circ}F$  and  $125^{\circ}F$ .

# NOTE: An alarm display will be masked by an error condition or when the control is in the Calibration or Setup menus.

# **Alarms**

A rate alarm alerts the operator when the process monitored by input 1 is increasing at a rate higher than the alarm high setting (R2HI), R3HI or **RYH!**) or decreasing at a rate lower than the alarm alarm low setting 

Alarms can be latching or non-latching. When the alarm condition is removed, a non-latching alarm automatically clears the alarm output and alarm message, if one is present. You must manually clear a latching alarm before it will disappear.

The alarm output is indicated by the corresponding LED on the front panel: L2; L3; or L4. There may be an alarm message flashing in the lower display, but if the Roun prompt is set to OFF (Global Menu), no alarm message is displayed. When an alarm message is displayed, it alternately flashes with the current prompt at a one-second interval in the lower display.

To clear a latching alarm, first correct the condition then press the Auto/Man key Auto once.

**Alarm silencing** is available with all alarms. This function overrides the alarm on initial power up. On power up, the alarm message will not appear and the appropriate L2, L3 or L4 LED and output will reflect a non-alarm condition. Silencing is active until the process has entered the safe region located between the low- and high-alarm settings. Then deviation outside this safe zone triggers an alarm. If an alarm occurs at this point, the output can be silenced by pressing the Auto/Man key are once, but the controller still displays the alarm message.

# **Error Codes**

#### NOTE:

To view the error code press the Auto/Man key (MAN) once. The upper display shows the error code for five seconds before returning to the

# Error Code E1 and E2 Messages

Four dashes, ----, in the upper display indicate a Series 988 error. The control goes into the manual mode and maintains the percent output selected at the **FRIL** prompt (Global Menu). That value (percent of output) is shown in the lower display.

# E ! ! E ? !: A/D underflow error

The analog-to-digital (A/D) converter of the input indicated by the first number is under range. An open or reversed polarity sensor is the most likely cause. Check the sensor. Make sure the input prompt is set to the correct sensor.



Figure 7.8 - Error code display.

# E 1 2 E2 2: Sensor under-range error

The sensor at the input indicated by the first number generated a value lower than that allowed for the range of the sensor, or the analog-to-digital (A/D) converter malfunctioned. Make sure the setting for the input (Input Menu) matches the sensor type and that the sensor range falls within the range of the process being controlled.

### E : 3 E2 3: Sensor over-range error

The sensor at the input indicated by the first number generated a value higher than that allowed for the range of the sensor, or the analog-to-digital (A/D) converter malfunctioned. Make sure the setting for the input (Input Menu) matches the sensor type and that the sensor range falls within the range of the process being controlled.

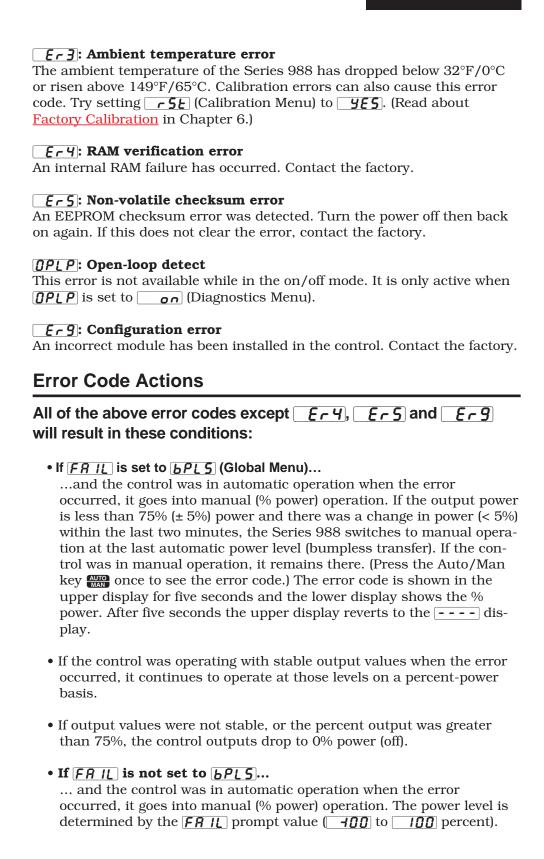
## E ! 4 E2 4: A/D overflow error

The analog-to-digital (A/D) converter at the input indicated by the first number is over range. An open or reversed polarity sensor is the most likely cause. Check the sensor. Make sure the input (Input Menu) is set to the correct sensor type.

The analog-to-digital (A/D) converter input voltage may be too high to convert an A/D signal.

#### NOTE:

An alarm display will be masked by an error condition or when the control is in the Calibration or Setup menus.



# **Error Codes**

#### To clear an error code...

- If  $[E_r]$  is set to [R], the error code should clear once the problem is corrected.
- If **Err** is set to **LAE**, correct the problem and cycle power. You can also clear the error by pressing both the Up-arrow ( and Downarrow keys to enter the Setup Menu, then press the Display key

# Error codes $[\xi, \xi]$ , $[\xi, \xi]$ and $[\xi, \xi]$ will result in these conditions:

- The control is in automatic operation with both control outputs off.
- The alarm outputs are in their alarm state (de-energized with the LED
- The lower display is blank.
- The upper display indicates the error code.
- All keys are inactive.
- With **Er5**, all Setup Menu prompts return to default values.
- The above conditions occur regardless of the FRIL value, or the settings in the Setup and Factory menus.

Cycle power to the control. If the error is still present contact the factory.

# NOTE:

An alarm display will be masked by an error condition or when the control is in the Calibration or Setup menus.

# Chapter 8 General Software

| Burst Fire          | <u>8.2</u>  |
|---------------------|-------------|
| Communications      | <u>8.4</u>  |
| Dead Band           | <u>8.6</u>  |
| Digital Events      | <u>8.8</u>  |
| Heater Current      | <u>8.10</u> |
| Input Filter        | <u>8.12</u> |
| Input Linearization | <u>8.14</u> |
| Ramp to Set Point   | <u>8.16</u> |
| Remote Set Point    | <u>8.18</u> |
| Retransmit          | 8.20        |
| Slidewire Feedback  | 8.22        |

# **Burst Fire**

## Requirements

- This feature only works with zero-cross, solid-state devices. It will not function correctly with random-fire devices.
- To enable burst fire the Series 988 must have an open collector or solid-state relay output: controllers with option "B," "C" or "K" selected for output 1 (98\_\_-\_\*\_\_), output 2 (98\_\_-\_\*-\_), output 3 (98\_\_-\_\_-\*\_\_) or output 4 (98\_\_-\_\_-\*\_\_).
- The time burst is appropriate for fast loads or very tight control. It provides advantages only for PID control, not for on/off control.
- The short time bases used by burst fire makes it incompatible with the heater current feature (98\_ \_-\_4\_ \_-\_ \_). The heater current option requires a minimum of 300 milliseconds on time to get a reading.
- The Series 988 has built in zero-cross detection circuitry, eliminating the need for external firing circuitry to trigger SCR's. The controller will not allow burst fire to be selected if its zero-cross detection circuitry is not functioning.
- The feature is enabled by selecting burst fire **br5** at the cycle time prompt for the appropriate output in the PID Menu **[LIR]**, **[LIB]**, **[LI**
- Only the 988 and 989 can use the burst fire feature. The low-voltage units (986 and 987) cannot use burst firing.

#### **Overview**

Variable, time-base burst firing from the Series 988 provides the most even distribution of power with the lowest level of noise generation (RFI). An SSR or SCR firing card translates a command signal into a burst of ac cycles. The output is zero-cross fired, which always allows at least one full ac cycle to pass within the variable time base. Burst firing is the preferred mode to control resistive loads.

The Series 988 detects when the ac sine wave of the load will cross the 0-volt point. It uses this information to switch the load on or off only at a 0-volt point, minimizing RFI.

The burst fire time base in the Series 988 varies from a maximum 1.66-second time base (1-percent output; 1 cycle on, 99 off) down to a 33.3-millisecond time base (50-percent output; 1 cycle on, 1 off). The graphs on the next page show how the time base varies with the percent output.

**CAUTION:** 

# The burst fire feature only functions with zerocross, solid-state devices. It will not function correctly with random-fire devices. Verify that the output

switching device

before selecting

quideline could

to equipment.

result in damage

burst fire. Failure to follow this

is compatible

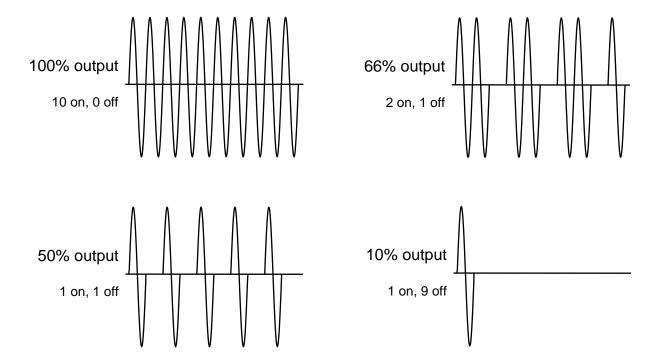


Figure 8.3a - Sine waves of burst fire settings.

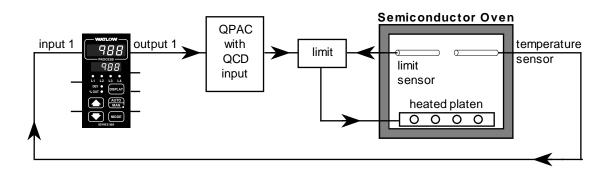


Figure 8.3b -Semiconductor oven with burst fire.

A Series 988 controls a heated platen in a semiconductor oven. Previously it used a power control requiring a 4-20mA signal to implement burst-fire control. We have replaced the power control with a Watlow Loyola QPAC with a QCD card that accepts a signal directly from an open-collector output of the Series 988. This gives smooth control at a lower overall system cost.

# **Communications**

## Requirements

Choose which interface your application will use: EIA/TIA-232 serial communications (98 $\_$ - $\_$ - $_-$ R $\_$ ), EIA/TIA-485 or EIA/TIA 232 serial communications (98 $\_$ - $_-$ - $_-$ U $\_$ ), or EIA/TIA-485 or EIA/TIA-422 serial communications (98 $\_$ - $_-$ - $_-$ S $\_$ ). The computer must have a compatible serial port or an appropriate converter must be used.

#### **Overview**

The serial communications feature allows the Series 988 family to receive commands from and transmit data to a master device, usually a computer. Any function that can be performed via the front panel, can also be accomplished using a serial communications port, allowing you to operate the controller from a computer and to store process data on a computer. L4 acts as the RX/TX indicator on the front display panel of the 988.

The Series 988 is available with a choice of serial hardware interfaces. An EIA/TIA-232 interface allows for one master (computer) and one controller, with a maximum network length of 50 feet (15 meters).

The EIA/TIA-485 or EIA/TIA-422 option equips the controller for a multidrop interface: up to 32 total network devices with EIA/TIA-485 and up to 10 total network devices with EIA/TIA-422. Each controller will have its own unique address. The total maximum network length is 4,000 feet (1,219 meters). All interfaces are isolated.

To select between EIA/TIA-485 or EIA/TIA-422, enter the Setup Menus by holding the up-arrow and down-arrow keys simultaneously until setup 5££ appears in the bottom display. Use the up-arrow key to select the Communications Menu [DP7]. At the interface prompt InEF select between 422 or 485.

Other parameters that must be configured in the Communications Menu [Dr?] are the baud rate [bRUd], data bits and parity [dRER], protocol [Prot], and device address [Rddr]. The protocol prompt must be set to full (ANSI X3.28 2.2-A3) or RTU Modbus if multiple devices are used with the EIA/TIA-485 or EIA/TIA-422 interface. If the full protocol or RTU Modbus is selected, a device address must be selected at the address prompt. For EIA/TIA-232, full [FULL] or on [CON/XOFF] protocol may be selected.

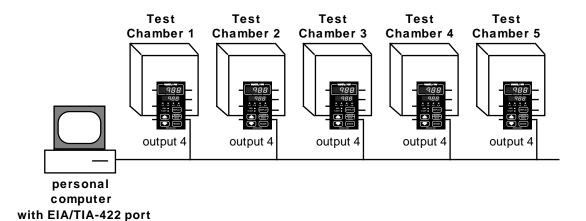


Figure 8.5 - Test chambers with communications.

# **Sample Application**

A test engineer uses Series 988s to control the temperatures of several automated test chambers. His computer is linked to the controllers through its EIA/TIA-422 serial communications port. His computer program monitors the temperatures of the chambers and initiates automatic test sequences when certain program parameters are met. After completing a sequence, the computer loads the next temperature to the controller. The computer periodically interrogates each controller for its process temperature, set point and alarm status. This information is stored on a disk to provide test verification data for the completed products.



WARNING:
If the dead band is set to a negative value, the heat and cool outputs can both be ON at the same time.

# **Dead Band**

# Requirements

The dead band feature is standard on any Series 988 controller with two control outputs. The dead band prompts will appear if the control outputs are configured for heat/cool or cool/heat.

## **Overview**

The dead band prompts,  $\boxed{\textbf{db} \quad \textbf{R}}$  and  $\boxed{\textbf{db} \quad \textbf{b}}$ , located in the PID menus, determine the amount of interaction between heat (reverse acting) and cool (direct acting) control outputs. The dead band directly offsets the target set point of the cool control output.

With a positive dead band, both control outputs will never be ON at the same time. With the process in a positive dead band, the output value is determined by adding the percent heat output to the percent cool output and only applying the result to the correct output — cooling action if the sum is negative and heating action if it is positive.

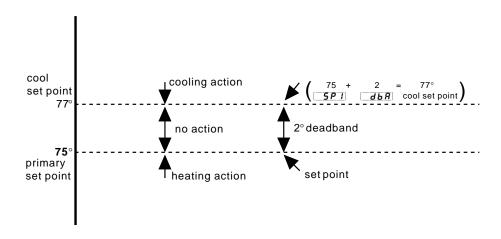


Figure 8.7a - Dead band graph.

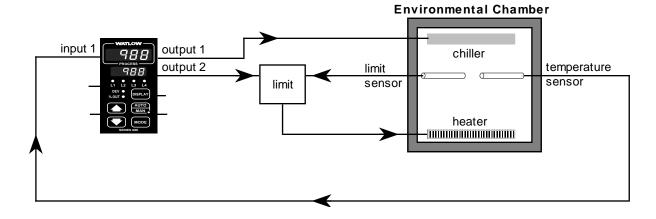


Figure 8.7b -Environmental chamber with dead band.

An engineer for an environmental chamber manufacturer, who is designing the heating and cooling system for a new chamber, wants to minimize the energy costs of operating the chamber. She has chosen the Series 988 and will configure the heat and cool outputs with a positive dead band.

When the chamber temperature is near ambient the cooling and heating systems had a tendency to buck one another, resulting in inefficient use of energy. The engineer started with a dead band of five degrees, but in the process of tuning the system for optimal control, the setting was reduced to two degrees. This made the chamber more energy efficient and reduced wear on the refrigeration system.

# **Digital Events**

# Requirements

A single digital event input is standard on all controls. A second digital input is available as an option for input 2 (98\_ --5\_ -- \_ ).

#### **Overview**

The digital event input options on the Series 988 controller allow the operator to select one of several software functions with the close of a customer-supplied switch or by a change in dc voltage (See <u>Chapter 2</u> for voltage and wiring information.).

The list below outlines the functions that can be controlled with a digital event input:

- **Idle set point Id5P** lets the operator select a second (idle) set point.
- **Turn control outputs off OFF** inhibits the control outputs.
- **Alarm reset RLr** resets alarms from a remote location.
- **Switch PID sets P**,**d** selects between PID set A or B (requires enhanced software, 98\_B-\_\_\_-\_\_).
- **Remote set point r 5P** switches to remote set points.
- **Front panel lockout** LOC locks out the front panel keys to prevent tampering.
- **Control output action**  $\boxed{\textit{Rctn}}$  switches the control action of outputs 1 and 2 from heating to cooling, or vice versa.
- **Auto/Manual operation** [R-[7]] switches to the manual mode of operation at the percent power selected with [FRIL] (Global Menu) and disables the Auto/Man key.

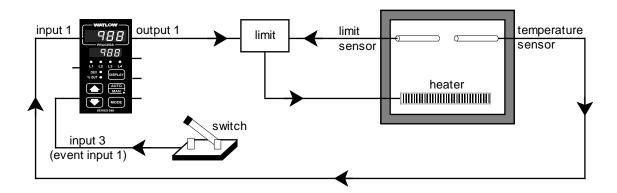


Figure 8.9 - Heater with digital event.

A manufacturing engineer is building an application that needs to switch to an idle temperature at the end of a batch and maintain that temperature until the next batch is loaded, with minimum operator interaction.

By connecting an external switch to the digital event input, he can select either the operating temperature or the idle temperature with the flip of a switch. The idle set point prompt is enabled by setting the Event Input 1 prompt <code>F.I</code>, in the Global Menu, to idle set point <code>Id5P</code>. The idle set point value is accessed by pressing the MODE key <code>mode</code> from anywhere in the display loop. When the switch closes, the lower display will indicate the idle set point, and the controller will maintain this new set point.

# **Heater Current**

### Requirements

Choose the heater current option (98\_ \_-4\_ \_-\_ \_) for input 2 and an appropriate current transformer. A current transformer must be ordered separately.

Output 1 cannot be used as a process output. The heater current feature monitors only output 1.

## **Overview**

The heater current feature measures and responds to heater current in a system. This is an ideal method for detecting heater loss in applications with multiple heaters. The current is measured when output 1 is on. For instance, if a system has five, 10-amp heaters, the heater current input measures 50 amps regardless of the percent output.

To view the heater current press the DISPLAY key and advance to the Process 2 prompt  $P_r$  ?. The upper display indicates the last valid current reading.

The Input 2 prompt In2 under the Input Menu InPE can be set to current **[urr**] or loop error detect **[urr**]. Current **[urr**] allows you to monitor heater current and set alarm set points based on high and low heater current values. Alarms can only be configured as process alarms (see <u>Alarms</u>, in Chapter 7). Setting to loop error detect **Loop** enables monitoring and alarm functions, and also triggers an error and shuts off all outputs if current is present with output 1 off or when no current is present and output 1 power is more than zero.

There are limits associated with this feature:

- To obtain a reading, the output on-time must be a minimum of 0.3 seconds. To calculate this, multiply the percent output by the cycle time setting. Example: With 30-percent output and a 2.0 second cycle time, the on-time would be:  $0.30 \times 2.0 = 0.6$  seconds. This would yield a valid reading. If a valid reading is not possible, the 988 will display the last valid reading.
- The heater current feature will not function with burst-fire outputs: Controllers with option "B," "C" or "K" selected for output 1 (98\_ -- \*-- \_), output 2 (98\_ -- \_\*- \_), output 3 (98\_ -- \_ -\* \_ \_) or output 4 (98\_ -- \_ -\* \_). This does not necessarily apply to the loop error detect feature. If enabled, any current detected with no output triggers an error.
- This feature will not function when the Series 988 has a process output for output 1 (98\_\_-F \_ \_ \_ \_ \_). A known cycle time is required to detect the current. There is no cycle time associated with process outputs.

The maximum signal the input can accept from the current transformer secondary is 50mA. So, you must calculate the output range of the current transformer before wiring the system.

### NOTE:

To obtain a reading, the output ON-time must be a minimum of 0.3 seconds.

#### NOTE:

The heater current feature will not function with burstfire outputs.

#### NOTE:

The heater current feature will not function when the Series 988 has a process output for output 1.

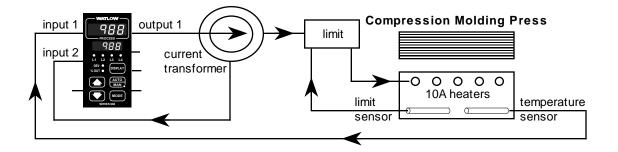


Figure 8.11 -Compression molding press using the heater current feature.

The Series 988 controls the lower platen of a compression molding press that contains five, 10-ampere heaters. A 50A:50mA current transformer is used to monitor heater current.

Set the Input 2 prompt to current furr, the Range Low 2 prompt r L 2 to 0 and the Range High 2 prompt r to 50. Find the range high 2 value with the following equation:

range high  $2 = \underline{\text{(maximum CT primary current (load current))}} \times 50\text{mA}$ (maximum output from CT secondary (input))

The application uses a Watlow current transformer (CT) part# 16-0233, which has a maximum input of 50 amperes, which corresponds to a maximum output of 50mA.

range high  $2 = (50 \text{Amps}) \times 50 \text{mA}$ 50mA

Solving for rH2 gives you 50. This is the range high 2 setting.

# **Input Filter**

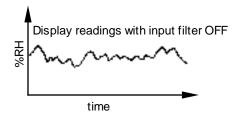
# Requirements

This feature is standard on all Series 988 controllers.

## **Overview**

NOTE: Use this feature with caution, because a large time constant could hide system upsets. In certain applications the process being measured can be unstable, which makes it difficult to control and also makes the constantly changing display difficult to read. The Series 988 input filter can solve these problems by smoothing out just the display or the display and the input signal.

You can set a time constant in seconds for a low-pass filter that will, if you select a positive value, affect the display only. Select a negative value to filter the input signal itself.



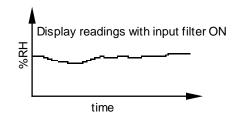


Figure 8.13a - Display readings with input filtering.

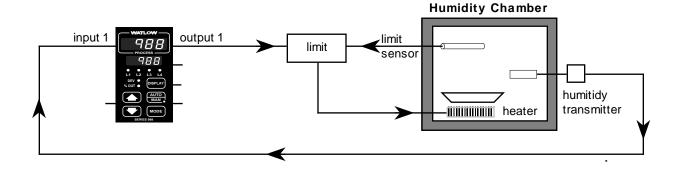


Figure 8.13b -Humidity chamber with input filtering.

# **Sample Application**

A Series 988 controls the humidity in an environmental chamber. The relative humidity (RH) sensor provides a 4-20mA signal over a 0-100% RH range. The sensor is very sensitive to changes caused by air flow in the chamber. The turbulence in the chamber makes the controller display jump two to three percent. To remove this display dithering set the filter time constant  $\boxed{\textit{FErI}}$  for input 1 to two seconds. This will smooth the display and provide a more realistic reading.

# **Input Linearization**

## Requirements

The square root extraction feature is standard on any Series 988 controller with universal signal conditioner inputs. The linearization prompt will appear if a process input is selected with the DIP switches (see Chapter 1).

#### Overview

In many flow applications the output signal from a flow transmitter represents a squared value of the actual flow. The square root must be extracted from the signal to make it useful to the operator. Many flow transmitters offer this feature in the transmitter itself, but this can add significantly to the cost. Using the square root extraction option in the Series 988 controller can save the operator money. The feature is enabled simply by setting input 1 linearization [L , n] or input 2 linearization [L , n] to square root extraction **root**.

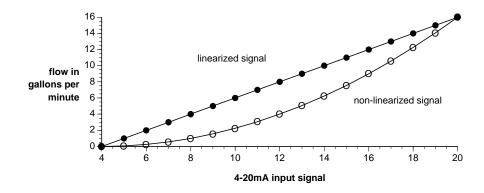


Figure 8.15a -**Graph of linearized** signal.

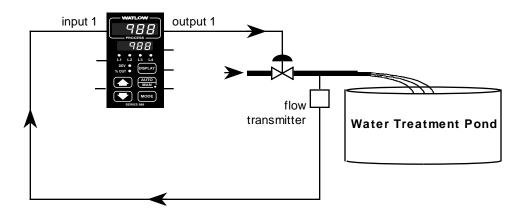


Figure 8.15b -Waste-water treatment with input linearization.

A waste water process engineer needs to control the flow of a solution to be mixed with wastewater to treat it. The transmitter provides a 4-20mA output without square root extraction. The engineer used the Series 988 with a universal signal conditioner input and a 4-20mA process output to control the flow. The input signal was linearized using the square root extraction feature of the 988.

The above system has a flow range of 0 to 16 gallons per minute. The range low and range high parameters for input 1 would be set to 0 and 16 respectively. The input 1 linearization prompt [[ , , , ]] would then be set to square root extraction **root**. You can see from the above graph that without square root extraction to linearize the signal it would not be useful for controlling the process.

# **Ramp To Set Point**

# Requirements

This feature is standard on all units.

#### **Overview**

Ramp to set point enables the Series 988 to ramp the set point at a user-defined rate. This allows the controller to start up a system or change between set points at a rate that will not stress the product or system components. The ramp rate is defined in degrees per minute. Ramp to set point can be initiated at start up only, or at start up and also on any set point changes.

When a ramp is initiated, the starting point for the ramp is the current process value. If the ramp is initiated on start up, the Series 988 looks at the process value upon power up, and uses that value as the starting point for the ramp. If a set point change initiates the ramp to set point function, the controller looks at the process value when the change is made and uses that value as the starting point for the ramp. If the set point is changed during a ramp, the process value at the time of the change becomes the starting point for the new ramp.

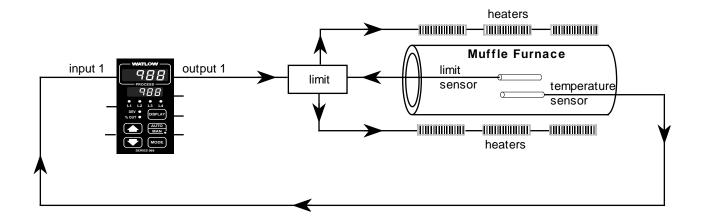


Figure 8.17 -Muffle furnace with ramp to set point.

An engineer needs to control the temperature of a muffle furnace. The furnace set point must be ramped up at a defined rate to prevent stressing the muffle and other system components. By enabling the ramp to set point function in the Series 988, the engineer can control the rate at which the set point will rise. Ramp to set point is enabled in the Global Menu using the Ramping Function prompt  $\boxed{\ r}$ . To ramp on start up only, select start  $\boxed{\ f}$ . To ramp on start up and on any set point changes, select set point  $\boxed{\ f}$ . The ramp rate  $\boxed{\ r}$   $\boxed{\ r}$   $\boxed{\ f}$  is in degrees per minute.

For further protection of the system, output 2, 3 or 4 can be configured as a rate alarm, monitoring the rate of increase or decrease in the process variable on input 1. The Alarm Low [RZLI] and Alarm High [RZHI] prompts (The "2" in these examples refers to output 2.) establish the ramp-down and ramp-up rate set points, respectively, in degrees per minute.

# **Remote Set Point**

# Requirements

Input 2 must be either a thermocouple (98\_ --1\_ -- \_ ) or universal signal conditioner (98\_ \_-2\_ \_-\_ \_).

To use a Series 988 as a master controller, choose one of the retransmit options for output 3 of the master (98\_ -- \_ - M\_ \_ for 0-20mA or 4-20mA; or 98\_ -- \_ -N\_ \_ for 0-5V= (dc), 1-5V= or 0-10V=).

#### **Overview**

The remote set point feature allows the Series 988 to use a thermocouple, RTD or process signal at input 2 to establish the set point. This feature gives the Series 988 the ability to have its set point value manipulated by an external source. A common application would use one ramping controller with a set-point retransmit output to ramp multiple controllers using the remote set point. Or you could use an analog output from a PLC to send set point values to a Series 988.

You may select between local and remote set points at the front panel, with an event input, from a remote computer using the communications feature or from an external switch using an event input.

# NOTE: Make sure all input and output impedances are

NOTE:

compatible.

Input 1 and 2 are not isolated from each other.

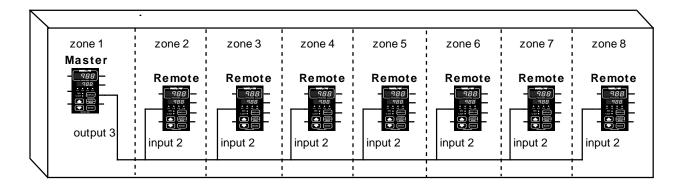


Figure 8.19 -Zone heating with remote set point.

An engineer has a machine with eight independent zones of heat. He wants to change set points on all zones without having to adjust each control individually. This can be achieved using a Series 988 with a  $0-5V^{--}$  (dc) retransmit output as the master controller. The seven remote 988s will use the  $0-5V^{--}$  (dc) signal on input 2 as a remote set point. When the set point is changed on the master controller, the retransmit output changes the set points of the seven remote controllers. By enabling the ramp to set point feature in the master controller, all eight zones are ramped up to set point at a user-defined rate on power up.

The retransmit output from the master Series 988 is set so that 0V ≡ (dc) represents 0°F and 5V= (dc) represents 800°F. On the remote controllers, set the input 2 DIP switch to the position for the 0-5, 1-5, 0-10V (dc) process input. In the Input Menu, under the Input 2 prompt // Ind. select 0-5. The Remote Set Point prompt **F5P** should be set to ON and decimal 2 JEC2 set to 0. The range low 2 L2 and the range high 2 **FH2** parameters will establish the scaling for the remote set point input. Range low 2 **rl2** should be set to 0 and range high 2 **FH2** should be set to 800. To operate a specific zone ten degrees hotter 2 **- H2** to 810. With remote set point **F5P** enabled and local **L** selected under the Local-remote prompt \(\begin{aligned} \overline{\chi} - \begin{aligned} \overline{\chi} & \overline{\chi} \end{aligned}\) in the System Menu, the set point is adjusted using the up-arrow and down-arrow keys. Selecting remote under the Local-remote prompt [L-r], disables the up-arrow and down-arrow keys, allowing the set point value to be manipulated by the input 2 signal.

# Retransmit

## Requirements

Output 3 is used for the retransmit option. Choose either a milliamp (98\_ \_-\_ \_ -M\_ \_ ) or a voltage (98\_ -- \_ \_ -N\_ \_ ) signal. Select the output range in the Output Menu.

## **Overview**

NOTE: Enhanced software is not required for this feature. The retransmit feature can be used to transmit an analog signal representing the value of either input process variable or the target set point variable. The retransmit signal is factory configured as either a milliamp  $(98\_--\_-M\_)$  or a voltage  $(98\_--\_-N\_)$  signal. In choosing the type of retransmit signal the operator must take into account the input impedance of the device to be retransmitted to and the required signal type, either voltage or milliamps.

Typically applications might use the retransmit option to record one of the variables with a chart recorder or to generate a set point for other controls in a multi-zone application (see page 8.19).

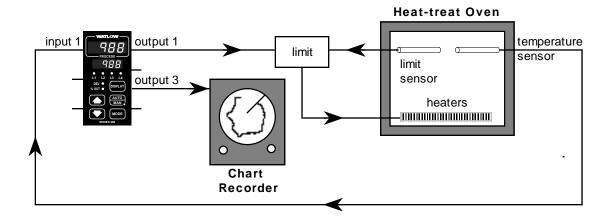


Figure 8.21 -Heat-treat oven with retransmit.

A Series 988 is being used to control the temperature of a heat-treat oven. The temperature of the process must be recorded on a chart recorder. The oven temperature range stays between  $600^{\circ}$  and  $900^{\circ}$  F. The chart recorder requires a 4-20mA signal.

In the Output Menu **[]** EPE set analog output **[Rout]** to **[Prc]** to tag the input 1 process value as the parameter to be retransmitted. Set retransmit low limit **[Rr]** to 600 to set the low range for the retransmit signal to 600. Set retransmit high limit **[Rr]** to 900 to set the high range for the retransmit signal to 900. Set retransmit calibrate offset **[RI]** to 0, assuming there is no calibration offset required.

The retransmit output will be 4mA until the oven temperature is greater than 600 degrees F, at which point the signal will increase with temperature to 20mA at 900° F and will not exceed 20mA.

# Slidewire Feedback

## NOTE:

Outputs must be compatible with the slidewire valve actuators.

# Requirements

A slidewire configuration uses at least two inputs and two control outputs. Input 2 can only be selected as a slidewire input (98\_ \_-\_3\_ \_-\_ \_).

#### **Overview**

The Series 988 can control the position of a valve with a slidewire feed-back position indicator. The controller senses the resistance of the slidewire and compares it to the range low and range high settings to determine the valve position. The controller compares this to the percent output and takes action to match the two by opening or closing the valve.

Set the hunt [hunt] parameter to limit valve hunting. The value is set for the percent of output (0.0 to 100.0). When the valve is within this dead band, a change in output greater than half the hunt parameter is required to trigger action. Output 1 responds to "close" commands and output 2 responds to "open" commands.

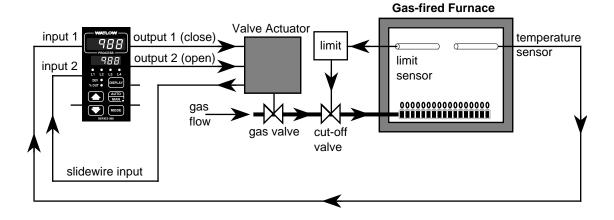


Figure 8.23 -Gas-fired furnace with slidewire feedback.

A Series 988 controls the gas valve for a gas-fired furnace to heat treat large metal parts. First the controller must be "married" to the slidewire feedback from the valve actuator. To do this, first set the Input 2 prompt <code>In2</code> to slidewire <code>[5]</code>. Advance to the Learn Low Resistance prompt <code>[rn1]</code>. Close the valve manually to the minimum resistance reading from the slidewire. Select <code>[ye5]</code> in the upper display and press the Mode key <code>[rnH]</code>. Manually open the valve (maximum slidewire resistance). Select <code>[ye5]</code> in the upper display and press the Mode key <code>[rnH]</code>. At this point both the high and low resistance values have been learned and stored in the range low 2 and range high 2 parameters.

You can also manually set the range low and range high values. From the slidewire specifications, determine the low and high resistance values and enter these at the Range Low  $\lceil r \mid Z \rceil$  and Range High  $\lceil r \mid R \mid Z \rceil$  prompts.

Once the control is operating, adjust the hunt hunt parameter, to minimize valve oscillations. The hunt parameter sets up a dead band on both sides of the current valve position. The desired valve position is then compared to the actual position. If the difference is greater than the one-half of the hunt value, the Series 988 repositions the valve to achieve the temperature set point. Once repositioning is complete, the dead band is recalculated for the new valve position.

# **Chapter 9** Enhanced Software

| Cascade      | <u>9.2</u>  |
|--------------|-------------|
| Differential | <u>9.6</u>  |
| Dual PID     | <u>9.8</u>  |
| Duplex       | <u>9.10</u> |
| Ratio        | 9.12        |

# Cascade

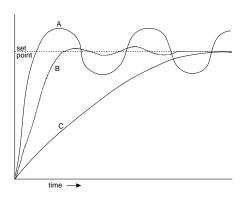
# Requirements

Cascade control requires enhanced software and two analog inputs, input 1 to monitor the primary, or outer, loop and input 2 to monitor the secondary, or inner, loop. At least one control output is required to control the process.

#### Overview

Cascade control can handle a difficult process with minimal overshoot, while reaching the set point quickly. This minimizes damage to system components and allows for oversizing heaters for optimal heat-up rates. Heater life is also extended by reducing thermal cycling of the heater.

Systems with long lag times between the energy source (heater, steam, etc.) and the measured process value cannot be controlled accurately or efficiently with a single control loop, because a lot of energy can build up



before a response is detected. This can cause the system to overshoot the set point, which could damage the heater, product or heat transfer medium, such as a heat transfer fluid.

This graph illustrates a system with a long lag time. Curve A represents a single-control system with PID parameters that allow a maximum heat-up rate. Too much energy is introduced and the set point is over-

shot. In most long-lag-time systems the process value may never settle out to an acceptable error. Curve C represents a single-control system tuned to minimize overshoot. This results in unacceptable heat-up rates, with the final value taking hours to reach. Curve B shows a cascade system

that limits the energy introduced into the system, allowing an optimal heat-up rate with minimal overshoot.

This drawing shows two controllers configured as a cascade system. The second controller generates the internal set point. The Series

988 effectively combines both controllers into a single package.

The primary controller measures the process in the outer, or primary, loop with input 1 and compares the value to the desired set point. The differ-

Figure 9.2a - System heat-up profiles using three different control methods.

Figure 9.2b - The cascade feature allows one Series 988 controller to internalize the functions of two controllers.

ence between the set point and the process temperature generates an internal percent output value for the second, or inner loop, controller. This value cannot be seen by the operator. This internal percent (% int) output generates the internal set point for the secondary, or inner loop. The secondary loop uses this set point and the value of input 2 (typically attached to the heater sheath) to control the heat source temperature.

## Algorithm

The following formulas show how the primary control sends a set point (based on input 2 range-high and range-low values) to the secondary control. The secondary control uses this set point (SP int) to generate a percent output (% out) to the heater.

1.) 
$$%_{int}$$
 = PID Set A [In1 - SP]

2.) 
$$SP_{int} = (rH2 - rL2) * \%_{int} + rL2$$

3.) 
$$\%_{out}$$
 = PID Set B [In2 -  $SP_{int}$ ]

The critical parameters are the range settings for input 2 of the inner loop controller. The range-high value (rH2) is the maximum allowed set point for the secondary, or inner, loop. The range-low value (rL2) is the minimum allowed set point. In a system controlling a heater this would be the maximum and minimum desired sheath temperatures of the heater. Typically the range-low term is set below the ambient temperature. Otherwise the system could never fully cool down.

## Setup

When tuning a cascade system, the inner loop must be tuned first. In a heating system the inner loop is comprised of the output device and the input 2 sensor, which usually measures the heater sheath temperature. The output device controls a power switching device, which, in turn switches the heater. The set point for the inner loop is generated by the outer loop and will have a range between range low  $2 \frac{1}{rH^2}$  and range high  $2 \frac{1}{rH^2}$ .

Before tuning the inner loop you must make sure <code>rl2</code> and <code>rh2</code> are set properly. Set the value of <code>rl2</code> slightly lower than the ambient temperature, otherwise the system will never fully cool down. Set <code>rh2</code> to the maximum desired heat source temperature. The inner loop can be auto-tuned by setting <code>RUE</code> to <code>Prdb</code>. While auto-tuning, the inner loop will be controlled in an ON/OFF mode at a set point equal to <code>RESP</code> x <code>rh2</code>.

Once the inner loop, PID B, has completed auto-tuning, we can then autotune the outer loop, PID A. The outer loop will generate the set point for the inner loop. This is done by comparing the value of the input 1 sensor to the process set point, performing the control algorithm by using the values of  $P \cdot dR$ , then generating a set point between  $r \cdot LR$  and  $r \cdot LR$ .

The outer loop can be auto-tuned by setting  $\boxed{\textbf{RUE}}$  to  $\boxed{\textbf{P.dR}}$ . While auto-tuning, the outer loop will be controlled in an on/off mode at a set point equal to  $\boxed{\textbf{RESP}}$  x  $\boxed{\textbf{SPI}}$ . In a heating application, make sure the set point is set at a value above ambient temperature. In most cases, the auto-tuning feature will tune  $\boxed{\textbf{P.dR}}$  for acceptable control. If not, you must then manually tune the outer loop.

Before beginning manual tuning, record the values of **Pb IR** and **re IR** generated by the auto-tuning feature. The auto-tune for the outer loop will not generate a value for **re IR**, because rate (derivative) in the outer loop seems to cause instability in most systems.

Start manual tuning by setting  $\[ reclaim \] \[ reclaim \]$  to  $\[ reclaim \] \[ reclaim \]$  Enter the desired process set point and let the system stabilize. Once the system stabilizes, observe the value of  $\[ reclaim \] \[ reclaim \] \[ reclaim \]$  in the Display Menu. If the  $\[ reclaim \] \[ reclaim \] \[ reclaim \]$  value fluctuates, make the proportional band setting  $\[ reclaim \] \[ reclaim \] \[ reclaim \] \[ reclaim \]$  value stabilizes. Make adjustment  $\[ reclaim \] \[ reclaim \] \[ reclaim \] \[ reclaim \]$  in 5° to 10° increments, allowing time between adjustments for the system to stabilize.

Once Pr2 has stabilized, observe percent power in the display loop. It should be stable,  $\pm 10\%$ . At this point, the process temperature should also be stable, but will exhibit droop (stabilized below set point). The droop can be eliminated with reset of integral.

Start with a setting of 0.01; allow 10 minutes for the process temperature to come up to set point. If it has not, increase the setting to 0.05 and wait another 10 minutes. After this, double the reset setting until process value equals the set point. If the process becomes unstable, the reset value is too large. Decrease the setting until the process stabilizes.

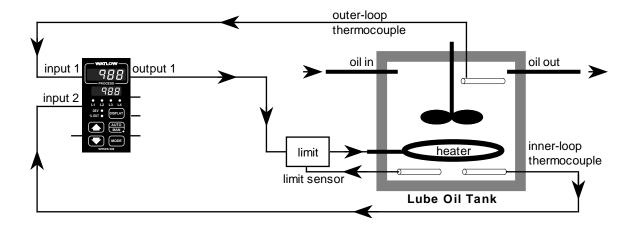


Figure 9.5 - Lube oil tank with cascade control.

## **Sample Application**

A Series 988 controller is used to heat lube oil to  $125^{\circ}F$  with a screw-plug-style heater. To protect the oil from breaking down and maximize its life, it is desirable to limit the maximum heater sheath temperature to  $250^{\circ}F$ .

# **Differential**

# Requirements

Two inputs and the enhanced software option are required.

#### **Overview**

Differential control allows the Series 988 to control one process at a difference to another process. Input 2 acts as a remote set point input. However the displayed set point indicates the desired difference between input 1 and input 2. The set point that input 1 will use is determined by the equation:

internal set point = input 2 + differential set point

The lower display shows the differential set point, which can be adjusted with the increment (up-arrow) and decrement (down-arrow) keys.

Please note that while in the differential control mode the internal set point for input 1 cannot be viewed and must be calculated with the equation.

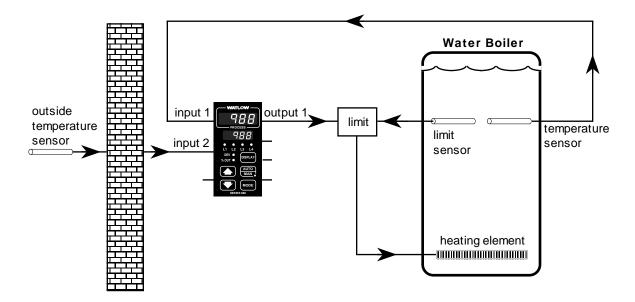


Figure 9.7 - Water boiler with differential control.

The most common application using differential control is to maintain water temperature in a boiler at a differential to the outside air temperature. A thermocouple at input 2 senses the outside air temperature and adjusts the internal set point to maintain the boiler water temperature 120 degrees higher. Substituting values we have: boiler temperature = outside temperature +  $120^{\circ}$ .

In this application the system uses two type J thermocouples: one to sense boiler water temperature (input 1) and one to sense the outside air temperature (input 2).

To configure the controller, first enable input 2 (set ). To enable the differential control algorithm set the control prompt [nell in the Global Menu to differential ]. Press the DISPLAY key. The lower display will read 0, indicating no differential between input 1 and input 2. Adjust the set point to 120. The internal set point for input 1 is now equal to the input 2 value plus 120, which will maintain the boiler water temperature 120 degrees higher than the outside air temperature.

# **Dual PID Sets**

### Requirements

The Series 988 controller needs the enhanced software option to use dual PID sets.

#### **Overview**

Standard software units have a single set of PID parameters. Units with enhanced software can use two independent sets of heat/cool PID parameters, PID A P.dR and PID B P.db. To enable dual PID, enter the Global Menu and set the algorithm prompt RL90 to dual PID P.d2. This second set of PID parameters enables the controller to switch between two sets of PIDs, to compensate for changes in the system characteristics. This need can arise from a variety of circumstances, such as significant set point changes (controlling at 250, then controlling at 750), operating a furnace with half a load versus a full load of steel, changing the speed of a conveyor through a curing oven or using different materials in an extruder.

Series 988 controllers can be configured to switch between PID A and PID B based on a process value, a set point value or the event input status.

- At **P.d2** PID 2 Crossover Selection (Global Menu) select what will cause the switch:
  - **Proc** Crossover Process Value, (input 1), PIDs will switch based on the crossover process value;
  - **5EPE** Crossover Set Point (1) Value, PIDs will switch at the crossover set point value, PID A used below the crossover point and PID B above;
  - no crossover.
- At **E**, **!** Event Input 1 or **E**, **?** Event Input 2 select **P**, **d**:
  - PID A is used when the event input switch is open;
  - PID B when the event input switch is closed.

(Note: One event input is standard on all units, a second event input is an option.)

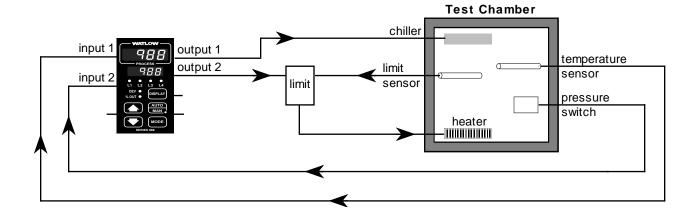


Figure 9.9 - Test chamber controlled with dual PID sets.

## **Sample Application**

A test engineer needs to control the temperature in a test chamber that can be operated at normal atmosphere or under vacuum conditions. If he tunes the controller for normal atmospheric conditions, when he reaches the portion of his test that requires a vacuum, he must stop the test and enter new PID parameters to maintain stable temperatures. The system characteristics are so very different, that one set of PIDs will not give satisfactory results under both normal and vacuum conditions.

The Series 988 solves this problem with the dual PID option. Auto-tuning PID A under normal atmospheric conditions, then auto-tuning PID B under vacuum conditions, establishes PID values for two sets of system characteristics. A pressure switch connected to the event input tells the controller when to switch between PID A and PID B, eliminating the need to change PID values manually.

# **Duplex**

## Requirements

The duplex control feature requires enhanced software and a process output.

## NOTE: Duplex applications require a special valve.

## **Overview**

Certain systems require that a single process output control both heating and cooling outputs. A Series 988 controller configured with enhanced software and a process output can function as two separate outputs. With a 4 to 20mA output the heating output will operate from 12 to 20mA (0 to +100 percent) and the cooling output will operate from 12 to 4mA (0 to -100 percent). In some cases this type of output is required by the device that the 988 controls, such as a three-way valve that opens one way with a 12 to 20mA signal and opens the other way with a 4 to 12mA signal. This feature reduces the overall system cost by using a single output to act as two outputs.

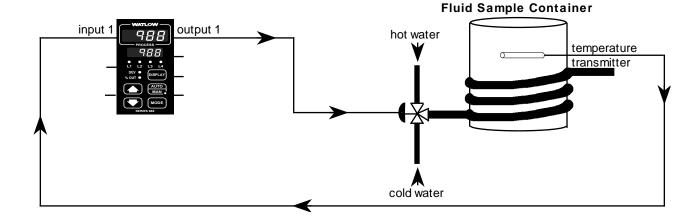


Figure 9.11 - Fluid sample container with duplex control.

# **Sample Application**

The system outlined above uses a three-way valve for heating and cooling a fluid sample. Coils surround the container holding the fluid. When the temperature needs to be raised, the signal to the valve will be between 12 and 20mA, sending hot water through the coils. When cooling is required, the signal will be between 12 and 4mA, sending cold water through the coils.

# **Ratio**

## Requirements

Ratio control requires enhanced software. Two analog inputs are required to monitor the process, and at least one output adjusts the controlled part of the process.

## **Overview**

This feature allows the Series 988 to control one process as a ratio of another process. This is especially useful in applications that mix two materials, whether steam, paint or food ingredients.

Input 2 of the controller measures the part of the process that is either uncontrolled or controlled by another device. The part of the process controlled by the 988 will be maintained at a level equal to the quantity measured at input 2 multiplied by the ratio term set by the user. Input 1 monitors the controlled part of the process.

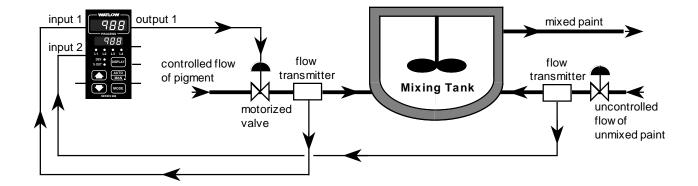


Figure 9.13 - Mixing tank with ratio control.

## **Sample Application**

Blue pigment must be added to paint at a ratio of one part per 100 to create a mixed paint of the desired color. The uncolored paint flows into the mixer in an uncontrolled stream that is set manually and sensed by input 2. A motorized valve controls the flow of pigment, which is monitored by the flow sensor to input 1. The flow rate of the uncolored paint determines the set point for the motorized valve that controls the pigment flow. If an operator needs to change the rate of flow for the uncolored paint, the set point will shift accordingly to maintain the correct ratio in the mixing

The application engineer set up this feature in software by choosing ratio rate as the control [rate] parameter in the Global Menu. The set point value displayed was then a ratio value. He entered 0.01 to maintain an input 1:input 2 ratio of 1:100.

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# Glossary, A - L

**annunciator** — A visual display that uses pilot lights to indicate the former or existing condition of several items in a system.

**bumpless transfer** — A smooth transition from auto (closed loop) to manual (open loop) operation. The control output(s) does not change during the transfer.

**burst fire** — A power control method that repeatedly turns on and off full ac cycles. Also called zero-cross fire, it switches close to the zero-voltage point of the ac sine wave. Variable-time-base burst fire selectively holds or transits ac cycles to achieve the desired power level.

**calibration offset** — An adjustment to eliminate the difference between the indicated value and the actual process value.

**cascade** — Control algorithm in which the output of one control loop provides the set point for another loop. The second loop, in turn, determines the control action.

**closed loop** — A control system that uses a sensor to measure a process variable and makes decisions based on that feedback.

**cold junction** — See junction, cold.

**cold junction compensation** — Electronic means to compensate for the effective temperature at the cold junction.

**current transformer** — A transformer designed for measuring electrical current.

**dead band** — The range through which a variation of the input produces no noticeable change in the output. In the dead band, specific conditions can be placed on control output actions. Operators select the dead band. It is usually above the heating proportional band and below the cooling proportional band.

**default parameters** — The programmed instructions that are permanently stored in the microprocessor software.

**derivative** — The rate of change in a process variable. Also known as rate. See PID.

 $\label{eq:continuous} \textbf{Deutsche Industrial Norm (DIN)} — A set of technical, scientific and dimensional standards developed in Germany. Many DIN standards have worldwide recognition.$ 

**DIN** — See Deutsche Industrial Norm.

**droop** — In proportional controllers, the difference between set point and actual value after the system stabilizes.

**duty cycle** — The percentage of a cycle time in which the output is on.

 ${\bf external\ signal\ conditioner\ power\ supply}-{\bf A\ dc\ voltage\ source\ that\ powers\ external\ devices.}$ 

filter —

**digital filter (DF)** — A filter that slows the response of a system when inputs change unrealistically or too fast. Equivalent to a standard resistor-capacitor

(RC) filter.

**digital adaptive filter** — A filter that rejects high frequency input signal noise (noise spikes).

**heat/cool output filter** — A filter that slows the change in the response of the heat or cool output. The output responds to a step change by going to approximately 2/3 its final value within the number of scans that are set.

**form A** — A single-pole, single-throw relay that uses only the normally open (NO) and common contacts. These contacts close when the relay coil is energized. They open when power is removed from the coil.

**form B** — A single-pole, single-throw relay that uses only the normally closed (NC) and common contacts. These contacts open when the relay coil is energized. They close when power is removed from the coil.

**form C** — A single-pole, double-throw relay that uses the normally open (NO), normally closed (NC) and common contacts. The operator can choose to wire for a Form A or Form B contact.

**hunting** — Oscillation of process temperature between the set point and the process variable.

**hysteresis** — A change in the process variable required to re-energize the control or alarm output. Sometimes called switching differential.

**integral** — Control action that automatically eliminates offset, or droop, between set point and actual process temperature. See reset, automatic.

**isolation** — Electrical separation of sensor from high voltage circuitry. Allows use of grounded or ungrounded sensing element.

**Joint Industrial Standards** (JIS) — A Japanese agency that establishes and maintains standards for equipment and components. Also known as JISC (Japanese Industrial Standards Committee), its function is similar to Germany's Deutsche Industrial Norm (DIN).

JIS — Joint Industrial Standards.

**junction** — The point where two dissimilar metal conductors join to form a thermocouple.

**cold junction** — Connection point between thermocouple metals and the electronic instrument. See reference junction.

**grounded junction** — Type of thermocouple probe in which the hot, or measuring junction, is an integral part of the sheath material. No electrical isolation is provided

**isolated junction** — A form of thermocouple probe construction in which the measuring junction is fully enclosed in a protective sheath and electrically isolated from it. Commonly called an ungrounded junction.

**reference junction** — The junction in a thermocouple circuit held at a stable, known temperature (cold junction). Standard reference temperature is 32°F (0°C).

**thermocouple junction** — The point where the two dissimilar metal conductors join. In a typical thermocouple circuit, there is a measuring junction and a reference junction. See reference junction.

 $\mbox{\bf ungrounded junction} - \mbox{ See isolated junction}.$ 

**linearization, square root** — The extraction of a linear signal from a nonlinear signal corresponding to the measured flow from a flow transmitter. Also called square root extraction.

**Modbus (RTU)** — Remote Terminal Unit.

**NEMA 4X** — A NEMA specification for determining resistance to moisture infiltration. This rating certifies the controller as washable and corrosion resistant.

**on/off** — A method of control that turns the output full on until set point is reached, and then off until the process error exceeds the hysteresis.

 ${f open\ loop}$  — A control system with no sensory feedback.

**output** — Control signal action in response to the difference between set point and process variable.

**overshoot** — The amount by which a process variable exceeds the set point before it stabilizes.

**P control** — Proportioning control.

**PD control** — Proportioning control with derivative (rate) action.

**PDR control** — Proportional derivative control with manual reset, used in fast responding systems where the reset causes instabilities. With PDR control, an operator can enter a manual reset value that eliminates droop in the system.

**PI control** — Proportioning control with integral (automatic reset) action.

**PID** — Proportional, integral, derivative. A control mode with three functions: proportional action dampens the system response, integral corrects for droop, and derivative prevents overshoot and undershoot.

**process variable** — The parameter that is controlled or measured. Typical examples are temperature, relative humidity, pressure, flow, fluid level, events, etc. The high process variable is the highest value of the process range, expressed in engineering units. The low process variable is the lowest value of the process range.

**proportional band (PB)** — A range in which the proportioning function of the control is active. Expressed in units, degrees or percent of span. See PID.

**proportional control** — A control using only the P (proportional) value of PID control.

**rate band** — A range in which the rate function of a controller is active. Expressed in multiples of the proportional band. See PID.

**ratio** — A method by which the controller measures the flow of an uncontrolled variable and uses a proportion of it to control the flow of a second variable.

reference junction — See junction.

**reset** — Control action that automatically eliminates offset, or droop, between set point and actual process temperature. Also see integral.

**automatic reset** — The integral function of a PI or PID temperature controller that adjusts the process temperature to the set point after the system stabilizes. The inverse of integral.

**automatic power reset** — A feature in latching limit controls that does not recognize power outage as a limit condition. When power is restored, the output is reenergized automatically, as long as the temperature is within limits.

 $manual\ reset-1)$  A feature on a limit control that requires human intervention to return the limit to normal operation after a limit condition has occurred. 2) The adjustment of a proportional control to raise the proportional band to compensate for droop.

**no key reset** — A method for resetting the controller's memory (for instance, after an EPROM change).

resistance temperature detector (RTD) — A sensor that uses the resistance temperature characteristic to measure temperature. There are two basic types of RTDs: the wire RTD, which is usually made of platinum, and the thermistor, which is made of a semiconductor material. The wire RTD is a positive temperature coefficient sensor only, while the thermistor can have either a negative or positive temperature coefficient.

**retransmit output** — An analog output signal that may be scaled to represent the process value or set point value.

**RTD** — See resistance temperature detector.

**slidewire feedback** — A method of controlling the position of a valve. It uses a potentiometer to vary resistance and indicate position of the valve.

**switching sensitivity** — In on/off control, the temperature change necessary to change the output from full on to full off. See hysteresis.

**thermal system** — A regulated environment that consists of a heat source, heat transfer medium or load, sensing device and a control instrument.

**thermocouple (t/c)** — A temperature sensing device made by joining two dissimilar metals. This junction produces an electrical voltage in proportion to the difference in temperature between the hot junction (sensing junction) and the leadwire connection to the instrument (cold junction).

**thermocouple break protection** — The ability of a control to detect a break in the thermocouple circuit and take a predetermined action.

**three-mode control** — Proportioning control with integral (reset) and derivative (rate). Also see PID.

**time proportioning control** — A method of controlling power by varying the on/off duty cycle of an output. This variance is proportional to the difference between the set point and the actual process temperature.

**zero cross** — Action that provides output switching only at or near the zero-voltage crossing points of the ac sine wave. See burst fire.

**zero switching** — See zero cross.

# **Specifications**

(1234)

#### **Control Mode**

- Dual input, quad output, optional retransmit of set point or process variable.
- Programmable direct and reverse acting control outputs.
- One-step auto-tuning.

#### **Operator Interface**

- · Local/remote set point capability.
- Dual, 4-digit LED displays: upper, 0.4" (10mm); lower, 0.3" (8mm).
- Mode, Auto/Man, Display, Up and Down keys.
   Input
- Contact input for software function select.
- Type J, K, T, N, C(W5)<sub>2</sub>, D(W3)<sub>2</sub>, E, R, S, B, Pt 2<sub>2</sub> thermocouple, 1° or 0.1° RTD.
- 0-50mV= (dc), 0-20mA, 4-20mA, 0-5V= (dc), 1-5V= (dc), 0-10V= (dc) process.
- Slidewire, digital event input or heater current options.
- Sensor break protection de-energizes control output to protect system or selectable bumpless transfer to manual operation. Latching or non-latching.
- °F or °C display or process units, user selectable.

#### **Sensor Ranges**

| J t/c:                    | 32     | to | 1500°F       | or | 0     | to | 816°C   |
|---------------------------|--------|----|--------------|----|-------|----|---------|
| K t/c:                    | -328   | to | 2500°F       | or | -200  | to | 1371°C  |
| T t/c:                    | -328   | to | 750°F        | or | -200  | to | 399°C   |
| N t/c:                    | 32     | to | 2372°F       | or | 0     | to | 1300°C  |
| R t/c:                    | 32     | to | 3200°F       | or | 0     | to | 1760°C  |
| S t/c:                    | 32     | to | 3200°F       | or | 0     | to | 1760°C  |
| B t/c:                    | 1598   | to | 3300°F       | or | 870   | to | 1816°C  |
| E t/c:                    | -328   | to | 1470°F       | or | -200  | to | 799°C   |
| C t/c (W5) <sub>2</sub> : | 32     | to | 4200°F       | or | 0     | to | 2316°C  |
| D t/c (W3) <sub>2</sub> : | 32     | to | 4200°F       | or | 0     | to | 2316°C  |
| Pt 2 <sub>2</sub> :       | 32     | to | 2543°F       | or | 0     | to | 1395°C  |
| 1°RTD (JIS):              | -328   | to | 1166°F       | or | -200  | to | 630°C   |
| 1°RTD (DIN):              | -328   | to | 1472°F       | or | -200  | to | 800°C   |
| 0.1°RTD                   |        |    |              |    |       |    |         |
| (JIS and DIN)             | :-99.9 | to | 999.9°F      | or | -73.3 | to | 537.7°C |
| 0-5V≕ (dc):               | -999   | to | 9999         |    |       |    |         |
| 1-5V≕ (dc):               | -999   | to | 9999         |    |       |    |         |
| 0-10V≕ (dc):              | -999   | to | 9999         |    |       |    |         |
| 0-20mA:                   | -999   | to | 9999         |    |       |    |         |
| 4-20mA:                   | -999   | to | 9999         |    |       |    |         |
| 0-50mV= (dc)              | :-999  | to | 9999         |    |       |    |         |
| Slidewire:                | 100    | to | $1200\Omega$ |    |       |    |         |
| Current:                  | 0      | to | 50A          |    |       |    |         |
| Potentiometer             | : 0    | to | $1200\Omega$ |    |       |    |         |
| Output Outle              |        |    |              |    |       |    |         |

### **Output Options**

- Solid-state relay, 0.5A @ 24V~ (ac) min., 253V~ (ac) max., opto-isolated, burst fire. With or without contact suppression.
- Open collector: Max. voltage 42V= (dc), max. current
- Switched dc signal: Min. turn-on voltage of 3V= (dc) into min. 500Ω load; max. On voltage not greater than 32V= (dc) into an infinite load, isolated.
- Electromechanical relay<sub>1</sub>, Form C, 5A @ 120/240V~ (ac), 6A @ 28V= (dc), 1/8 hp. @ 120V~ (ac) or 125VA @ 120V~ (ac). With or without contact suppression. Off-state output impedance with RC suppression is 20kΩ.

- Process, 0-20mA, 4-20mA into 800Ω maximum, 0-5V= (dc), 1-5V= (dc) or 0-10V= (dc) into 1kΩ minimum<sub>1</sub>, reverse acting, isolated.
- Electromechanical relay, Form A/B, 5A @ 120/240V~ (ac), 6A @ 28V= (dc), 1/8 hp. @ 120V~ (ac) or 125VA @ 120V~ (ac). Without contact suppression.
- External transmitter power supply, 5V ±5% @ 30mA, 12V ±5% @ 30mA or 20V ±5% @ 30mA.
- EIA/TIA-232 communications or EIA/TIA-485, EIA/TIA-422 communications, opto-isolated.

#### **Accuracy**

- Calibration accuracy and sensor conformity: ± 0.1% of span, ±1 LSD, 77°F ± 5°F (25°C ± 3°C) ambient and rated line voltage ±10%.
- Accuracy span: 1000°F (540°C) minimum.
- Temperature stability: ± 0.2°F/°F (0.1°C/°C) change in ambient.
- Voltage stability: ± 0.01% of span /% of rated line voltage.

### **Agency Approvals**

- UL, C-UL File #43684
- CE: 89/336/EEC Electromagnetic Compatibility Directive.

EN 50081-2: 1994 Emissions. EN 50082-2: 1995 Immunity.

- 73/23/EEC Low-Voltage Directive.
- EN 61010-1: 1993 Safety. NEMA 4X

#### **Terminals**

 #6 compression universal head screws (tighten to 5 inch/pounds maximum), accepts 20-14 gauge wire.

#### Line Voltage/Power

- 100 to 240V~ <sub>1</sub> (ac) +10%/-15%, 50/60Hz, ± 5%.
- 24 to  $28V = \frac{1}{1} (ac/dc) + 10\% 15\%, \frac{50}{60}Hz, \pm 5\%.$
- 16VA maximum.
- Fused internally (factory replaceable only) Slo-Blo® type (time-lag): 2A, 250V for high-voltage versions; 5A, 250V for low-voltage versions.
- · Non-volatile memory retains data if power fails.

## **Operating Environment**

32 to 149°F (0 to 65°C), 0 to 90% RH, non-condensing.

#### **Storage Temperature**

-40 to 185°F (-40 to 85°C).

### Mechanical

- 1/8 DIN panel mount, NEMA 4X (IP65 equivalent) front panel
- Overall width x height x depth: horizontal - 4.03" x 2.18" x 4.74" (102mm x 55mm x 120mm); vertical - 2.18" x 4.03" x 4.74" (55mm x 102mm x 120mm).
- Depth behind panel; 4.06" (103mm).
- Weight: less than or equal to 14.0oz (0.40kg).

#### Sample/Update Rates

- 1 input: 10Hz.
- 2 inputs: 5Hz.
- Retransmit: 1Hz.
- · Remote set point: 1Hz.
- PID: 10Hz.
- Outputs: 10Hz.
- Display: 2Hz.
- Alarm Outputs: 1 Hz

#### Resolution

- Inputs: 16 bits.
- Outputs: 12 bits.
- <sup>1</sup> Electromechanical relays are warranted for 100,000 closures only. Solid-state switching devices are recommended for applications requiring fast cycle times or extended service life.
- <sup>2</sup> Not an ANSI symbol.

# Warranty



The Watlow Series 988 is warranted to be free of defects in material and workmanship for 36 months after delivery to the first purchaser for use, providing that the units have not been misapplied. Since Watlow has no control over their use, and sometimes misuse, we cannot guarantee against failure. Watlow's obligations hereunder, at Watlow's option, are limited to replacement, repair or refund of purchase price, and parts which upon examination prove to be defective within the warranty period specified. This warranty does not apply to damage resulting from transportation, alteration, misuse or abuse.

# **Watlow Controls**

Watlow Controls is a division of Watlow Electric Mfg. Co., St. Louis, Missouri, a manufacturer of industrial electric heating products since 1922. Watlow begins with a full set of specifications and completes an industrial product that is manufactured totally inhouse, in the U.S.A. Watlow products include electric heaters, sensors, controls and switching devices. The Winona operation has been designing solid state electronic control devices since 1962, and has earned the reputation as an excellent supplier to original equipment manufacturers. These OEMs depend upon Watlow Controls to provide compatibly engineered controls which they can incorporate into their products with confidence. Watlow Controls resides in a 100,000-square-foot marketing, engineering and manufacturing facility in Winona, Minnesota.

## Returns

- 1. Call Watlow Customer Service, (507) 454-5300, for a Return Material Authorization (RMA) number before returning any item for repair. We need this information:
  - Ship to address
- · Bill to address
- Contact name
- · Phone number
- Ship via
- Your P.O. number
- Symptoms and/or special instructions
- Name and phone number of person returning the material.
- Prior approval and an RMA number, from the Customer Service Department, is needed when returning any unused product for credit. Make sure the RMA number is on the outside of the carton, and on all paperwork returned. Ship on a Freight Prepaid basis.
- 3. After we receive your return, we will examine it and determine the cause for your action.
- In cases of manufacturing defect, we will enter a repair order, replacement order, or issue credit for material. A 20-percent restocking charge is applied for all returned stock controls and accessories.
- 5. If the unit is unrepairable, it will be returned to you with a letter of explanation. Repair costs will not exceed 50 percent of the original cost.

# **Shipping Claims**

When you receive your Watlow control, examine the package for any signs of external damage it may have sustained enroute. If there is apparent damage either outside the box or to its contents, make a claim with the shipper immediately. Save the original shipping carton and packing material.

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| (A/D overflow error) 7.8   |  | <b>5EPE</b> (crossover set point value) 4.39             |
| <b>E</b> , <b>I</b> (event input 1) 4.40   | <b>OPE</b> (Operation Menus) <u>5.1</u> - <u>5.16</u>      | <b>5</b> <i>E</i> - <i>E</i> (start) 8.17                |
| E , 15 (event input 1 status) 5.4  | <b>DPLP</b> (open loop) <u>6.12</u> , <u>7.9</u>           | 555 (system lockout) 6.4                                 |
| E , 2 (event input 2) 4.40 - 4.41  | <b>DE 1</b> (output 1) 4.19                                | <b>5 5 5</b> (System Menu) <b>5</b> .2                   |
|  | <b>BE2</b> (output 2) 4.21                                 |  |
| E ,25 (event input 2 status) 5.4   | ### (output 3) 4.25  | T 11 1/ 14/ 1/ 1/ -                                      |
| Er 3 (ambient temperature error) 7.9   |  | T, U, V, W, X, Y, Z                                      |
| Ery (RAM identification error) 7.9   | <b>DE4</b> (output 4) 4.28                                 |  |
| Er 5 (non-volatile checksum error) 7.9   | <b>DEPE</b> (output lockout) 6.5                           | <u> とのいと</u> (test outputs) <u>6.11</u>                  |
| , —  | <b>BEPE</b> (Output Menu) 4.18                             |  |
| Erg (configuration error) 7.9  | (Output 1 module type) 6.10                                |  |
| Err (error latching) 4.36  |  |  |
|  | (output 2 module type) 6.10                                |  |
| г  | ①ヒリヨ (output 3 module type) 6.10                           |  |
| F  | (output 4 module type) 6.10                                |  |
| ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( )  | <u>66.70</u>   |  |
| FRIL (failure mode) 4.35   | _  |  |
| FER (software filter 1) 4.7  | P  |  |
| FEC2 (software filter 2) 4.15  | •  |  |
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| <u>FULL</u> (Iuli) 4.40, 0.4   | Pb 1b (proportional band, output 1, PID B) 5.10            |  |
|  | Pb2R (proportional band, output 2, PID A) 5.13             |  |
| G  |  |  |
| 0  | <b>Pb2b</b> (proportional band, output 2, PID B) 5.13      |  |
| <b>9LbL</b> (Global Menu) 4.34   | <b>P</b> , <b>d</b> (switch PID sets) 4.38, 8.8            |  |
| 9LbL (global lockout) 6.5  | (PID 2 crossover selection) 4.38, 9.8                      |  |
| (global lockout) 6.5   | P , dR (PID A Menu) 5.3, 9.8                               |  |
|  |  |  |
| Н  | <b>P</b> , <b>d b</b> (PID B Menu) <u>5.3</u> , <u>9.8</u> |  |
| 11   | P JAR (PID A lockout) 6.4                                  |  |
| H .9H (alarm 3 trigger) 4.26   | P ,db (PID B lockout) 6.4                                  |  |
|  | PLOT (Panel Lockout Menu) 6.1 - 6.6                        |  |
| H,P (high power limit) 4.42  |  |  |
| Hunt (hunt) 4.16, 8.22, 8.23   | <b>Pr 2</b> (input 2 process ) 3.2, 8.10, 9.4              |  |
| <b>HY5</b> (hysteresis 1) 4.20   | <b>Prc !</b> (process 1) 4.20                              |  |
| <b>HY52</b> (hysteresis 2) 4.22  | Prc2 (process 2) 4.21                                      |  |
|  | <b>Prc 3</b> (process 3) 4.31                              |  |
| <b>HY53</b> (hysteresis 3) 4.26  |  |  |
| <b>HY5Y</b> (hysteresis 4) 4.29  | Proc (crossover process value) 4.39, 9.8                   |  |
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|  |  |  |
| •  | Q, R   |  |
| <b>1d5P</b> (idle set point) <u>5.3</u> , <u>8.8</u>   | ~, it  |  |
| In I (input 1) 4.3 - 4.4   | <b>FRIR</b> (rate, output 1, PID A) 5.12, 9.4              |  |
|  | <b>FRIB</b> (rate, output 1, PID B) 5.12                   |  |
| (input 2) 4.9  |  |  |
| InPt (Input Menu) 4.2  | <b>R</b> (rate, output 2, PID A) <u>5.15</u>               |  |
| InPt (input lockout) 6.5   | <b>┌ Я ≥ Ь</b> (rate, output 2, PID B) 5.15                |  |
| IntF (interface type) 4.47   | <b>FREE</b> (ramp rate) 4.43                               |  |
|  | (ratio) 4.36, 9.13   |  |
| IE IR (integral, output 1, PID A) 5.11   |  |  |
| IE IB (integral, output 1, PID B) 5.11   | r E IR (reset, output 1, Pid A) 5.11, 9.4                  |  |
| IE 2R (integral, output 2, PID A) 5.14   | r E Ib (reset, output 1, PID B) 5.11                       |  |
| IE 26 (integral, output 2, PID B) 5.14   | reset, output 2, PID A) 5.14                               |  |
| <b>LY</b> (input 1 module type) 6.9  | reset, output 2, PID B) 5.14                               |  |
|  |  |  |
| (input 2 module type) 6.9  | r EU (reverse action) 4.37                                 |  |
|  | <b>FHI</b> (range high 1) 4.5 - 4.6                        |  |
| J, K, L  | <b>→ H2</b> (range high 2) 4.11 - 4.12, 8.11, 9.3          |  |
| J, IX, L   | <b>r</b> L I (range low 1) 4.5 - 4.6                       |  |
| LRE (latching) 4.36  | respectively 4.11 - 4.12, 8.11, 9.3                        |  |
|  |  |  |
| <b>LRE2</b> (latching 2) 4.24  | root extraction) 8.14, 8.15                                |  |
| <b>LRE3</b> (latching 3) 4.27  |  |  |
|  | <b>P</b> (ramping function) 4.43, 8.17                     |  |
| <b>LREY</b> (latching 4) 4.30  |  |  |
| [ [ ] (latching 4) 4.30 [ ] (input 1 linearization) 4.8.8.14.8.15  | <b>F5P</b> (remote set point) 4.10, 8.8, 8.19              |  |
| [ ] (latching 4) 4.30<br>[ ] (input 1 linearization) 4.8, 8.14, 8.15<br>[ ] (input 2 linearization) 4.15, 8.14 |  |  |

# Menu Overview

Figure A.10 -The Series 988 Map.

This is a complete

listing of all Series

Not all prompts will

appear on your con-

dependent on your

configuration and model number.

Press DISPLAY to return

to the Display Loop

to advance through

Press or to

move between the

advance through a

menus.

menu.

Press MODE to

Hold MODE while

pressing to move backwards

through the menus.

Press or to

select prompt values.

the Display Loop.

from any location and

988 prompts.

trol. They are

To navigate:

NOTE:

75 → Pr 2 → InSP → Press DISPLAY to exit Display Loop any menu and (Lower Display) Set point 1, Remote set point or % OUT LED on reach the Display (cascade only) Loop at any time. Press MODE to advance to the Operation **Operation Menus** SP2 ( ) Set point 2 IdSP ( ) Idle set point menus. Outputs are still active. OPEr ( ) Operation (SyS) (System) (PIDA) (PIDB) (PIDB) Pb1A ( ) Output 1 proportional band A Pb1b ( ) Ei1S () Event input 1 status Output 1 proportional band B Ei2S () rE1A ( ) Output 1 reset A Event input 2 status rE1b () Output 1 reset B It1A ( ) Output 1 integral A It1b ( ) Output 1 integral B A2LO () Alarm 2 low rA1A ( ) Output 1 rate A A2HI ( ) Alarm 2 high rA1b ( ) Output 1 rate B A3LO () dE1A ( ) Output 1 derivative A Alarm 3 low dE1b ( ) Output 1 derivative B Ct1A ( ) Output 1 cycle time A Alarm 3 high Ct1b ( ) Output 1 cycle time B A4LO ( ) Pb2A ( ) Output 2 proportional band A Alarm 4 low Pb2b ( ) Output 2 proportional band B rE2A ( ) Output 2 reset A A4HI ( ) Alarm 4 high rE2b ( ) Output 2 reset B It2A ( ) Output 2 integral A Auto-tune It2b ( ) Output 2 integral B rA2A ( ) Output 2 rate A rA2b ( ) Output 2 rate B dE2A ( ) Output 2 derivative A Ct2A ( ) Output 2 cycle time A dE2b ( ) Output 2 derivative B Ct2b ( ) Output 2 cycle time B db A ( ) Dead band A db b ( ) Dead band B Press and for 3 seconds to enter the Setup menus. Outputs are disabled. Setup Menus Setup SEt () (OtPt) (Output) (COM) (Communications) (InPt) (gLbL) (Global) (Input) bAUd ( ) Baud rate Ot1 ( ) Output 1 ( ) Celcius\_Fahrenhe Input 1 dAtA ( ) Data bits and parity Prc1 ( ) Process 1 dEC1 () ( ) Failure mode Decimal place 1 FAIL Protocol type Prot () HYS1 ( ) Hysteresis 1 rL1 () Range low 1 Err () Error latching Addr () Address Ot2 ( ) Output 2 ( ) rH1 Range high 1 CntL ( ) Control type Prc2 ( ) Process 2 intF ( ) Interface type CAL1 ( ) Calibration offset 1 CSAC ( ) Cascade action HYS2 ( ) Hysteresis 2 rtd1 () RTD calibration curve 1 ALgO ( ) Control algorithm SP2c ( ) Control set point 2 Ftr1 () Input 1 software filter Pid2 ( ) PID 2 crossover selection AL2 () Alarm 2 Lin1 ( ) Input 1 linearization Proc ( ) Crossover process value A2Sd ( ) Alarm 2 side In2 ( ) Input 2 StPt () Crossover set point value LAt2 ( ) Latching for alarm 2 ( ) Remote set point rSP Ei1 () Event input 1 SIL2 ( ) Silence alarm 2 dEC2 () Decimal place 2 () Event input 2 Ot3 ( ) Output 3 Range low 2 Anun ( ) Annunciator AL3 () Alarm 3 rH2 ( ) Range high 2 ( ) Low power limit A3Sd ( ) Alarm 3 side LmL ( ) Learn range low HYS3 ( ) Hysteresis 3 ( ) High power limit LmH () Learn range high LAt3 ( ) Latching for alarm 3 AtSP ( ) Auto-tune set point CAL2 ( ) Calibration offset 2 SIL3 ( ) Silence alarm 3 ( ) Ramping function ( ) RTD calibration curve 2 Ot4 ( ) Output 4 rAtE () Ramp rate Ftr2 ( ) Input 2 software filter AL4 ( ) Alarm 4 Lin2 ( ) Input 2 linearization A4Sd ( ) Alarm 4 side Hunt ( ) Slidewire dead band HYS4 ( ) Hysteresis 4 :SHyS ( ) Slidewire inner LAt4 ( ) Latching for alarm 4 SIL4 ( ) Silence alarm 4 Aout ( ) Analog output Prc3 ( ) Process 3 A r L ( ) Retransmit low limit A r H ( ) Retransmit high limit

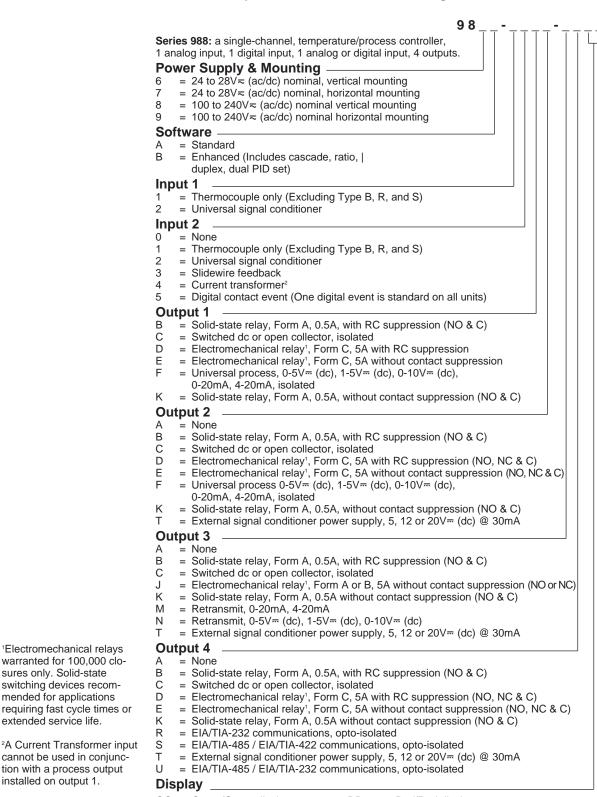
ACAL ( ) Retransmit cal. offset 5EE prompt, press A and A another Fcty ( ) Factory **Factory Menus** 3 seconds to enter the Factory menus. ation) (PLOC) (Panel Lockout) (diAg) (Diagnostics) (CAL) b380 ( LOC ( ) Front Panel lockout dAtE () Factory ship date A 50 () b10U ( SyS ( ) System menu lockout SOFt () Software revision A 00 ( b OU PidA ( ) PIDA menu lockout Serial number tc b20A ( Pidb ( ) PIDB menu lockout AMb () Ambient temperature A 0H ( b 4A ( InPt () Input menu lockout Acnt () Ambient A/D count A 20 ( b 0u ( OtPt ( ) Output menu lockout gnd () Ground A/D count A 15 () b100 ( gLbL ( ) Global menu lockout cnt1 () Input 1 A/D count A380 () 14 COM ( ) Communications menu lockou cnt2 () Input 2 A/D count A10U ( 120 () diAg ( ) Diagnostics menu lockout ity1 ( ) Input 1 module A 0u ( 10 ( ( ) Calibration menu lockout Input 2 module ity2 ( ) 110 () Output 1 module A 4A ( 24 Output 2 module Oty2 ( ) A 0u ( 2 20 () Output 3 module Otv3 () 20 A100 ( Output 4 module Oty4 ( ) 210 ( Test displays dISP () b 00 3 LO ( Test output tout () b 0H ( 3 HI ( OPLP ( ) Open loop b 20 ( rSt Restore factory values b15 () ( ) Default prompts

### NOTE:

The controller will not default back to normal display while in the Factory Menu. All outputs are disabled while in this menu.

# **Ordering Information**

To order, complete the code number to the right with the information below:



cannot be used in conjunction with a process output

<sup>1</sup>Electromechanical relays

warranted for 100,000 closures only. Solid-state

switching devices recom-

mended for applications requiring fast cycle times or

extended service life.

installed on output 1.

RG = Red/Green displays

# **Declaration of Conformity**

( € 96 Series 986, 987, 988, 989 WATLOW CONTROLS

1241 Bundy Boulevard

Winona, Minnesota 55987 USA

Declares that the following product: Enalish

Designation: Series 986, 987, 988, 989

Model Number(s): 9 8 (6, 7, 8 or 9) (Any letter) - (1 or 2) (0 1 2 3 4 or 5) (BCDEForK) (ABCDEFKorT) - (ABCJKM N or T) (A B C D E K R S or T) (Any two letters)

Classification: Control, Installation Category II, Polution Degree II Rated Voltage: 100 to 240V~ (ac) or 24 to 28V≂ (ac/dc)

Rated Frequency: 50/60 Hz Rated Power Consumption: 16VA maximum

Meets the essential requirements of the following European Union Directive(s) using the relevant section(s) of the normalized standards and related documents shown:

89/336/EEC Electromagnetic Compatibility Directive

EN 50082-2: 1995 EMC Generic immunity standard, Part 2: Industrial environment

EN 61000-4-2: 1995 Electrostatic discharge EN 61000-4-4: 1995 Electical fast transients ENV 50140: 1994 Radiated immunity 1994 Conducted immunity FNV 50141: ENV 50204: 1995 Cellular phone

EN 50081-2: 1994 EMC Generic emission standard, Part 2: Industrial

environment

EN 55011: Limits and methods of measurement of radio disturbance characteristics of industrial, scientific and medical radio-

frequency equipment (Class A) 1995 Limits for harmonic current emissions

EN 61000-3-2: 1995 Limitations of voltage fluctuations and flicker EN 61000-3-3:

73/23/EEC Low-Voltage Directive

EN 61010-1: 1993 Safety requirements for electrical equipment for

measurement, control, and laboratory use, Part 1:

General requirements

Déclare que le produit suivant : Francais

Série 986, 987, 988, 989 Désignation:

Numéro(s) de modèle(s) : 98 (6, 7, 8 ou 9) (lettre quelconque) - (1 ou 2) (0, 1, 2, 3, 4 ou 5) (B, C, D, E, F ou K) (A, B, C, D, E, F, K ou

T) - (A, B, C, J, K, M, N ou T) (A, B, C, D, E, K, R, S,

ou T) (deux lettres quelconques) Commande, installation catégorie II, degré de

pollution II

Tension nominale: 100 à 240 V ~ **ou** 24 à 28 V  $\approx$  (c.a./c.c.)

Fréquence nominale : 50/60 Hz

Consommation

Classification :

d'alimentation nominale : 16 VA maximum

Conforme aux exigences de la (ou des) directive(s) suivantes de l'Union Européenne figurant aux sections correspondantes des normes et documents

associés ci-dessous

89/336/EEC Directive de compatibilité électromagnétique

EN 50082-2: 1995 Norme générique d'insensibilité électromagnétique, Partie 2 : Environnement industriel

EN 61000-4-2 : 1995 Décharge électrostatique EN 61000-4-4 : 1995 Courants électriques transitoires rapides

ENV 50140: 1994 Insensibilité à l'énergie rayonnée FNV 50141 1994 Insensibilité à l'énergie par conduction ENV 50204: 1995 Téléphone cellulaire

EN 50081-2:

1994 Norme générique sur les émissions électromagnétiques. Partie 2 : Environnement industriel

Limites et méthodes de mesure des caractéristiques

EN 55011: d'interférences du matériel radiofréquence industriel. scientifique et médical (Classe A) EN 61000-3-2 : 1995 Limites d'émission d'harmoniques

1995 Limitations d'écarts de tension et de papillotement 73/23/EEC Directive liée aux basses tensions

EN 61010-1: 1993 Exigences de sécurité pour le matériel électrique de

mesure, commande et de laboratoire, Partie 1 :

Exigences générales

Erklärt, daß das folgende Produkt:

Beschreibung: Serie 986, 987, 988, 989

ModelInummer(n): 9 8 (6 7 8 oder 9) (beliebiger Buchstabe) - (1 oder 2) (0 1 2 3 4 oder 5) (B C D E F oder K) (A B C D E F K

oder T) - (A B C J K M N oder T) (A B C D E K R S oder T) (2 beliebige Buchstaben)

Deutsch

Klassifikation: Regelsystem, Installationskategorie II, Emissionsgrad II 100 bis 240 V~ (ac) oder 24 bis 28 V≂ (ac/dc) Nennspannung:

50/60 Hz Nennfrequenz: Stromverbrauch: Max. 16 VA

Erfüllt die wichtigsten Normen der folgenden Anweisung(en) der Europäischen Union unter Verwendung der untenstehenden einschlägigen Dokumente:

89/336/EEC Elektromagnetische Übereinstimmungsanweisung

1995 EMC-Rahmennorm für Störsicherheit, Teil 2: Industrielle EN 50082-2: Umwelt

EN 61000-4-2: 1995 Elektrostatische Entladung EN 61000-4-4: 1995 Elektrische schnelle Stöße ENV 50140: 1994 Strahlungsimmunität 1994 Leitungsimmunität1995 Mobiltelefon FNV 50141: ENV 50204

EN 55011:

EN 50081-2: 1994 EMC-Rahmennorm für Emissionen, Teil 2: Industrielle

Beschränkungen und Methoden der Messung von Funkstörungsmerkmalen industrieller, wissenschaftlicher und medizinischer Hochfrequenzgeräte (Klasse A)

EN 61000-3-2: 1995 Grenzen der Oberwellenstromemissionen

EN 61000-3-3: 1995 Grenzen der Spannungsschwankungen und Flimmern

72/23/EEC Niederspannungsrichtlinie zu entsprechen

1993 Sicherheitsrichtlinien für Elektrogeräte zur Messung, zur EN 61010-1: Steuerung und im Labor, Teil 1: Allgemeine Richtlinien

Declara que el producto siguiente: Español

Designación: Series 986, 987, 988, 989

Números de modelo 9 8 (6 7 8 ó 9)(Cualquier letra) - (1 ó 2)(0 1 2 3 4 ó

5)(B C D E F o K)(A B C D E F K o T) - (A B C J K M N o T)(A B C D E K R S o T)(Cualquier combinación

de dos letras)

Clasificación: Control, categoría de instalación II, grado de

contaminación ambiental II

100 a 240 V~ (Vca) o 24 a 28V ≂ (Vca/Vcc) Tensión nominal:

Frecuencia nominal: 50/60 Hz Consumo nominal

de energía: 16 VA máximo

Cumple con los requisitos esenciales de las siguientes directivas de la Unión Europea, usando las secciones pertinentes de las reglas normalizadas y los

documentos relacionados que se muestran: 89/336/EEC - Directiva de compatibilidad electromagnética

EN 50082-2: 1995 Norma de inmunidad genérica del EMC, parte 2: Ambiente industrial

EN 61000-4-2: 1995 Descarga electrostática 1995 Perturbaciones transitorias eléctricas rápidas EN 61000-4-4:

FNV 50140: 1994 Inmunidad radiada ENV 50141: 1994 Inmunidad conducida ENV 50204: 1995 Teléfono portátil

EN 50081-2: 1994 Norma de emisión genérica del EMC, parte 2: Ambiente

industrial

EN 55011: Límites v métodos de medición de características de perturbaciones de radio correspondientes a equipos de radiofrecuencia industriales, científicos y médicos (Clase A)

EN 61000-3-2: Límites para emisiones de corriente armónica EN 61000-3-3:

1995 Limitaciones de fluctuaciones del voltaie 73/23/EEC Directiva de baja tensión

EN 61010-1: 1993 Requerimientos de seguridad para equipos eléctricos de medición, control y uso en laboratorios, Parte 1:

Requerimientos generales

Erwin D. Lowell Winona, Minnesota, USA

Name of Authorized Representative Place of Issue

General Manager January 9, 1996 Title of Authorized Representative Date of Issue

MUELL

Signature of Authorized Representative

(1230)

